# Systems Laboratory, Spring 2025

Damiano Varagnolo – CC-BY-4.0

## building and interpreting phase portraits

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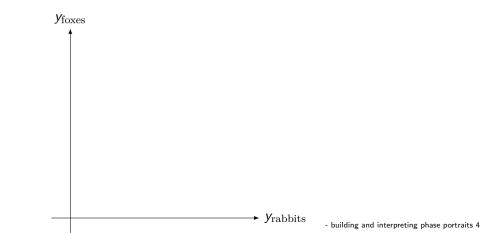
developed content units	taxonomy levels
phase portrait	u1, e1
prerequisite content units	taxonomy levels
ODE	u1. e1

## Main ILO of sub-module "building and interpreting phase portraits"

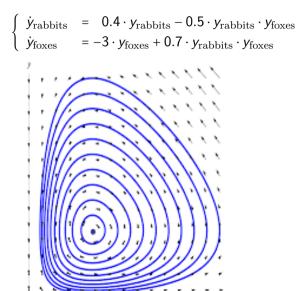
**Construct** and interpret phase portraits of first- and secondorder autonomous ODEs using qualitative analysis techniques

## Starting with an example: a Lotka-Volterra model (*≠* real world):

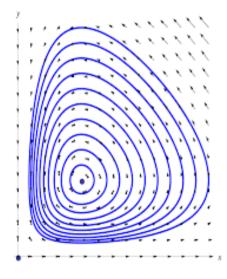
$$\begin{cases} \dot{y}_{\text{rabbits}} &= 0.4 \cdot y_{\text{rabbits}} - 0.5 \cdot y_{\text{rabbits}} \cdot y_{\text{foxes}} \\ \dot{y}_{\text{foxes}} &= -3 \cdot y_{\text{foxes}} + 0.7 \cdot y_{\text{rabbits}} \cdot y_{\text{foxes}} \end{cases}$$



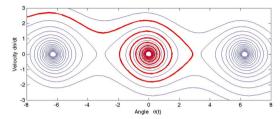
## The result, if we were plotting everything



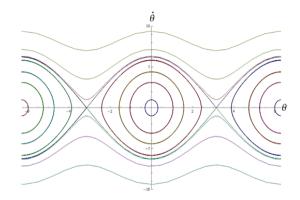
Phase Portrait = a graphical representation of the trajectories of a dynamical system in the state space



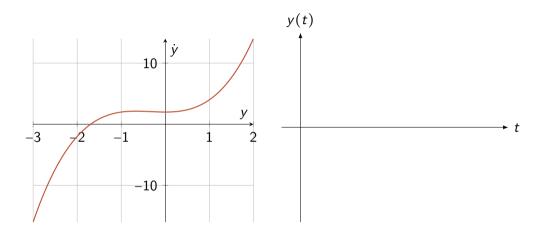
#### Which system is this one?



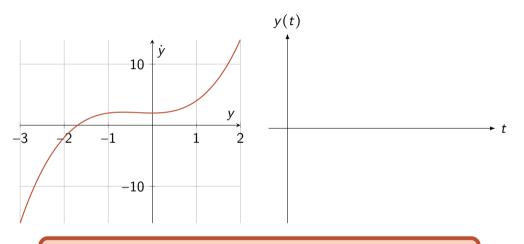
## And this one?



#### Phase Portraits for first-order ODEs

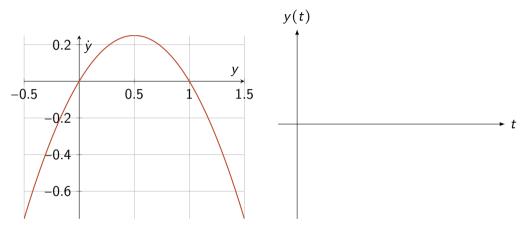


#### Phase Portraits for first-order ODEs

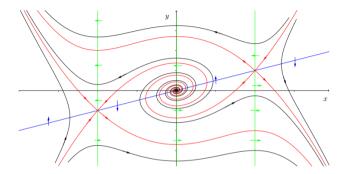


drawing the phase portrait as a 2-D thing in this case is a big error

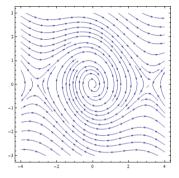
Another example:  $\dot{y} = y(1-y)$ 



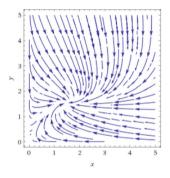
- equilibria: y = 0 and y = 1
- if y < 0 or y > 1,  $\dot{y}$  is negative (flow left)
- if 0 < y < 1,  $\dot{y}$  is positive (flow right)



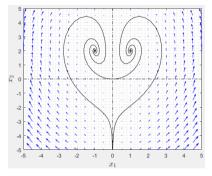
- equilibria: where trajectories do not move
- limit cycles: closed trajectories indicating periodic behavior



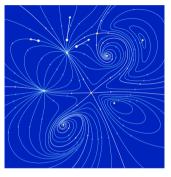
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#### Most important python code for this sub-module

### Tutorial on how to plot phase portraits

https://aleksandarhaber.com/

phase-portraits-of-state-space-models-and-differential-equations-in-pythometry and a state-space-models-and-differential-equations-in-pythometry and a state-space-models-and-differential-equations

## Self-assessment material

What is the primary purpose of a phase portrait?

- I: To find the exact numerical solution of a system
- II: To visualize the qualitative behavior of a dynamical system
- III: To approximate the integral of a function
- IV: To determine the frequency response of a system
- V: I do not know

How do you determine equilibrium points in a phase portrait of a first-order system  $\dot{y} = f(y)$ ?

- I: By solving  $\dot{y} = 0$  for all values of t
- II: By solving f(y) = 0 for y
- III: By integrating f(y) over time
- IV: By setting f(y) to a constant value
- V: I do not know

Which of the following best describes the phase portrait of the system  $\dot{y} = y(1-y)$ ?

- I: It consists of a single trajectory with no equilibrium points
- II: It has two equilibrium points at y = 0 and y = 1, with flow directions determined by the sign of f(y)
- III: It has infinitely many equilibrium points
- IV: It has no equilibrium points and exhibits oscillatory behavior
- V: I do not know

What distinguishes the phase portrait of a second-order system from a first-order system?

- I: Second-order phase portraits only have one equilibrium point
- II: Second-order phase portraits require a two-dimensional state space (e.g., x vs.  $\dot{x}$ )
- III: First-order systems can have limit cycles, while second-order systems cannot
- IV: Phase portraits for second-order systems do not contain information about stability
- V: I do not know

Which of the following statements about phase portraits of nonlinear systems is correct?

- I: Nonlinear systems always have a single equilibrium point
- II: Nonlinear phase portraits can be analyzed only by solving the system numerically
- III: Nonlinear phase portraits may exhibit equilibrium points, limit cycles, and chaotic behavior
- IV: Nonlinear phase portraits always resemble those of linear systems for small perturbations
- V: I do not know

## Recap of sub-module "building and interpreting phase portraits"

- A phase portrait is a graphical representation of a dynamical systems trajectories in state space.
- Phase portraits provide qualitative insight into system behavior without requiring explicit solutions.
- First-order systems have a one-dimensional state space, while second-order systems require two dimensions, etc.

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