

$$m_1 = 1 \text{ kg}$$

$$m_2 = 4 \text{ kg}$$

$$m_3 = 3 \text{ kg}$$

$$v_1 = 2 \text{ m/s}$$

$$v_3 = -1 \text{ m/s}$$

$$v_2 = 0 \text{ m/s}$$

$$v_{CM} = ?$$

(v_{sist})

$$P = m_{TOT} \cdot v_{CM} = (\text{cost})$$

in assenza
di \vec{F} esterne

$$\vec{P} = \sum_i m_i \vec{v}_i = m_1 \vec{v}_1 + m_2 \vec{v}_2 + m_3 \vec{v}_3$$

$$P = 1 \cdot 2 + 3 \cdot (-1) = -1 \text{ N s}$$

$$M_{TOT} \cdot v_{CM} = -1 (=P)$$

$$v_{CM} = \frac{P}{M_{TOT}} = \frac{-1}{1+4+3} = -\frac{1}{8} \text{ m/s} = -0,125 \text{ m/s}$$

(ip: urto anelastico)

ΔP_i PUNTO ①

$$\Delta P_i = m_i (\Delta v_i) = m_i (v_{fin} - v_{in})$$

$$\Delta P_1 = m_1 (\Delta v_1) = m_1 (v_{fin} - v_{in})$$

$$= 1 (-0,125 - 2)$$

$$= (-2,125 \text{ N s})$$

$$\Delta E_{K_3} = \frac{1}{2} m_3 (\Delta v_3)^2 \rightsquigarrow NO$$

$$\left(-0,125 - 1 \right)^2 \rightsquigarrow (-1,125)^2$$

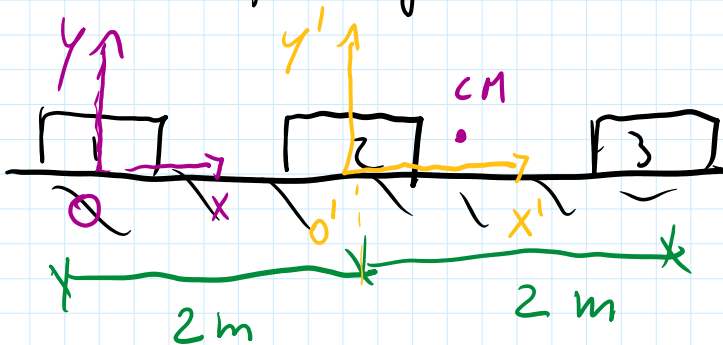
$$\Delta E_{K_3} = \frac{1}{2} m_3 (v_{cm})^2 - \frac{1}{2} m_3 (v_3)^2$$

$$= \frac{1}{2} \cdot 3 (-0,125)^2 - \frac{1}{2} \cdot 3 (-1)^2$$

$$= (-1,477 \text{ J})$$

(in cinetica
è diminuita)

Ora corpi fermi $\rightsquigarrow X_{CM}$?



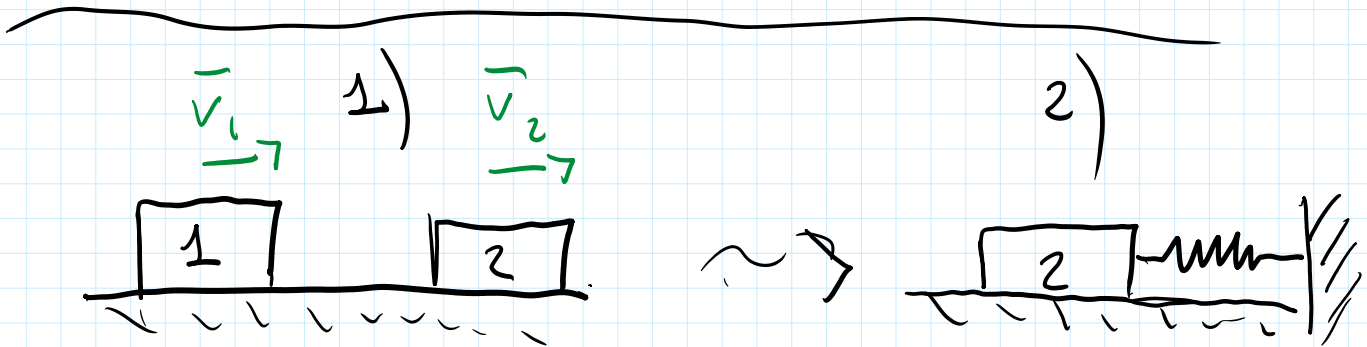
$$X_{CM} = \frac{(v_1 m_1) + x_1 m_1 + x_2 m_2 + x_3 m_3}{m_1 + m_2 + m_3}$$

($\odot \times y$)

$$\begin{aligned}
 & \overbrace{m_1 + m_2 + m_3} \\
 & = \frac{0 \cdot 2 + 2 \cdot 4 + 4 \cdot 3}{8} = 2,5 \text{ m}
 \end{aligned}$$

$$\begin{aligned}
 X_{CM} &= \frac{-2 \cdot 2 + 0 \cdot 4 + 2 \cdot 3}{8} \\
 & \approx 0,5 \text{ m}
 \end{aligned}$$

(o'x'y)



$$m_1 = m_2 = 0,5 \text{ kg}$$

$$v_1 = 10 \text{ m/s}$$

$$\mu = 0$$

$$v_2 = 5 \text{ m/s}$$

$$\text{URTO ELASTICO} \rightarrow \left(\begin{aligned} \vec{P}_{TOT} &= \text{cost} \\ E_{K_{TOT}} &= \text{cost} \end{aligned} \right)$$

$$m_1 v_1 + m_2 v_2 = m_1 v_1' + m_2 v_2' = (m_1 + m_2) \cdot v_{CM}$$

$$\frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 = \frac{1}{2} m_1 (v_1')^2 + \frac{1}{2} m_2 (v_2')^2 = \left(\frac{1}{2} M_{TOT} (v_{CM})^2 \right)$$

$$(v' = v_{lin})$$

$$(v' = v_{fin})$$

$$\left\{ \begin{array}{l} 0,5(10+5) = 0,5(v_1' + v_2') \\ \backslash \end{array} \right.$$

$$\left\{ \begin{array}{l} 15 = v_1' + v_2' \leadsto v_1' = 15 - v_2' \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{1}{2} \cdot 0,5 \cdot 100 + \frac{1}{2} \cdot 0,5 \cdot 25 = \frac{1}{2} \cdot 0,5 (15 - v_2')^2 + \frac{1}{2} \cdot 0,5 (v_2')^2 \end{array} \right.$$

$$\left\{ \begin{array}{l} \backslash \\ 125 = (v_2')^2 - 30(v_2') + 225 + (v_2')^2 \end{array} \right.$$

$$\left\{ \begin{array}{l} \backslash \\ 2(v_2')^2 - 30v_2' + 100 = 0 \end{array} \right.$$

$$(v_2')^2 - 15v_2' + 50 = 0$$

$$(v_2' - 10)(v_2' - 5) = 0$$

$$\begin{array}{l} \nearrow v_2' = 10 \text{ m/s (I)} \\ \searrow v_2' = 5 \text{ m/s (II)} \end{array}$$

II)

$$v_2' = 5 \text{ m/s}$$

$$v_1' = 10 \text{ m/s}$$

CASO SISTEMA
IN CUI 2 MASSE
NON SI TOCCANO,
OWERO SONO IN

MOTO STAZIONARIO

$$I) \left. \begin{array}{l} v_2' = 10 \text{ m/s} \\ v_1' = 5 \text{ m/s} \end{array} \right\} \begin{array}{l} \text{SOLUZIONE CERCAIA} \\ \text{URTO ELASTICO} \end{array}$$

\bar{V} corpo 2 rispetto corpo 1

$$\leadsto v_{2 \text{ REL}}' = 5 \text{ m/s} \quad \left(\underbrace{\bar{V}_{\text{TOT}}}_{10 \text{ m/s}} = \underbrace{\bar{V}_{\text{SISTEMA RELATIVO}}}_{5 \text{ m/s}} + \underbrace{\bar{V}_{\text{CORPO RELATIVA}}}_{5 \text{ m/s}} \right)$$

$$\left(\begin{array}{l} F = m \cdot a \quad - K \cdot x = m \frac{d^2 x}{dt^2} \\ \text{BILANCIO FORZE} \\ \left(\sqrt{\frac{m}{K}} = \omega \right) \quad x = -\omega^2 \frac{dx}{dt^2} \end{array} \right)$$

BILANCIO ENERGIA

$$E_{\text{TOT}} = \text{cost}$$

↓

$$E_K + E_{\text{elastica}} = \text{cost}$$

$$\left(\frac{1}{2} m (v_2')^2 = \frac{1}{2} K (\Delta x)^2 + \text{cost} \right)$$

$$\left(\frac{1}{2} m (V_2)^2 = \frac{1}{2} K (\Delta x) + c_0 v t \right)$$

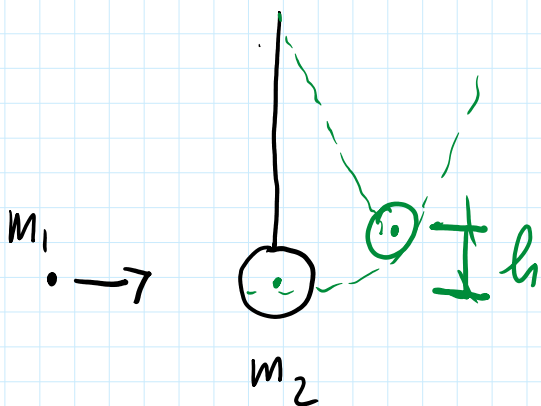
\leadsto caso $\Delta x_{MAX} \leadsto$ TUTTA CINETICA
 DIVENTA
 ELASTICA
 \uparrow
 $\equiv A$

$$E_K = \frac{1}{2} 0,5 \cdot 10^2 = 25 \text{ J}$$

$$E_{EL, MAX} = \frac{1}{2} K A^2 = E_K$$

$$25 = \frac{1}{2} K \cdot (0,38)^2$$

$$K = \frac{50}{(0,38)^2} = 346 \text{ N/m}$$



$$m_1 = 0,1 \text{ kg}$$

$$m_1 + m_2 = 10 \text{ kg}$$

$$V_1 = 200 \text{ m/s}$$

$$T = 5 \cdot 10^{-4} \text{ s}$$

$$P = c_0 v t$$

$$(m_1 + m_2) \cdot v_{cm} = m_1 v_1 + m_2 v_2$$

$$v_{cm} = \frac{m_1 v_1 + m_2 v_2}{m_1 + m_2} = \frac{0,1 \cdot 200 + 9,9 \cdot 0}{10} = 2 \text{ m/s}$$

$$\left(\sum F = m \cdot a \right) \quad \times$$

$$\underline{E_{TOT} = c o n s t}$$

$$\frac{1}{2} (m_1 + m_2) v_{cm}^2 = E_K = \frac{1}{2} \cdot 10 \cdot 2^2 = 20 \text{ J}$$

$E_{GRAV MAX} \rightsquigarrow$ TUTTA CINETICA DIVENTA GRAVITAZIONALE \rightsquigarrow h MASSIMA

$$E_{GRAV MAX} = m \cdot g \cdot h$$

$$\rightarrow 20 = 10 \cdot 9,8 \cdot h$$

$$h = \frac{20}{10 \cdot 9,8} = \underline{0,2 \text{ m}}$$

TEO MEDIA INTEGRALE

$$\Delta P = \int_{t_1}^{t_2} F dt = F_m \cdot \tau$$

$$\Delta P = \int_{t_1}^{t_2} F d\tau \stackrel{v}{=} F_m \cdot \tau$$

$$J = \int_{t_1}^{t_2} F d\tau = F_m \cdot \tau$$

$$\Delta P = (m_1 + m_2) v_2' = \cancel{m_2} v_2$$
$$= 20 \text{ N s}$$

$$\Delta P = F_m \cdot \tau \quad \leadsto \quad F_m = \frac{\Delta P}{\tau} = \frac{20}{5 \cdot 10^{-4}} = 40000 \text{ N}$$
$$= 40 \text{ kN}$$