

SINGULARITIES OF SMOOTH MAPPINGS

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ABSTRACT. In this seminar we want to provide a classification scheme for singularities of smooth mappings due to Thom and Boardman. According to the framework developed in [2] we remind the notions of Jet Bundles and Thom's transversality and then we introduce the intrinsic derivative of maps between bundles. We apply these tools to give a classification of singularities for a generic class of mappings and we illustrate applications to one and two dimensional cases. In particular, we show a result by Morse for the local behavior of a function near a non-degenerate critical point and the results by Whitney on the singularities of mappings between 2-manifolds (see [3]). In the end we define the Thom-Boardman stratification for the general case.

The restricted time frame prevents a presentation of a second scheme of classification, based on the "local ring" of a map, for which we refer to [1] and [2](Chapter VII).

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1. PRELIMINARIES

1.1. Jet Bundles.

Definition 1. Let X, Y be smooth manifolds and $p \in X$. Let $f, g : X \rightarrow Y$ be smooth mappings such that $f(p) = g(p) = q$.

- (1) $f \sim_1 g$ at $p \stackrel{def}{\iff} df(p) = dg(p)$ as linear mappings $T_p X \rightarrow T_q Y$.
- (2) $f \sim_k g$ at $p \stackrel{def}{\iff} df(p) \sim_{k-1} dg(p)$ at every point of $T_p X$.
- (3) Let $J^k(X, Y)_{p,q}$ be the set of the equivalence classes under the relation " $\sim_k$ at p " of mappings $f : X \rightarrow Y$, with $f(p) = q$.
- (4) Set $J^k(X, Y) = \bigsqcup_{(p,q) \in X \times Y} J^k(X, Y)_{p,q}$. An element $\sigma \in J^k(X, Y)$ is called k -jet.
- (5) Let σ a k -jet. Then there exist $p \in X$ and $q \in Y$ such that $\sigma \in J^k(X, Y)_{p,q}$: p is called *source of σ* and q is called *target of σ* . Moreover

$$\begin{aligned} \alpha : J^k(X, Y) &\rightarrow X \\ \sigma &\longmapsto (\text{source of } \sigma) \end{aligned}$$

is the *source map* and

$$\begin{aligned} \beta : J^k(X, Y) &\rightarrow Y \\ \sigma &\longmapsto (\text{target of } \sigma) \end{aligned}$$

is the *target map*.

Note that given $f : X \rightarrow Y$ is defined canonically the mapping

$$j^k f : X \rightarrow J^k(X, Y)$$

$$p \mapsto j^k f(p) = \text{the equivalence class of } f \text{ in } J^k(X, Y)_{p, f(p)}$$

Proposition 1. Let $U \subset \mathbb{R}^n$ open, then $f, g : U \rightarrow \mathbb{R}^m$ are such that $f \sim_k g$ at $p \iff$ the Taylor expansions of f and g up to order k are identical at p . Hence we can write $j^k f(p) = (p, f(p), T_k f_1(p), \dots, T_k f_m(p))$, where

$$T_k f_i(p) = \sum_{|\alpha| > 0} \frac{\partial^{|\alpha|} f_i}{\partial x^\alpha}(p) \frac{(x - p)^\alpha}{\alpha!}.$$

Let A_n^k be the vector space of polynomials in n -variables of degree $\leq k$ which have their constant term equal to zero. One can choose as coordinates for A_n^k the coefficients of the polynomials. Then A_n^k is isomorphic to some Euclidean space $\mathbb{R}^l$. Let $B_{n,m}^k = \bigoplus_{i=1}^m A_n^k$.

Theorem 1. Let X and Y be smooth manifolds of dimension n and m respectively. Then

- (1) $J^k(X, Y)$ is a smooth manifold, with
$$\dim J^k(X, Y) = m + n + \dim(B_{n,m}^k).$$
- (2) $\alpha : J^k(X, Y) \rightarrow X$, $\beta : J^k(X, Y) \rightarrow Y$ and $\alpha \times \beta : J^k(X, Y) \rightarrow X \times Y$ are submersions.
- (3) If $g : X \rightarrow Y$ is smooth then $j^k g : X \rightarrow J^k(X, Y)$ is smooth.

Proposition 2. Let X, Y be smooth manifolds. Then $J^k(X, Y)$ is a fiber bundle over $X \times Y$, with fiber $B_{n,m}^k$.

If $Y = \mathbb{R}^m$ then $J^k(X, \mathbb{R}^m)$ is a vector bundle over $X \times \mathbb{R}^m$, where the addition of jets in $J^k(X, \mathbb{R}^m)_{p,q}$ is given by the addition of functions representing these jets. Moreover $J^1(X, Y)$ is canonically isomorphic to $\text{Hom}(TX, TY)$, hence using this identification we can think of $J^1(X, Y)$ as a vector bundle over $X \times Y$ with fiber $\text{Hom}(\mathbb{R}^n, \mathbb{R}^m) \cong B_{n,m}^1$.

1.2. The Whitney $\mathcal{C}^\infty$ Topology. In this section our aim is to introduce a topology on $\mathcal{C}^\infty(X, Y)$.

Definition 2. Let X, Y be smooth manifolds.

- (1) Let $k \in \mathbb{N}$. Let $U \subset J^k(X, Y)$ be an open set.

$$M(U) := \{f \in \mathcal{C}^\infty(X, Y) \mid j^k f(X) \subset U\}$$

(Note that $M(U \cap V) = M(U) \cap M(V)$)

The family

$$\left\{ M(U) \mid U \underset{\text{open}}{\subset} J^k(X, Y) \right\}$$

form a basis for a topology on $\mathcal{C}^\infty$. This topology is called the Whitney $\mathcal{C}^k$ Topology.

- (2) Let's denote with W_k the set of all open sets in $\mathcal{C}^\infty(X, Y)$ with Whitney $\mathcal{C}^k$ Topology, for every k . Then

$$W = \bigcup_{k=0}^{\infty} W_k$$

form a basis for Whitney $\mathcal{C}^\infty$ Topology on $\mathcal{C}^\infty(X, Y)$.

Theorem 2. Let X, Y be smooth manifolds. Then $\mathcal{C}^\infty(X, Y)$ is a Baire space in the Whitney $\mathcal{C}^\infty$ Topology.

(Note that by definition in a Baire space every residual subset, which is a countable intersection of open dense subsets, is dense).

2. TRANSVERSALITY

Definition 3. Let X and Y be smooth manifolds of dimensions n and m respectively. Let $f : X \rightarrow Y$ be a smooth mapping. Let W be a regular submanifold of Y and x a point in X . Then we say that f is transversal to W at x ($f \pitchfork W$ at x) if either

- $f(x) \notin W$ or
- $f(x) \in W$ and $T_{f(x)}Y = T_{f(x)}W + \text{Im } df(x)$
(where $df(x) : T_x X \rightarrow T_{f(x)}Y$)

We say that f is transversal to W if $f \pitchfork W$ at every point $x \in X$.

Proposition 3. Let X, Y be smooth manifolds. Let $f : X \rightarrow Y$ be a differentiable mapping and let W be a regular submanifold of Y . Suppose that

- $\dim X + \dim W < \dim Y$.
- $f \pitchfork W$.

The $f(X) \cap W = \emptyset$.

Lemma 1. *Let X, Y be smooth manifolds, $W \subset Y$ a submanifold, and $f : X \rightarrow Y$ smooth. Let $p \in X$ and $f(p) \in W$. Suppose there is a neighborhood U of $f(p)$ in Y and a submersion $\phi : U \rightarrow \mathbb{R}^k$ ($k = \text{codim } W$) such that $W \cap U = \phi^{-1}(0)$. Then $f \pitchfork W$ at p iff $\phi \circ f$ is a submersion at p .*

Remark 1. Note that such a neighborhood always exists. For there exists a chart (U, α) , $\alpha : U \rightarrow \mathbb{R}^m$ and a decomposition of $\mathbb{R}^m = \mathbb{R}^k \times \mathbb{R}^{m-k}$ so that $W \cap U = \alpha^{-1}(0_k \times \mathbb{R}^{m-k})$. Let $\pi : \mathbb{R}^m \rightarrow \mathbb{R}^k$ be the projection on the first factor, then $\phi = \pi \circ \alpha$.

Proof. By assumption we have that $\text{Ker } d\phi(f(p)) = T_{f(p)}W$. So $f \pitchfork W$ at p if and only if

$$\begin{aligned} T_{f(p)}Y &= T_{f(p)}W + df(p)(T_pX) \\ \Leftrightarrow T_{f(p)}Y &= \text{Ker } d\phi(f(p)) + df(p)(T_pX) \end{aligned}$$

Since $d\phi(f(p))$ is surjective we have that $d(\phi \circ f)(p)$ is surjective $\Leftrightarrow$ the last equality holds. Thus $\phi \circ f$ is a submersion iff $f \pitchfork W$ at p . $\square$

Theorem 3. *Let $f : X \rightarrow Y$ be transversal to the regular submanifold W of Y (set $\text{codim } W = k$). Then $f^{-1}(W)$ is a regular submanifold of X of codimension k .*

Theorem 4 (Thom's Transversality Theorem). *Let X and Y be smooth manifolds of dimensions n and m respectively. Let W be a submanifold of $J^k(X, Y)$. Let*

$$T_W = \left\{ f \in \mathcal{C}^\infty(X, Y) \mid j^k f \pitchfork W \right\}.$$

Then T_W is a residual subset of $\mathcal{C}^\infty(X, Y)$ in the Whitney $\mathcal{C}^\infty$ Topology.

3. CLASSIFICATION OF SINGULARITIES

3.1. S_r singularities. We give a first classification of singularities of a smooth mapping. Let σ be in $J^1(X, Y)$. Then $\sigma \in J^1(X, Y)_{p,q}$ for some $(p, q) \in X \times Y$. We have that $J^1(X, Y) \cong \text{Hom}(TX, TY)$, then σ defines a unique linear map $T_pX \rightarrow T_qY$. If $f \in \mathcal{C}^\infty(X, Y)$ is a representative for σ (i.e. $j^1 f(p) = \sigma$) then this map is $df(p)$. Define:

- $\text{rank } \sigma = \text{rank } df(p)$
- $\text{corank } \sigma = l - \text{rank } df(p)$, with $l = \min\{\dim X, \dim Y\}$

Let:

$$S_r = \left\{ \sigma \in J^1(X, Y) \mid \text{corank } \sigma = r \right\}$$

Let V, W be vector spaces. Let $S : V \rightarrow W$ be a linear map and define $\text{corank } S = q - \text{rank } S$, with $q = \min\{\dim V, \dim W\}$. Define

$$L^r(V, W) = \left\{ S : V \rightarrow W \mid \text{corank } S = r \right\}$$

Let $n = \dim V$, $m = \dim W$.

Proposition 4. *$L^r(V, W)$ is a submanifold of $\text{Hom}(V, W)$, with*

$$\text{codim } L^r(V, W) = (m - q + r)(n - q + r).$$

Theorem 5. Let X, Y be manifolds, with $n = \dim X$, $m = \dim Y$, $q = \min\{\dim X, \dim Y\}$. Then S_r is a submanifold of $J^1(X, Y)$, with $\text{codim} S_r = (n - q + r)(m - q + r)$. In fact, S_r is a subfiber-bundle of $J^1(X, Y)$ with fiber $L^r(\mathbb{R}^n, \mathbb{R}^m)$.

Lemma 2. $f : X \rightarrow Y$ is an immersion $\Leftrightarrow j^1 f(X) \cap (\bigcup_{r \neq 0} S_r) = \emptyset$

Let $\text{Im}(X, Y)$ be the subset of immersions in $\mathcal{C}^\infty(X, Y)$.

Theorem 6 (Whitney Immersion Theorem). Let X, Y be smooth manifolds with $\dim Y \geq 2 \cdot \dim X$. Then $\text{Im}(X, Y)$ is an open dense subset of $\mathcal{C}^\infty(X, Y)$ (in the Whitney $\mathcal{C}^\infty$ Topology).

Definition 4. Let $f : X \rightarrow Y$. We say that f has a singularity of type S_r at $x \in X$ if $\text{rank } df(x) = q - r$, ($q = \min\{\dim X, \dim Y\}$).

Let $S_r(f) \subset X$ be the set of all singularities of f of type S_r . Clearly $S_r(f) = (j^1 f)^{-1}(S_r)$. Hence, by Thom Transversality Theorem, there exists an open and residual subset $G \subset \mathcal{C}^\infty(X, Y)$ such that $S_r(f)$ is a submanifold of X and $\text{codim} S_r(f) = \text{codim} S_r = (n - q + r)(m - q + r)$, $\forall f \in G$.

Definition 5. We will say that a mapping $f : X \rightarrow Y$ is *one generic* if $j^1 f \bar{\cap} S_r$, for all r .

3.2. The Intrinsic Derivative. In this section we develop a technique due to Porteous for differentiating maps between vector bundles. This is the intrinsic derivative and it plays a rather important role in the Thom-Boardman theory. First we give a local definition of this notion and later a more global one.

Let X be a manifold and let $E = X \times \mathbb{R}^k$, $F = X \times \mathbb{R}^l$ be two product bundles over X . Let $\rho : E \rightarrow F$ be a vector bundle homomorphism. * Then for all $p \in X$, $\rho_p : \mathbb{R}^k \rightarrow \mathbb{R}^l$ is a linear map hence we can view ρ as a mapping

*Given two vector bundles $E \rightarrow X$, $F \rightarrow Y$, a map $\phi : E \rightarrow F$ is said to be a vector bundle homomorphism if

- (1) $\exists$ a function $f : X \rightarrow Y$ called *base map* s.t.

$$\begin{array}{ccc} E & \xrightarrow{\phi} & F \\ \downarrow & & \downarrow \\ X & \xrightarrow{f} & Y \end{array}$$

commutes.

- (2) ϕ is smooth.
 (3) $\phi_p : E_p \rightarrow E_{f(p)}$ is a linear map.

If the two vector bundles have the same base manifold X , then the vector bundle homomorphisms are those with the identity as base map, i.e. those for which the following diagram commutes

$$\begin{array}{ccc} E & \xrightarrow{\phi} & F \\ & \searrow & \swarrow \\ & X & \end{array}$$

$X \rightarrow \text{Hom}(\mathbb{R}^k, \mathbb{R}^l)$. Then for $p \in X$ makes sense to consider the differential

$$(d\rho)_p : T_p X \rightarrow T_p \text{Hom}(\mathbb{R}^k, \mathbb{R}^l) = \text{Hom}(\mathbb{R}^k, \mathbb{R}^l)$$

Let $K_p = \ker \rho(p)$ and $L_p = \text{coker} \rho(p)$. We define the intrinsic derivative of ρ at p , $(D\rho)_p$, in this trivial situation by the composite map

$$T_p X \rightarrow \text{Hom}(\mathbb{R}^k, \mathbb{R}^l) \rightarrow \text{Hom}(K_p, L_p)$$

where the second arrow is given by "restricting and projecting". It's easy to see that the intrinsic derivative is invariant under vector bundle isomorphisms.

In general, let E and F be vector bundles over X and $\rho : E \rightarrow F$ be a vector bundle homomorphism. Then fixing $p \in X$, we can set $K_p = \ker \rho(p)$ and $L_p = \text{coker} \rho(p)$. We may define the *intrinsic derivative of ρ at p*

$$(D\rho)_p : T_p X \rightarrow \text{Hom}(K_p, L_p)$$

by choosing a local trivialization of E and F in a neighborhood of p and computing as above. Since the definition is invariant under VB -isomorphism then the intrinsic derivative is independent of the choice of trivializations.

Now we give another definition of intrinsic derivative. Consider again the submanifold $L^r(V, W) \subset \text{Hom}(V, W)$ and let $A \in L^r(V, W)$, $K_A = \ker A$, $L_A = \text{coker} A$. Let N_A be the normal sapce to $L^r(V, W)$ at the point A , i.e.

$$N_A = \frac{T_A \text{Hom}(V, W)}{T_A L^r(V, W)}.$$

Then there is a canonical identification $N_A \cong \text{Hom}(K_A, L_A)$. This fact holds for vector bundles as well.

Let $E \rightarrow X$, $F \rightarrow X$ be vector bundles. Then we have the subfiber bundle $L^r(E, F)$ of $\text{Hom}(E, F)$, with generic fiber $L^r(E_x, F_x)$. Let $\sigma \in L^r(E_x, F_x)$. Since we are dealing with fiber bundles

$$N_\sigma = \frac{T_\sigma \text{Hom}(E, F)}{T_\sigma L^r(E, F)} = \frac{T_\sigma \text{Hom}(E_x, F_x)}{T_\sigma L^r(E_x, F_x)}$$

Then as in the case of vector spaces $N_\sigma \cong \text{Hom}(K_\sigma, L_\sigma)$, where $K_\sigma = \ker \sigma$, $L_\sigma = \text{coker} \sigma$.

Let $\rho : E \rightarrow F$ be a vector bundles homomorphism. Looking at ρ as a map $X \rightarrow \text{Hom}(E, F)$ we set $\sigma = \rho_x$ and we assume $\text{corank} \sigma = r$ (hence $\sigma \in L^r(E, F)$). Then $(D\rho)_x$ is the composite map

$$T_x X \xrightarrow{(d\rho)_x} T_x \text{Hom}(E, F) \longrightarrow \frac{T_\sigma \text{Hom}(E, F)}{T_\sigma L^r(E, F)} \cong \text{Hom}(K_\sigma, L_\sigma)$$

One can immediately proves the following:

Proposition 5. *Suppose $\sigma = \rho_x$ is of corank r . Then the following are equivalent:*

(1) $(D\rho)_x : T_x X \rightarrow \text{Hom}(K_\sigma, L_\sigma)$ is surjective.

(2) $\rho \bar{\cap} L^r(E, F)$ at x .

Let $f : X \rightarrow Y$ be a smooth map. Consider the homomorphism between vector bundles

$$df : TX \rightarrow f^*TY$$

and fix $x \in X$.

We want to compute the intrinsic derivative

$$D(df)_x : T_x X \rightarrow \text{Hom}(K_x, L_x)$$

where $K_x = \ker(df)_x$, $L_x = \text{coker}(df)_x$. We trivialize the tangent bundles by choosing coordinates $(x_1, \dots, x_n)$ centered at x and $(y_1, \dots, y_m)$ centered at $y = f(x)$. Moreover we choose this coordinates such that $(df)_x$ has the form

$$\left(\begin{array}{c|c} I_s & 0 \\ \hline 0 & 0 \end{array} \right)$$

In terms of these coordinates the last $m - s$ coordinate functions of f can be written in the form:

$$f_\alpha = \sum_{i,j=1}^s a_\alpha^{ij} x_i x_j + \sum_{j=1}^s \sum_{\beta=s+1}^n b_\alpha^{ij} x_\beta x_j + \sum_{\beta,\gamma=1}^n c_\alpha^{\beta\gamma} x_\beta x_\gamma + O(|x|^3)$$

$$\alpha = s+1, \dots, m$$

We have that $\text{Hom}(T_x X \otimes K_x, L_x) \cong \text{Hom}(T_x X, \text{Hom}(K_x, L_x))$, hence the intrinsic derivative can be viewed as a map

$$D(df)_x : T_x X \otimes K_x \rightarrow L_x$$

Now we assume to use $x_{s+1}, \dots, x_n$ as linear coordinates in K_x and $y_{s+1}, \dots, y_m$ in L_x . Then $D(df)_x$ in coordinates is defined just by the last two terms of the expression for f_α .

$$D(df)_x : T_x X \otimes K_x \rightarrow L_x$$

$$(v, w) \mapsto \left(\sum_{l=1}^n \sum_{\beta=s+1}^n \frac{\partial^2 f_\alpha}{\partial x_\beta \partial x_l}(x) v_l w_\beta \right)$$

with

$$\frac{\partial^2 f_\alpha}{\partial x_\beta \partial x_l}(x) = b_\alpha^{h\beta}, \quad h = 1, \dots, s \quad \beta = s+1, \dots, n \quad \alpha = s+1, \dots, m$$

$$\frac{\partial^2 f_\alpha}{\partial x_\beta \partial x_l}(x) = c_\alpha^{h\beta} + c_\alpha^{\beta h}, \quad h = 1, \dots, s \quad \beta = s+1, \dots, n \quad \alpha = s+1, \dots, m$$

Hence it's clear that the intrinsic derivative $D(df)_x$ is determined by the 2-jet $j^2 f(x)$. Moreover if we restrict $D(df)_x$ to $K_x \otimes K_x$ we have a symmetric map, then it induces a mapping

$$\delta^2 f_x : K_x \circ K_x \rightarrow L_x$$

(where $K_x \circ K_x$ denotes the symmetric product).

Now let f be a real valued function and let x be a critical point of f . Then $K_x = T_x X$ and $L_x = \mathbb{R}$. The mapping

$$\delta^2 f_x : T_x X \circ T_x X \rightarrow \mathbb{R}$$

is called the Hessian of f at x .

3.3. Morse Theory. In this section we want to determine the structure of generic mappings of X into $\mathbb{R}$.

Since the dimension of $\mathbb{R}$ is 1, the only non-empty submanifolds of $J^1(X, \mathbb{R})$ of type S_r are S_0 and S_1 . Thus p is a singularity (or a critical point) for $f : X \rightarrow \mathbb{R}$ if and only if $j^1 f(p) \in S_1$.

Definition 6. Let $f : X \rightarrow \mathbb{R}$ be a smooth mapping. We give the following definitions

- A point $p \in S_1(f)$ is said to be *nondegenerate* if $j^1 f \nrightarrow S_1$ at p .
- f is a *Morse function* if all of its singularities are *nondegenerate*.

Just applying the Thom Transversality Theorem we have the following result.

Theorem 7. Let X be a smooth manifold. Then the set of Morse functions is an open dense subset of $C^\infty(X, \mathbb{R})$.

Proposition 6. Let $f : X \rightarrow \mathbb{R}$ be a smooth function. Then nondegenerate critical points of f are isolated.

Proof. Let $p \in X$ be a nondegenerate critical point for f . Applying Lemma 1 we can say that there exist a neighborhood V of x s.t. $(j^1 f)^{-1}(S_1) \cap V$ is a submanifold of X of codimension equal to $\text{codim} S_1 = \dim X$.

Then $(j^1 f)^{-1}(S_1) \cap V$ consists only of isolated points and hence there exist a neighborhood $W \subset V$ of p s.t. $(j^1 f)^{-1}(S_1) \cap W = \{x\}$. $\square$

Proposition 7. Let $f : X \rightarrow \mathbb{R}$ be smooth with a critical point at p . Then the symmetric bilinear form

$$\delta^2 f_p : T_p X \circ T_p X \rightarrow \mathbb{R}$$

is nondegenerate iff p is a nondegenerate critical point of f .

Definition 7. Let p be a nondegenerate critical point of $f : X \rightarrow \mathbb{R}$. Then the *index* of f at p is the index of $\delta^2 f_p$.[†]

Theorem 8 (Morse). Let $g : \mathbb{R}^n \rightarrow \mathbb{R}$ be given by

$$g(x_1, \dots, x_n) = c - (x_1^2 + \dots + x_k^2) + x_{k+1}^2 + \dots + x_n^2$$

where c is a constant. Then

- (1) g has a nondegenerate critical point of index k at the origin and has no other singularities.
- (2) Let $f : X \rightarrow \mathbb{R}$ be a smooth with a nondegenerate critical point of index k at $p \in X$. Then there is a neighborhood U of p and a chart

[†]

Proposition 8. Let B a symmetric, nondegenerate, bilinear form on a real vector space V of dimension n . Then there is a basis $v_1, \dots, v_n$ of V and an integer $k \leq n$, called the index of B , such that $B(v_i, v_j) = s_i \delta_{ij}$, where $s_i = -1$ if $i \leq k$ and $s_i = 1$ if $i > k$.

$\phi : U \rightarrow \mathbb{R}^n$ with $\phi(p) = 0$, such that

$$\begin{array}{ccc} U & \xrightarrow{f} & \mathbb{R} \\ \downarrow \phi & \nearrow g & \\ \mathbb{R}^n & & \end{array}$$

commutes, where $c = f(p)$.

Note that in the coordinates $\phi_1, \dots, \phi_n$ defined in the neighborhood U of p , f has the normal form

$$f(x) = f(p) - (\phi_1^2(x) + \dots + \phi_k^2(x)) + \phi_{k+1}^2(x) + \phi_n^2(x)$$

for all $x \in U$.

3.4. The $S_{r,s}$ singularities. Let $f : X \rightarrow Y$ be one-generic. We will denote with $S_{r,s}(f)$ the set of points where the map $f : S_r(f) \rightarrow Y$ drops rank s . We note that $\text{codim} S_r(f) > \dim X - \dim Y$ hence $\dim S_r(f) < \dim Y$. Thus we have that $x \in S_{r,s}(f)$ if and only if $x \in S_r(f)$ and $\ker(df)_x$ intersects the tangent space to $S_r(f)$ in an s dimensional subspace. For example for maps between manifolds of dimension 2 we have to deal just with $S_{1,0}(f)$ and $S_{1,1}(f)$. Our goal for this section is to show that $S_{r,s}(f)$ are *generically* submanifolds and to compute their dimensions. The idea is to construct global submanifold $S_{r,s}$ in $J^2(X, Y)$ such that

$$x \in S_{r,s}(f) \Leftrightarrow j^2 f(x) \in S_{r,s}$$

First of all recall that $J^1(X, Y) \cong \text{Hom}(TX, TY)$ and hence $S_r \cong L^r(TX, TY)$. Given $\sigma \in S_r$ with source at x and target at y we can define the vector subspaces $K_\sigma = \ker \sigma$ and $L_\sigma = \text{coker} \sigma$ in $T_x X$ and $T_y Y$ respectively. Hence we have two vector bundles on S_r which we denote with K and L . As we have seen in section 3.2 the normal bundle to S_r in $J^1(X, Y)$ is canonically isomorphic to $\text{Hom}(K, L)$. Remember that we have a natural projection

$$\pi_{2,1} : J^2(X, Y) \rightarrow J^1(X, Y).$$

Then set $S_r^{(2)} = \pi_{2,1}^{-1}(S_r)$. Since the intrinsic derivative is determined by the 2-jet, we have that the intrinsic derivative gives us a map of fiber bundles:

$$\begin{array}{ccc} S_r^{(2)} & \xrightarrow{(\bullet)} & \text{Hom}(K \circ K, L) \\ \searrow \pi_{2,1} & & \swarrow \\ & S_r & \end{array}$$

Moreover it's clear from the calculations done in Section 3.2 that the top arrow is surjective. Now we recall some standard algebraic facts, let V and W be vector spaces, then:

- (1) $V \otimes V = (V \circ V) \oplus (V \wedge V)$. So there is a canonical projection $\pi : V \otimes V \rightarrow V \circ V$ whose kernel is $V \wedge V$.
- (2) $\text{Hom}(V \otimes V, W) \cong \text{Hom}(V, \text{Hom}(V, W))$.

Consider the map

$$Hom(V \circ V, W) \rightarrow Hom(V \otimes V, W) \rightarrow Hom(V, Hom(V, W))$$

where the first arrow is given by $A \mapsto A \cdot \pi$ and the second arrow by $B \mapsto \phi_B$, $\phi_B(u)(v) = B(u \otimes v)$.

Let $Hom(V \circ V, W)_s$ be the pre-image of $L^s(V, Hom(V, W))$ under this map, then the following proposition holds:

Proposition 9. *$Hom(V \circ V, W)_s$ is a submanifold of $Hom(V \circ V, W)$ of codimension*

$$\frac{l}{2}k(k+1) - \frac{l}{2}(k-s)(k-s+1) - s(k-s) \quad (\star)$$

where $k = \dim V$, $l = \dim W$.

Given two vector bundles $E \rightarrow X$, $F \rightarrow X$ let $Hom(E \circ E, F)_s$ be the fiber bundle whose fiber is $Hom(E_p \circ E_p, F_p)$. By the previous proposition then we have that $Hom(E \circ E, F)_s$ is a fiber sub-bundle of $Hom(E \circ E, F)$. In particular it's a submanifold and his condimension is given by $(\star)$, with k the fiber dimension of E and l the fiber dimension of F .

Let $S_{r,s}$ be the pre-image under the map $(\bullet)$ of $Hom(K \circ K, L)_s$. Since this map is a submersion then $S_{r,s}$ is a submanifold of $S_r^{(2)}$ of the same codimension of $Hom(K \circ K, L)_s$.

Proposition 10. *Let $f : X \rightarrow Y$ be 1-generic. Then*

$$x \in S_{r,s}(f) \Leftrightarrow j^2 f(x) \in S_{r,s}.$$

Proof. Let x be in $S_r(f)$ and $j^1 f(x) = \sigma \in S_r$. Since $S_r \cong L^r(TX, TY)$ then we have seen that

$$N_\sigma = \frac{T_\sigma J^1(X, Y)}{T_\sigma S_r} = Hom(K_\sigma, L_\sigma).$$

Consider the map

$$j^1 f : X \rightarrow J^1(X, Y).$$

Then we know that the differential $d(j^1 f)_x : T_x X \rightarrow T_\sigma J^1(X, Y)$ induces a map

$$D(df)_x : T_x X \rightarrow Hom(K_\sigma, L_\sigma)$$

which is the intrinsic derivative of (df) at x .

Since $j^1 f \bar{\cap} S_r$ then $D(df)_x$ is surjective and $\ker D(df)_x = T_x S_r(f)$. Now suppose $x \in S_{r,s}$. Then $K_\sigma = \ker(df)_x$ intersects $T_x S_r(f) = \ker D(df)_x$ in an s -dimensional space, this implies that

$$D(df)_x : K_\sigma \rightarrow Hom(K_\sigma, L_\sigma)$$

has a kernel of dimension s . Hence $D(df)_x \in Hom(K_\sigma \circ K_\sigma, L_\sigma)_s$ and $j^2 f(x) \in S_{r,s}$.

The converse is equally easy to see. $\square$

Corollary 1. *Let $f : X \rightarrow Y$ be smooth. If $j^2 f \bar{\cap} S_{r,s}$ then $S_{r,s}(f)$ is a submanifold of $S_r(f)$ whose codimension is given by $(\star)$ where $l = \dim Y - \dim X + k$ and $k = r + \max(\dim X - \dim Y, 0)$.*

Thus $S_{r,s}(f)$ is a submanifold of X and $\text{codim} S_{r,s} = r^2 + er + (\text{codim } S_{r,s}(f) \text{ in } S_r(f))$, where $e = |\dim X - \dim Y|$.

The Transversality Theorem says that the condition $j^2 f \bar{\cap} S_{r,s}$ is satisfied by a residual set of smooth mappings. A mapping for which this condition is satisfied for all r, s is called 2-generic.

3.5. The Whitney Theorem for Generic Mappings between 2-Manifolds.

Let X and Y be 2-dimensional manifolds and let $f : X \rightarrow Y$ be 1-generic mapping. Then $S_1(f)$ has codimension 1 in X and $S_2(f)$ doesn't occur since it would have to be of codimension 4. Let $p \in S_1(f)$, $q = f(p)$. One of the following two situations can occur

$$(1) T_p S_1(f) \oplus \ker(df)_p = T_p X,$$

$$(2) T_p S_1(f) = \ker(df)_p.$$

Definition 8. Let $f : X \rightarrow Y$ s.t. $j^1 f \bar{\cap} S_1$. Then $x \in S_1(f)$ is a *fold point* if $T_x S_1(f) \oplus \ker(df)_x = T_x X$. Otherwise if $T_x S_1(f) = \ker(df)_x$ then x is said to be a *cuspid point*.

The first theorem of Whitney for maps between 2-manifolds gives the normal form for fold points.

Theorem 9. *If p is a fold point then one can choose a system of coordinates (x_1, x_2) centered at p and (y_1, y_2) centered at $f(p)$ such that f is the mapping*

$$(x_1, x_2) \mapsto (x_1, x_2^2)$$

Now we will suppose p to be a cuspid point, this situation is more complicated. Let us choose a smooth nonvanishing vector field ξ along $S_1(f)$ such that at each point of $S_1(f)$ ξ is in the kernel of (df) . By assumption $\xi(p) \in T_p S_1(f)$. Now let k be a smooth function on X such that $k = 0$ on $S_1(f)$ and $(dk)_p \neq 0$. Consider $(dk)(\xi) : S_1(f) \rightarrow TX$. Then by assumption $(dk)_p(\xi(p)) = 0$ and one can check that the order of this zero does not depend on the choice of ξ and k .

Definition 9. p is *simple cuspid point* if this zero is a simple zero.

The second main theorem of Whitney states

Theorem 10. *If p is a simple cuspid then one can find coordinates (x_1, x_2) centered at p and (y_1, y_2) centered at $f(p)$ s.t. f has the form*

$$(x_1, x_2) \mapsto (x_1, x_1 x_2 + x_2^3).$$

Now let $f : X \rightarrow Y$ be a 2-generic map.

Then the points in $S_{1,0}(f)$ are folds and those in $S_{1,1}(f)$ are cusps. Moreover from the previous section we have that $\dim S_{1,1} = 0$ (note that this implies also that cuspid points are isolated).

Let x be a cuspid point and suppose that x is not a simple cuspid. Then it can be proved that there exists coordinates (x_1, x_2) centered at x , (y_1, y_2) centered at $f(x)$ and a map

$$\phi : (x_1, x_2) \mapsto (x_1, x_1 \alpha(x_1, x_2))$$

with the same 3-jet at 0 as f . Then for this map $S_{1,1}(\phi)$ is the whole x_2 axis and since ϕ has the same 3-jet as f at 0 then we can conclude

that $j^2\phi \pitchfork S_{1,1}$ at 0. This implies that locally $S_{1,1}(\phi)$ is a submanifold and $\dim S_{1,1}(\phi) = 0$ which is absurd since it is the x_2 axis. Thus if f is 2-generic the all cusps are simple. We have proved the following

Theorem 11. *Let X and Y be 2-manifolds. Then there is a residual set in $C^\infty(X, Y)$ s.t. if f belongs to this set, its only singularities are folds and simple cusps.*

3.6. The Thom-Boardman stratification. Now it is clear how to define high order version of singularities. If $f : X \rightarrow Y$ is 2-generic, $S_{i,j,k}(f)$ is the set of points of $S_{i,j}$ where the map

$$f : S_{i,j}(f) \rightarrow Y$$

drops rank by k . If, by chance, $S_{i,j,k}$ turns out to be a manifold, we can define $S_{i,j,k,l}$ similarly. Thom conjectured that for a residual set of mappings this process could be continued indefinitely. This conjecture was proved by Boardman.

Theorem 12. *For every sequence of integers $r_1, \dots, r_k$ such that $r_1 + \max(0, \dim X - \dim Y) \geq r_2 \geq \dots \geq r_k \geq 0$, one can define a fiber subbundle, $S_{r_1, \dots, r_k}$ of $J^k(X, Y)$ such that if $j^1 f$ is transversal to all manifolds $S_{t_1, \dots, t_l}$, $l < k$, then $S_{r_1, \dots, r_k}(f)$ is well defined and*

$$x \in S_{r_1, \dots, r_k}(f) \Leftrightarrow j^k f(x) \in S_{r_1, \dots, r_k}.$$

Definition 10. We will call a mapping $f : X \rightarrow Y$ s.t. $j^k f$ is transversal to all the $S_{r_1, \dots, r_k}$'s a *Boardman map*.

By Thom's Transversality Theorem it's clear that Boardman maps are residual in $C^\infty(X, Y)$. If f is a Boardman map then we can partition X into a disjoint union of subsets consisting of the non-singular points $X \setminus \bigcup_{i \neq 0} S_i(f)$ and the Boardman sets $S_{r_1, \dots, r_k}(f)$ with $r_k = 0$. Then the map

$$f : X \setminus \bigcup_{i \neq 0} S_i(f) \rightarrow Y$$

is an immersion or a submersion depending on $\dim X$ and $\dim Y$; and if $r_k = 0$ the map

$$f : S_{r_1, \dots, r_k}(f) \rightarrow Y$$

is an immersion. This partition of X is called *Thom-Boardman stratification* and has the property that f , restricted to each stratum, is a particularly simple kind of map (either an immersion or a submersion).

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