Filtering Lab: Noise Reduction and Outlier Rejection

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Contents map

developed content units	taxonomy levels
Filter design and performance evaluation	u1, e1
Practical trade-offs (noise vs. outliers)	u2, e2
Python implementation of filters	u3, e3
prerequisite content units	taxonomy levels
Sinusoidal fidality ITI systems	u1 o1

Basic Python/NumPy/Matplotlib	u2, e2

Main ILO of sub-module

"Filtering Lab: Noise Reduction and Outlier Rejection"

Choose the right filter for a given signal (noise vs. outliers)

Quantify filter performance (e.g., frequency distortion, outlier rejection)

Understand practical implications of impulse/frequency responses

Todays Plan

- Task 1: Tweak Butterworth parameters (order, cutoff) and observe effects
- Task 2: Compare frequency content (original vs. filtered)
- Task 3: Visualize impulse/frequency responses of LTI filters
- Task 4: Smooth signals using moving average, median, or Savitzky-Golay

Signals Youll Work With

Real-world:

- EMG (biceps movement)
- Heavily quantized time series

Synthetic:

- Sine/square waves + noise
- Same + outliers (spikes)

Goal: Match the filter to the problem!



FilteringLab.ipynb

Summarizing

Choose the right filter for a given signal (noise vs. outliers)

Quantify filter performance (e.g., frequency distortion, outlier rejection)

Understand practical implications of impulse/frequency responses

Main intuitions:

- Butterworth: Smooth noise, but distorts edges
- Median: Crush outliers, preserve sharp transitions
- Savitzky-Golay: Smooth while preserving peaks

Most important python code for this sub-module

Key Python Functions

Butterworth Filter

from scipy.signal import butter, filtfilt
b, a = butter(N, cutoff, btype='low')
filtered_signal = filtfilt(b, a, signal)

Savitzky-Golay
from scipy.signal import savgol_filter
filtered_signal = savgol_filter(signal, window_length, polyorder)

Self-assessment material

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Question 1

Which filter is least suitable for removing sparse, large-amplitude outliers?

Potential answers:

- I: Median filter
- II: Butterworth filter
- III: Moving average
- IV: Savitzky-Golay filter

Recap of sub-module

"Filtering Lab: Noise Reduction and Outlier Rejection"

- Filter choice depends on signal features (noise band, outliers, quantization).
- Always check frequency/impulse responses for unintended effects.
- Non-linear filters (median) handle outliers; linear filters (Butterworth) handle noise.

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