

Space of trajectories

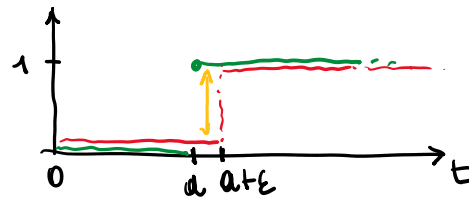
We have seen that t-MC's are defined so to have globally right-continuous trajectories $[X(\omega) = \mathbb{R}_t^+ \rightarrow S \text{ is right-cont. } \forall \omega \in \Omega]$

The possible presence of jumps does not allow to compare two trajectories by the uniform norm, which is the most common norm for continuous trajectories.

Example: let $x(t) := 1 - \mathbb{1}_{[0, a)}(t)$, $y(t) = 1 - \mathbb{1}_{[0, a+\varepsilon)}(t)$, $t \geq 0$

for $a, \varepsilon > 0$. Then $x, y: \mathbb{R}^+ \rightarrow \mathbb{R}$ are right-cont. trajectories

which are very close to each other if ε is small:



However, the sup-norm $\|x-y\| := \sup_{t \in \mathbb{R}^+} |x(t)-y(t)| = 1$ hence it doesn't allow to express the closeness among x and y .

Space $D[0, T]$ [and $D(\mathbb{R}^+)$] and the Skorokhod topology

For $T \in \mathbb{R}^+$, let

$$D[0, T] := \{x: [0, T] \rightarrow \mathbb{R}, \text{right-continuous, with left limit}\}$$

càdlàg trajectories

where càdlàg is the French acronym of "right-cont, left-limit".

FACT: a càdlàg trajectory has at most countably many jumps.

PLAN:

1. We first define a metric (with related topology) on $D[0, T]$.
2. Int. then, move to define a metric on $D(\mathbb{R}^+)$

1. We first define a metric (with relaxed topology) on $\mathcal{D}[0, T]$.
2. We then move to define a metric on $D(\mathbb{R}^+)$.
3. We comment on the easy generalization to trajectories on a metric space (S, ρ) , with

$$D([0, T], S) = \{x: [0, T] \rightarrow S, x \text{ càdlàg}\}, \text{ for } T \in \mathbb{R}^+$$

(and similarly $D(\mathbb{R}^+, S)$). Example: $S = \mathbb{R}^d, \mathbb{N}_0, \{0, 1\}^{\mathbb{T}_+}$

1.

Def [metric on $D[0, T]$]

Let $\Lambda = \{\lambda: [0, T] \rightarrow [0, T]: \lambda \text{ strictly increasing, continuous, } \lambda(0)=0, \lambda(T)=T\}$

For $x, y \in D[0, T]$, we define

$$d_T(x, y) := \inf_{\lambda \in \Lambda} \{ \|\lambda - \text{Id}\| \vee \|x - y \circ \lambda\| \}$$

where $\|x\| := \sup_{t \in [0, T]} |x(t)|, \forall T \in \mathbb{R}^+, \text{Id} \equiv \text{Identity on } [0, T]$.

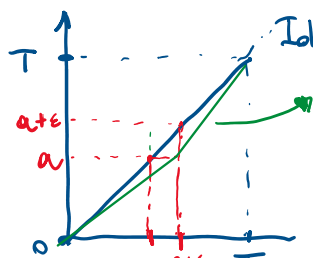
Comment (idea beyond the metric):

Λ is the set of possible transformations (cont. and \uparrow) of the time interval $[0, T]$. If in Λ there is λ close to the Id ($\|\lambda - \text{Id}\| < \varepsilon$) which allows to match the jumps among trajectories x and y ($\|x - y \circ \lambda\| < \varepsilon'$) $\Rightarrow d_T(x, y) < \varepsilon \vee \varepsilon'$.

In the starting example, $x(t) = \mathbb{1}_{[0, a)}(t), y(t) = \mathbb{1}_{[0, a+\varepsilon)}(t)$

with $t \in [0, T]$, have

matching jump for $\lambda: \rightarrow$

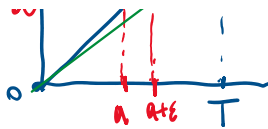


graph of $\lambda \in \Lambda$ s.t.

$$\|x - y \circ \lambda\| = 0$$

$$\|\lambda - \text{Id}\| < \varepsilon$$

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$$\|x - y\| = 0$$

$$\|x - Id\| < \varepsilon$$

Def: The Skorokhod topology is the topology induced by the metric d on $D[0, T]$, with open set

$$B(x_0, r) = \{x \in D[0, T] : d_T(x, x_0) < r\}, \text{ for } x_0 \in D[0, T], r > 0.$$

Notice that $C[0, T] \subset D[0, T] \subset \mathbb{R}^{[0, T]}$.

Some useful results

1. $D[0, T]$ is complete and separable

2. If $d_T(x^{(n)}, x) \xrightarrow{n \rightarrow \infty} 0$ (or $x^{(n)} \xrightarrow{n \rightarrow \infty} x$ in $(D[0, T], d_T)$)

$$\implies x^{(n)}(t) \xrightarrow{n \rightarrow \infty} x(t) \quad \forall t \text{ cont. point of } x$$

Moreover if x is cont. $\implies \|x^{(n)} - x\| \rightarrow 0$

$$(x^{(n)} \rightarrow x \text{ in } (C[0, T], \|\cdot\|))$$

2.

Def [metric on $D(\mathbb{R}^+)$]

For $x, y \in D(\mathbb{R}^+)$, we define

$$d_{\infty}(x, y) := \sum_{m=1}^{\infty} \frac{1}{2^m} \wedge d_m(\Psi_m x, \Psi_m y)$$

where $\Psi_m : D(\mathbb{R}^+) \rightarrow D[0, m]$ is s.t

← (left continuous in m)

$$\Psi_m x(t) = x(t) \mathbb{1}_{[0, m-1]}(t) + (m-t)x(t) \mathbb{1}_{[m-1, m]}(t)$$

In particular, it holds the following result (without proof)

In particular, it holds the following result (without proof)

Theorem: $d_\infty(x^{(n)}, x) \xrightarrow{n \rightarrow \infty} 0 \iff d_t(x^{(n)}, x) \xrightarrow{n \rightarrow \infty} 0$, $\forall t$ cont. point of x

3.

Let (S, ρ) a metric space and $D([0, T], S) \subset S^{[0, T]}$ space of coding functions $x: [0, T] \rightarrow S$.

To provide a metric on this space it is enough to replace the Euclidean metric $|\cdot|$ on \mathbb{R} with ρ , so that

$$d_T(x, y) = \inf_{\lambda \in \Lambda} \{ \|\lambda - I_0\| \vee \|x - y \circ \lambda\|_\rho \}, \text{ with}$$

$$\|x - y \circ \lambda\|_\rho = \sup_{t \in [0, T]} \rho(x(t), y \circ \lambda(t))$$

All the mentioned properties and results hold in this general context.
