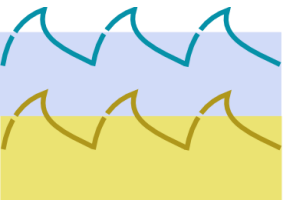


Development of a DESERT Module

UNWiS - Padova (Italy)
30th of January – 3rd of February 2023

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DESERT structure

Architecture of the DESERT software stack and modules organization

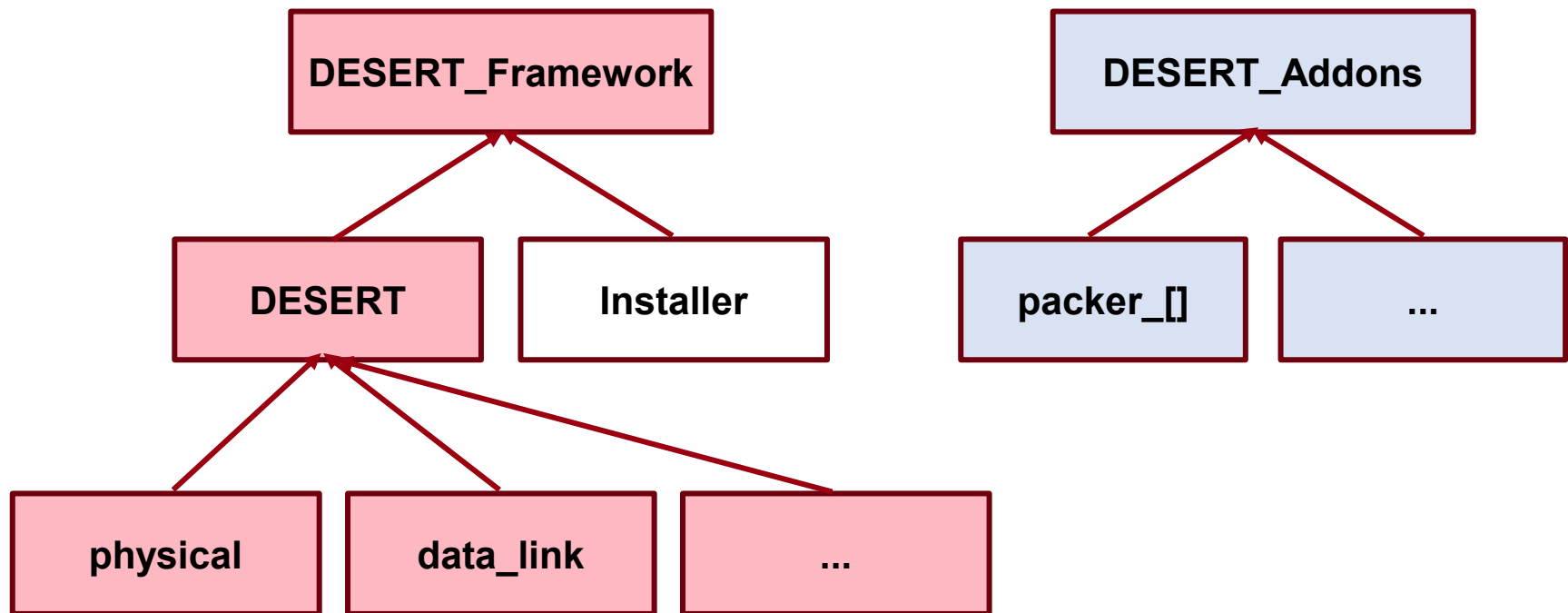


NS-MIRACLE inheritance

- DESERT inherits the modular structure of NS-MIRACLE
- A general Module is implemented, along with most basic layers (MMac, MPhy), inheriting from this Module
- Before delving into development, check for basic functionalities: they could be already implemented

Folders organization

DESERT, as it is downloaded from the main repo, is organized in the following folders



Folders organization

- Once compiled, DESERT will create another folder named **DESERT_buildCopy_LOCAL** at the root of the DESERT repo
- This folder contains the compiled elements and the generated Makefiles: from here it is possible to compile a single module

DESERT_Framework

*Sources and
configuration for
compilation*

DESERT_Addons

*Sources and
configuration for the
addons*

**DESERT_buildCopy
_LOCAL**

*Compiled binaries
and configured
Makefiles*

DESERT Modules

How to develop and add a new module in
DESERT Underwater



Where to put them

- As seen, DESERT modules lie in `DESERT_Underwater/DESERT_Framework/DESERT`
- DESERT organizes modules according (when possible) to the ISO/OSI stack: understand and decide where your new module should be placed
- As an example, we want to implement a new physical layer module, called *Cool PHY*



Cool PHY basics

- We start by creating the folder to host our new PHY module: `uwcoolphy`

```
DESERT_Framework/DESERT/physical/uwcoolphy
```

- then, we proceed to create the 2 basic files needed by C++ to define (properly) a class, and so, an object: `uwcoolphy.h`, `uwcoolphy.cpp`
- add another important file, that will be explained later: `initlib.cpp`
- and add a `Makefile.am`, specifying the compilation of the module

The module class

- Our module, is a layer module (PHY), so it can be inserted in the communication stack of the nodes in our simulation
- It is implemented through a C++ class, that we call `UwCoolPhy`
- For this class to work in a DESERT simulation, some types of binding are necessary
 - Bound variable (`bind`)
 - Constructor connection with `OTcl`

Module Tcl binding [1]

- The first binding links variables for, e.g., setting parameters, via the function `bind()`

```
C++    |    bind("debug", (int *) &debug_);
```

```
Tcl    |    Module/UW/PHYSICAL set debug 1
```

- the string parameter is the Tcl variable that is bound (has the same value of) to the second parameter (a C++ declared variable)
- and is usually done in the C++ constructor

Module Tcl binding [2]

- The second binding is performed at the Constructor and allows to instantiate it in Tcl
- It is built, defining a class and its constructor

```
static class UwCoolPhyClass : public TclClass
{
public:
    UwCoolPhyClass()
        : TclClass("Module/UW/CoolPhy")
    { }
    TclObject * create(int, const char *const *) {
        return (new UwCoolPhy);
    }
}
```

Name of the
C++ class plus
"Class"

Name of the
module in the
Tcl script

Name of the
C++ class
(constructor)

The *initlib.cpp* file

- to complete our *Cool PHY* module, we define all the methods implementing the features we want
- we need to fill in also the `initlib.cpp`, which makes the real connection between C++ and OTcl
 - define an extern variable (it represents an EmbeddedTcl object) with a specific name structure: `<ModuleNameInCamelCase><TclCode>`
 - define a function with fixed naming, which is the name of your module with the first capital letter and `_Init` suffix

```
#include <tclcl.h>
extern EmbeddedTcl UwCoolPhyTclCode;

extern "C" int
Uwcoolphy_Init()
{
    UwCoolPhyTclCode.load();
    return 0;
}
```



Initializing Tcl variables

- It is suggested to initialize all the Tcl variables you have *binded* in your C++ class
- To this end, we create a file ending in `<>-init.tcl`:
`uwcoolphy-init.tcl`
- There, we can initialize the variables via Tcl code

```
Module/UW/CoolPhy set SN_Bits          32
Module/UW/CoolPhy set err_Bits         0
Module/UW/CoolPhy set Modulation_Bits  0
Module/UW/CoolPhy set Traffic_Type_Bits 0
Module/UW/CoolPhy set debug_           0
```

Make the module to compile [1]

To be able to compile our module, we need to fill in our `Makefile.am`

- add the definition of your library: name of the library must always be `lib` prefix + name of the folder hosting the module

```
lib_LTLIBRARIES = libuwcoolphy.la
```

- Specify the sources

```
libuwcoolphy_la_SOURCES = initlib.cpp \  
                          <TABS>          uwcoolphy.cpp
```

- Remember to define the `CPPFLAGS`, `LDFLAGS` and `LIBADD` as needed
- Define the Tcl files variables defaults like this

```
TCL_FILES = uwcoolphy-init.tcl
```

Make the module to compile [2]

We also need to modify the top-level `configure.ac` and `Makefile.am`

configure.ac

Add the folder of your module to the `CPPFLAGS`

```
DESERT_CPPFLAGS="$DESERT_CPPFLAGS -I$(top_srcdir)/physical/uwcoolphy'
```

Add your module's Makefile to the `AC_CONFIG_FILES`

```
physical/uwcoolphy/Makefile
```

Makefile.am

Add module's folder to the list of `SUBDIRS`

```
physical/uwcoolphy
```

Using the module

- In a Tcl simulation script, we are going to use our module
 - first, by setting its parameters
 - then, instantiating an object
 - and connecting, when needed, or calling the necessary methods on it

```
Module/UW/CoolPhy  set BitRate_          32500
Module/UW/CoolPhy  set AcquisitionThreshold_dB_ 10.0
```

```
set phy($id) [new Module/UW/CoolPhy]
```

```
$node($id) addToChannel $channel $phy($id) 1
$phy($id) setSpectralMask $data_mask
```

The *command* method [1]

There exists another way to communicate between C++ and Tcl scripts: the *command* method

This method parses strings, passed via Tcl, that are interpreted as commands, and can then call C++ functions (its binding is already defined and inherited)

It must be declared in this way, in your module class

```
virtual int command(int, const char *const *);
```

The *command* method [2]

Then, it should be defined in this way

```
UwCoolPhy::command(int argc, const char *const *argv) {  
    if (argc == 2) {  
        if (strcmp(argv[1], "Method1") == 0) {  
            method1();  
            return TCL_OK;  
        }  
    }  
    if (argc == 3) { ...  
    }  
    return Module::command(argc, argv);  
}
```

Process **first** based on number of parameters and **then** based on string comparison. Remember to return `TCL_OK` if string comparison returns 0, and to call the original (father) command at the end of your module's command:

```
return Module::command(argc, argv);
```