

Sia  $\mathcal{B} = \{ \underline{x}_1, \dots, \underline{x}_m \}$  una base di  $\mathbb{R}^m$ .

①  $\mathcal{B}$  è detta ORTOGONALE  $(\Leftrightarrow)$

$$\underline{x}_i \perp \underline{x}_j \quad \text{per } i \neq j \quad (\Leftrightarrow)$$

$$\underline{x}_i \cdot \underline{x}_j = 0_{\mathbb{R}} \quad \text{per } i \neq j$$

②  $\mathcal{B}$  è detta ORTONORMALE  $(\Leftrightarrow)$

$$\underline{x}_i \perp \underline{x}_j \quad \text{per } i \neq j \quad \text{e} \quad \|\underline{x}_i\| = 1 \quad \forall i \quad (\Leftrightarrow)$$

$$\underline{x}_i \cdot \underline{x}_j = 0_{\mathbb{R}} \quad \text{per } i \neq j \quad \text{e} \quad \underline{x}_i \cdot \underline{x}_i = 1 \quad \forall i$$

### Proposizione

Sia  $\mathcal{B} = \{ \underline{x}_1, \dots, \underline{x}_m \}$  una base ON di  $\mathbb{R}^m$

Allora  $\forall v \in \mathbb{R}^m$

$$v = \underbrace{(v \cdot \underline{x}_1)}_{\in \mathbb{R}} \underline{x}_1 + \dots + \underbrace{(v \cdot \underline{x}_m)}_{\in \mathbb{R}} \underline{x}_m = \begin{pmatrix} v \cdot \underline{x}_1 \\ v \cdot \underline{x}_2 \\ \vdots \\ v \cdot \underline{x}_m \end{pmatrix} \mathcal{B}$$

dim  $\forall v \in \mathbb{R}^m \exists \lambda_i \in \mathbb{R}$  tali che

$$v = \lambda_1 \underline{x}_1 + \lambda_2 \underline{x}_2 + \dots + \lambda_m \underline{x}_m = \begin{pmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_m \end{pmatrix} \mathcal{B}$$

(poiché  $\mathcal{B}$  è una base di  $\mathbb{R}^m$ )

$$v \cdot \underline{x}_1 = (\lambda_1 \underline{x}_1 + \lambda_2 \underline{x}_2 + \dots + \lambda_m \underline{x}_m) \cdot \underline{x}_1$$

② e ③

$$\textcircled{2} \text{ e } \textcircled{3} = \lambda_1 \underbrace{x_1 \cdot x_1}_1 + \lambda_2 \underbrace{x_2 \cdot x_1}_0 + \dots + \lambda_m \underbrace{x_m \cdot x_1}_0$$

poiché  $\|x_1\|=1$       poiché  $x_2 \perp x_1$       poiché  $x_m \perp x_1$

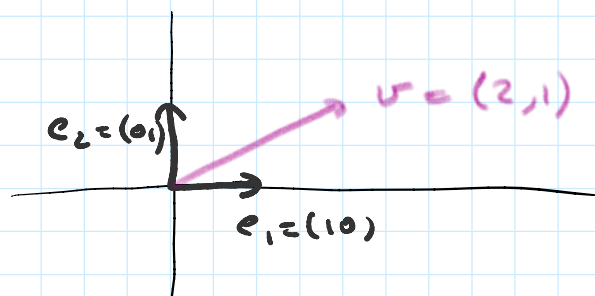
$\mathcal{B} = \{x_1, \dots, x_m\}$  è base ON

$$= \lambda_1$$

Idem si dimostra che  $\lambda_i = v \cdot x_i$

$$\Rightarrow v = \begin{pmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_m \end{pmatrix}_{\mathcal{B}} = \begin{pmatrix} v \cdot x_1 \\ \vdots \\ v \cdot x_m \end{pmatrix}_{\mathcal{B}}$$

Es



$\mathcal{e} = \{e_1, e_2\}$   
è ON

$$v = (2, 1) = 2e_1 + 1e_2$$

$$v \cdot e_1 = (2, 1) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 2 \cdot 1 + 1 \cdot 0 = 2$$

$$v \cdot e_2 = (2, 1) \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 2 \cdot 0 + 1 \cdot 1 = 1$$

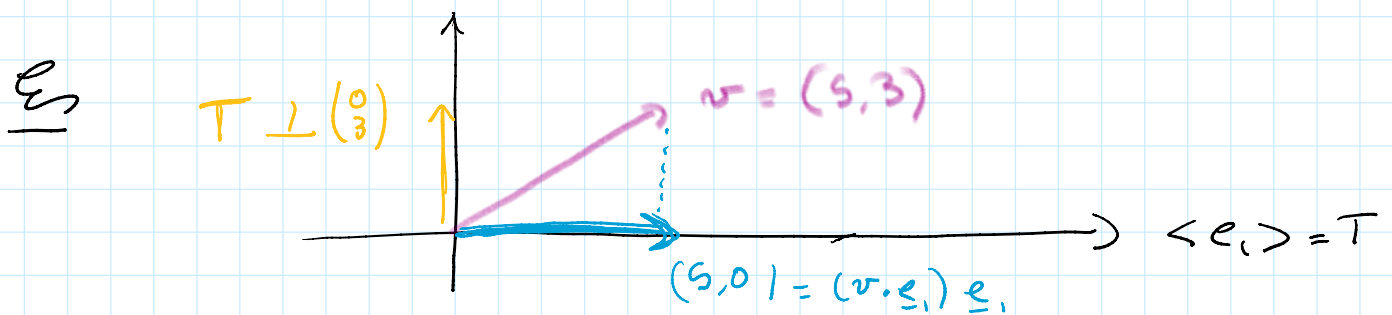
$$v = (v \cdot e_1) e_1 + (v \cdot e_2) e_2$$

Proposizione. ( $m \leq n$ )

Se  $\{\underline{x}_1, \dots, \underline{x}_m\}$  base ON di  $T$ ,  $T$  sottosp. vett. di  $\mathbb{R}^m$

Il vettore  $(v \cdot \underline{x}_1) \underline{x}_1 + \dots + (v \cdot \underline{x}_m) \underline{x}_m$   
è LA PROIEZIONE ORTOGONALE di  $v \in \mathbb{R}^m$  su  
 $T = \langle \underline{x}_1, \dots, \underline{x}_m \rangle$

Inoltre  $v - (v \cdot \underline{x}_1) \underline{x}_1 - \dots - (v \cdot \underline{x}_m) \underline{x}_m$   
è ORTOGONALE a  $T = \langle \underline{x}_1, \dots, \underline{x}_m \rangle$



$\mathbb{R}^2$ ,  $\mathcal{B} = \left\{ \underline{e}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \underline{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$  è base ON

$$\begin{aligned} (v \cdot \underline{e}_1) \underline{e}_1 &= \text{proiezione ortogonale di } v \text{ su } \langle \underline{e}_1 \rangle \\ &= \left[ (5, 3) \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right] \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= (5 \cdot 1 + 3 \cdot 0) \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= 5 \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 5 \\ 0 \end{pmatrix} \end{aligned}$$

$v - (v \cdot \underline{e}_1) \cdot \underline{e}_1$  è ortogonale a  $T = \langle \underline{e}_1 \rangle$

$$= \begin{pmatrix} 5 \\ 3 \end{pmatrix} - \begin{pmatrix} 5 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 3 \end{pmatrix} = 3 \underline{e}_2$$

## PROCEDIMENTO DI GRAM-SCHMIDT

(mi permette di ottenere una base ON a partire da una qualsiasi base)

Sia  $T$  un sottosp. vettoriale di  $\mathbb{R}^m$ ,  $T \neq \{0_{\mathbb{R}^m}\}$   
e  $\dim T = m \leq n$

Sia  $\mathcal{B} = \{\underline{t}_1, \dots, \underline{t}_m\}$  una base di  $T$ .

Allora esiste una base  $\mathcal{V} = \{\underline{v}_1, \dots, \underline{v}_m\}$  di  $T$

tale che

①  $\mathcal{V}$  è ON

②  $\langle \underline{v}_1 \rangle = \langle \underline{t}_1 \rangle$ ,  $\langle \underline{v}_1, \underline{v}_2 \rangle = \langle \underline{t}_1, \underline{t}_2 \rangle$

.....  $\langle \underline{v}_1, \dots, \underline{v}_h \rangle = \langle \underline{t}_1, \dots, \underline{t}_h \rangle$  con  $h \leq m$

$$\underline{v}_1 = \frac{\underline{t}_1}{\|\underline{t}_1\|}$$

$$\underline{v}_2 = \frac{\underline{t}_2 - (\underline{t}_2 \cdot \underline{v}_1) \underline{v}_1}{\|\underline{t}_2 - (\underline{t}_2 \cdot \underline{v}_1) \underline{v}_1\|} \quad \perp \underline{v}_1$$

$$\underline{v}_3 = \frac{\underline{t}_3 - (\underline{t}_3 \cdot \underline{v}_1) \underline{v}_1 - (\underline{t}_3 \cdot \underline{v}_2) \underline{v}_2}{\|\underline{t}_3 - (\underline{t}_3 \cdot \underline{v}_1) \underline{v}_1 - (\underline{t}_3 \cdot \underline{v}_2) \underline{v}_2\|} \quad \perp \underline{v}_1, \underline{v}_2$$

$$\underline{v}_m = \frac{\underline{t}_m - \sum_{i=1}^{m-1} (\underline{t}_m \cdot \underline{v}_i) \underline{v}_i}{\left\| \underline{t}_m - \sum_{i=1}^{m-1} (\underline{t}_m \cdot \underline{v}_i) \underline{v}_i \right\|}$$

E Determinare una base ON dalla base di  
 $T \subseteq \mathbb{R}^4$  data da  $\left\{ \underline{t}_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \underline{t}_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \underline{t}_3 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$

$\{ \underline{t}_1, \underline{t}_2, \underline{t}_3 \}$  non è ON poiché

$$\begin{aligned} \|\underline{t}_1\| &= \sqrt{\underline{t}_1 \cdot \underline{t}_1} = \sqrt{(1 \ 0 \ 1 \ 0) \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}} = \sqrt{1 \cdot 1 + 0 \cdot 0 + 1 \cdot 1 + 0 \cdot 0} \\ &= \sqrt{2} \neq 1 \end{aligned}$$

cioè  $\underline{t}_1$  non è versore

Oppure  $\underline{t}_2$  non è ortogonale a  $\underline{t}_3$ :

$$\underline{t}_2 \cdot \underline{t}_3 = (0 \ 1 \ 1 \ 0) \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} = 0 \cdot 0 + 1 \cdot 0 + 1 \cdot 1 + 0 \cdot 1 = 1$$

A partire da  $\{ \underline{t}_1, \underline{t}_2, \underline{t}_3 \}$  ricaviamo una base ON applicando Gram-Schmidt.

$$\underline{v}_1 = \frac{\underline{t}_1}{\|\underline{t}_1\|}$$

$$\|\underline{t}_1\|$$

$$\|\underline{t}_1\| = \sqrt{\underline{t}_1 \cdot \underline{t}_1} = \sqrt{(1\ 0\ 1\ 0) \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}} = \sqrt{1 \cdot 1 + 0 \cdot 0 + 1 \cdot 1 + 0 \cdot 0} \\ = \sqrt{1+1} = \sqrt{2}$$

$$\underline{v}_1 = \frac{1}{\sqrt{2}} \underline{t}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1/\sqrt{2} \\ 0 \\ 1/\sqrt{2} \\ 0 \end{pmatrix}$$

$$\underline{v}_2 = \frac{\underline{t}_2 - (\underline{t}_2 \cdot \underline{v}_1) \underline{v}_1}{\|\underline{t}_2 - (\underline{t}_2 \cdot \underline{v}_1) \underline{v}_1\|}$$

$$\underline{t}_2 - (\underline{t}_2 \cdot \underline{v}_1) \underline{v}_1 = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} - \left[ \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right] \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{2} \left[ (0\ 1\ 1\ 0) \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right] \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{2} \left[ \underbrace{0 \cdot 1 + 1 \cdot 0 + 1 \cdot 1 + 0 \cdot 0}_1 \right] \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1/2 \\ 1 \\ 1-1/2 \\ 0 \end{pmatrix} = \begin{pmatrix} -1/2 \\ 1 \\ 1/2 \\ 0 \end{pmatrix}$$

$$\left\| \begin{pmatrix} -1/2 \\ 1 \\ 1/2 \\ 0 \end{pmatrix} \right\| = \sqrt{\begin{pmatrix} -1/2 \\ 1 \\ 1/2 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -1/2 \\ 1 \\ 1/2 \\ 0 \end{pmatrix}}$$

$$= \sqrt{\begin{pmatrix} -\frac{1}{2} & \frac{1}{2} & 0 \end{pmatrix} \begin{pmatrix} -1/2 \\ 1 \\ 1/2 \\ 0 \end{pmatrix}}$$

$$= \sqrt{\frac{1}{4} + 1 + \frac{1}{4} + 0} = \sqrt{\frac{6}{4}} = \frac{\sqrt{6}}{2}$$

$$\underline{v}_2 = \frac{2}{\sqrt{6}} \begin{pmatrix} -1/2 \\ 1 \\ 1/2 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix}$$

$$\underline{v}_3 = \frac{\underline{t}_3 - (\underline{t}_3 \cdot \underline{v}_1) \underline{v}_1 - (\underline{t}_3 \cdot \underline{v}_2) \underline{v}_2}{\| \underline{t}_3 - (\underline{t}_3 \cdot \underline{v}_1) \underline{v}_1 - (\underline{t}_3 \cdot \underline{v}_2) \underline{v}_2 \|}$$

$$\underline{t}_3 - (\underline{t}_3 \cdot \underline{v}_1) \underline{v}_1 - (\underline{t}_3 \cdot \underline{v}_2) \underline{v}_2 =$$

$$\begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} - \left[ \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right] \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} - \left[ \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \cdot \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix} \right] \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} - \frac{1}{2} \left[ (0011) \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right] \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{6} \left[ (0011) \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix} \right] \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} - \frac{1}{2} \left[ \underbrace{0+0+1+0}_1 \right] \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{6} \left[ \underbrace{0+0+1+0}_1 \right] \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix}$$

$$\dots$$

$$\begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{6} \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix} =$$

$$\begin{pmatrix} -1/2 + 1/6 \\ -2/6 \\ 1 - 1/2 - 1/6 \\ 1 \end{pmatrix} = \begin{pmatrix} -2/6 \\ -2/6 \\ 2/6 \\ 1 \end{pmatrix} = \begin{pmatrix} -1/3 \\ -1/3 \\ 1/3 \\ 1 \end{pmatrix}$$

$$\left\| \begin{pmatrix} -1/3 \\ -1/3 \\ 1/3 \\ 1 \end{pmatrix} \right\| = \sqrt{\begin{pmatrix} -1/3 \\ -1/3 \\ 1/3 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -1/3 \\ -1/3 \\ 1/3 \\ 1 \end{pmatrix}}$$

$$= \sqrt{(-1/3 \ -1/3 \ 1/3 \ 1) \begin{pmatrix} -1/3 \\ -1/3 \\ 1/3 \\ 1 \end{pmatrix}}$$

$$= \sqrt{\frac{1}{9} + \frac{1}{9} + \frac{1}{9} + 1}$$

$$= \sqrt{\frac{12}{9}} = \frac{1}{3} \sqrt{12}$$

$$\underline{v}_3 = \frac{3}{\sqrt{12}} \begin{pmatrix} -1/3 \\ -1/3 \\ 1/3 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{12}} \begin{pmatrix} -1 \\ -1 \\ 1 \\ 3 \end{pmatrix}$$

La ON di  $T$  ottenuta a partire da  $\{t_1, t_2, t_3\}$



La ON di  $T$  ottenuta a partire da  $\{t_1, t_2, t_3\}$   
 è  $\left\{ \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix}, \frac{1}{\sqrt{12}} \begin{pmatrix} -1 \\ -1 \\ 1 \\ 3 \end{pmatrix} \right\}$

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$$\begin{aligned} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \cdot \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix} &= \frac{1}{\sqrt{2}} \frac{1}{\sqrt{6}} \left[ (1 \ 0 \ 1 \ 0) \begin{pmatrix} -1 \\ 2 \\ 1 \\ 0 \end{pmatrix} \right] \\ &= \frac{1}{\sqrt{2}} \frac{1}{\sqrt{6}} \left[ \underbrace{1 \cdot (-1) + 0 \cdot 2 + 1 \cdot 1 + 0 \cdot 0}_{\substack{-1+1 \\ 0}} \right] \\ &= 0 \end{aligned}$$

Def Sia  $T \subseteq \mathbb{R}^m$  sottosp. vettoriale

IL COMPLEMENTO ORTOGONALE DI  $T$   
 $\bar{e}$

$$\begin{aligned} T^\perp &= \left\{ v \in \mathbb{R}^m \mid v \cdot t = 0_{\mathbb{R}} \quad \forall t \in T \right\} \\ &= \left\{ v \in \mathbb{R}^m \mid v \perp t \quad \forall t \in T \right\} \\ &= \left\{ v \in \mathbb{R}^m \mid v \perp T \right\} \end{aligned}$$

Se  $\dim T = k$  e  $\{t_1, \dots, t_k\}$  base di  $T$

allora

$$T^\perp = \{ v \in \mathbb{R}^m \mid v \cdot t_i = 0 \text{ per } i=1, \dots, k \}$$

### Proprietà del complemento ortogonale

$$\textcircled{1} T = \{0_{\mathbb{R}^m}\} \Rightarrow T^\perp = \mathbb{R}^m$$

$$\textcircled{2} T = \mathbb{R}^m \Rightarrow T^\perp = \{0_{\mathbb{R}^m}\}$$

$\textcircled{3}$   $T^\perp$  è un sottospazio vettoriale di  $\mathbb{R}^m$ .

dim 1  $\forall x = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix} \in \mathbb{R}^m$

$$x \cdot 0_{\mathbb{R}^m} = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix} \cdot \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$= (x_1 \dots x_m) \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$= x_1 \cdot 0 + x_2 \cdot 0 + \dots + x_m \cdot 0 = 0$$

$$\Rightarrow x \cdot 0_{\mathbb{R}^m} = 0 \quad \forall x \in \mathbb{R}^m$$

$$\Rightarrow x \perp 0_{\mathbb{R}^m} \quad \forall x \in \mathbb{R}^m$$

$$\begin{aligned} \Rightarrow \{0_{\mathbb{R}^m}\}^\perp &= \{x \in \mathbb{R}^m \mid x \perp 0_{\mathbb{R}^m}\} = \mathbb{R}^m \\ &= \{x \in \mathbb{R}^m \mid x \cdot 0_{\mathbb{R}^m} = 0\} = \mathbb{R}^m \end{aligned}$$

dm 2 Sia  $\{\underline{t}_1, \dots, \underline{t}_m\}$  base ON di  $\mathbb{R}^m$

$$\forall w \in \mathbb{R}^m = T \quad w = \lambda_1 \underline{t}_1 + \dots + \lambda_m \underline{t}_m$$

$$w \in T^\perp \iff w \cdot \underline{t}_i = 0 \quad \text{per } i=1, \dots, m$$

$\uparrow$   
 $\mathbb{R}^m$

$$\begin{aligned} 0 &= w \cdot \underline{t}_1 = (\lambda_1 \underline{t}_1 + \dots + \lambda_m \underline{t}_m) \cdot \underline{t}_1 \\ &= \lambda_1 \underbrace{\underline{t}_1 \cdot \underline{t}_1}_1 + \lambda_2 \underbrace{\underline{t}_2 \cdot \underline{t}_1}_0 + \dots + \lambda_m \underbrace{\underline{t}_m \cdot \underline{t}_1}_0 \\ &\quad \begin{array}{ccc} \|\underline{t}_1\|=1 & \underline{t}_2 \perp \underline{t}_1 & \underline{t}_m \perp \underline{t}_1 \\ \uparrow & \uparrow & \nearrow \\ & \{ \underline{t}_1, \dots, \underline{t}_m \} \text{ è base ON} & \end{array} \end{aligned}$$

$$= \lambda_1$$

$$0 = w \cdot \underline{t}_h = \lambda_h \quad \text{per } h=1, \dots, m$$

$$\Rightarrow \lambda_1 = \lambda_2 = \dots = \lambda_m = 0$$

$$\Rightarrow w = \lambda_1 \underline{t}_1 + \dots + \lambda_m \underline{t}_m = 0_{\mathbb{R}^m}$$

$$\text{Dunque } T^\perp = (\mathbb{R}^m)^\perp = \{0_{\mathbb{R}^m}\}$$

dm 3  $T^\perp$  è sotto sp. vettoriale  $(\Rightarrow)$

$T^\perp$  è chiuso rispetto alla somma di vettori e

$T^\perp$  è chiuso rispetto alla moltiplicazione

$T^\perp$  è chiuso rispetto alla moltiplicazione per uno scalare.

$$v_1, v_2 \in T^\perp = \left\{ w \in \mathbb{R}^m \mid w \cdot t = 0 \quad \forall t \in T \right\}$$

$$\Rightarrow v_1 \cdot t \stackrel{\text{⊗}}{=} 0_{\mathbb{R}} \quad v_2 \cdot t \stackrel{\text{⊗}}{=} 0_{\mathbb{R}} \quad \forall t \in T$$

Domanda  $v_1 + v_2 \in T^\perp$  ?

$$(v_1 + v_2) \cdot t \stackrel{\text{Ⓜ}}{=} v_1 \cdot t + v_2 \cdot t \quad \forall t \in T$$

$$\stackrel{\text{⊗} \quad \text{⊗}}{=} 0_{\mathbb{R}} + 0_{\mathbb{R}} = 0_{\mathbb{R}}$$

$$\Rightarrow v_1 + v_2 \in T^\perp$$

Sia  $\lambda \in \mathbb{R}$ ,  $v \in T^\perp$  cioè  $v \cdot t \stackrel{\text{⊗}}{=} 0_{\mathbb{R}} \quad \forall t \in T$

Domanda  $\lambda v \in T^\perp$  ?

$$(\lambda v) \cdot t \stackrel{\text{Ⓜ}}{=} \lambda (v \cdot t) \stackrel{\text{⊗}}{=} \lambda 0_{\mathbb{R}} = 0_{\mathbb{R}}$$

$$\Rightarrow \lambda v \in T^\perp$$

Proprietà  $T \subseteq \mathbb{R}^m$

$$\textcircled{1} T \cap T^\perp = \{0_{\mathbb{R}^m}\} \quad (\Rightarrow T \oplus T^\perp)$$

$$\textcircled{2} (T^\perp)^\perp = T$$

$$\textcircled{2} (T^\perp)^\perp = T$$

$$\textcircled{3} T_1 \subseteq T_2 \Rightarrow T_1^\perp \supseteq T_2^\perp$$

$$\textcircled{4} (T_1 + T_2)^\perp = T_1^\perp \cap T_2^\perp$$

$$\textcircled{5} (T_1 \cap T_2)^\perp = T_1^\perp + T_2^\perp .$$