

Es1

$$y(n) = x(n-2) + \sum_{k=-\infty}^{-n-5} x(k) \frac{1}{3^{n-k}}$$

NO! STATICO, NO DEPENDENZA n=10

- 1) DIREZIONE: CAUSALE, LINEARE, TEMPORALMENTE INVARIANTE
- 2) RISPOSTA IMPULSIVA
- 3) BIBO STABILE?

$$y(n-n_0) = x(n-n_0-2) + \sum_{k=-\infty}^{-n-n_0-5} x(k) \frac{1}{3^{n-n_0-k}}$$

$$T[x(n-n_0)] = x(n-2-n_0) + \sum_{k=-\infty}^{-n-5} x(k-n_0) \frac{1}{3^{n-k}}$$

$$= x(n-2-n_0) + \sum_{m=-\infty}^{-n-n_0-5} x(m) \frac{1}{3^{n-m-n_0}}$$

$m = k-n_0$
 $k = m+n_0$

$$g(n) = T[\delta(n)] = \delta(n-2) + \sum_{k=-\infty}^{-n-5} \delta(k) \frac{1}{3^{n-k}}$$

$$= \delta(n-2) + \begin{cases} \frac{1}{3} \cdot \frac{1}{3^n} & n \leq -5 \\ 0 & \text{altrimenti} \end{cases}$$

RANGE k INCLUSE 0
RANGE k NON INCLUSE 0

$n-5 \geq 0$
 $n \leq 5$

NON BIBO STABILE

$\sum_{k=-\infty}^{-n-5} \delta(k) \frac{1}{3^{n-k}} \Rightarrow \delta(k) \frac{1}{3^n}$

$$= \frac{1}{3^n} \sum_{k=-\infty}^{-n-5} \delta(k)$$

Es2 4° APPRENDIO 10/2/2022

$x(t) \rightarrow \downarrow T=1/3 \rightarrow \uparrow g(t) \rightarrow \downarrow T=1/3 \rightarrow \uparrow h(t) \rightarrow y(t)$

PASSABANDA IDEALE PULS. DI TRAGUARDI $\omega_c = 2\pi$
 $1 \uparrow G(\omega)$

1) $Z(j\omega) = ?$
2) TRAVARE $h(t)$ CHE ASSICURI $y(t) = x(t)$

$$Z(j\omega) = \frac{1}{T} G(j\omega) \text{ REP } \frac{2\pi}{T} X(j\omega)$$

$$= 3 G(j\omega) \text{ REP } \frac{2\pi}{3} X(j\omega)$$

$$Z(j\omega) = 3 [X(j\omega) + X(j\omega - 6\pi) + X(j\omega + 6\pi)]$$

$$z(t) = 3 [x(t) + x(t) e^{j6\pi t} + x(t) e^{-j6\pi t}]$$

$$= 3 x(t) [1 + 2 \cos(6\pi t)]$$

$$Y(j\omega) = \frac{1}{T} H(j\omega) \text{ REP } \frac{2\pi}{T} Z(j\omega)$$

$$= 3 H(j\omega) \text{ REP } \frac{2\pi}{3} Z(j\omega)$$

$$\text{REP } \frac{2\pi}{3} Z(j\omega) = \text{REP } \frac{2\pi}{3} [3X(j\omega) + 3X(j\omega - 6\pi) + 3X(j\omega + 6\pi)]$$

$$= \text{REP } \frac{2\pi}{3} 3X(j\omega) + \text{REP } \frac{2\pi}{3} 3X(j\omega - 6\pi) + \text{REP } \frac{2\pi}{3} 3X(j\omega + 6\pi)$$

$$= 3 \text{ REP } \frac{2\pi}{3} X(j\omega)$$

$$Y(j\omega) = 3 H(j\omega) \text{ REP } \frac{2\pi}{3} X(j\omega)$$

$$= 27 H(j\omega) \text{ REP } \frac{2\pi}{3} X(j\omega)$$

$$27 H(j\omega) = \text{rect}(\frac{\omega}{6\pi})$$

$$H(j\omega) = \frac{1}{27} \text{rect}(\frac{\omega}{6\pi})$$

$$= \frac{1}{3} \cdot \frac{1}{3} \text{rect}(\frac{1}{3} \frac{\omega}{2\pi})$$

$$h(t) = \frac{1}{9} \text{sinc}(3t)$$

Es3

$$X(j\omega) = \frac{\text{sinc}(\frac{3\omega}{\pi})}{3\omega} \cdot 3 + j \omega^2 \cos(2\omega)$$

- 1) $X \in \mathbb{R}$ IMMAGINARIO? NO
- 2) $A_x = ?$

$A_x = X(j0) = 3 + j \cdot 0 = 3$

PARTE REALE DISPARI X
PARTE IMMAGINARIA PARI ✓

Es4 TERZO APPRENDIO 7/8/2021

$$H(z) = \frac{1}{(z^2+1)(z^2+3)} = \frac{1}{(z^2+j)(z^2-j)(z^2+3)}$$

- 1) POLI
- 2) BIBO STABILITA'

$z^2+1 = (z-j)(z+j)$
 $z^2+3 = (z-\sqrt{3}j)(z+\sqrt{3}j)$

$z^2+1 \rightarrow \text{POLI } z = \pm \frac{1}{j}$
 $z^2+3 \rightarrow \text{POLI } z = \pm \frac{1}{\sqrt{3}}$

$\alpha = \begin{cases} -j \\ j \\ -\sqrt{3}j \\ \sqrt{3}j \end{cases}$
 $R = \frac{1}{\alpha} = \begin{cases} j \\ -j \\ \sqrt{3} \\ -\sqrt{3} \end{cases}$

2 POLI SUL CERCHIO DI RAGGIO UNITARIO
NON BIBO STABILE

$$H(z) = \frac{R_0}{z^2+j} + \frac{R_1}{z^2-j} + \frac{R_2}{z^2+3}$$

$$h(n) = -R_0 j^{n+1} 1_0(n) - R_1 (-j)^{n+1} 1_0(n) - R_2 (\frac{1}{\sqrt{3}})^{n+1} 1_0(n)$$

non si cancellano!!!
SISTEMA

3) IDENTIFICARE UN'USCITA $x(n)$ CHE DA UN'USCITA NON LINEARE

$$(n+1) p_0^{n+1} 1_0(n) \xrightarrow{z} \frac{1}{(z^2 - \frac{1}{p_0})^2}$$

$$X(z) = \frac{1}{z^2+j}$$

$$Y_f(z) = X(z)H(z) = \frac{1}{(z^2+j)^2(z^2-j)(z^2+3)}$$

$$= \frac{R_0}{(z^2+j)^2} + \frac{R_1}{(z^2-j)} + \frac{R_2}{z^2-j} + \frac{R_3}{z^2+3}$$