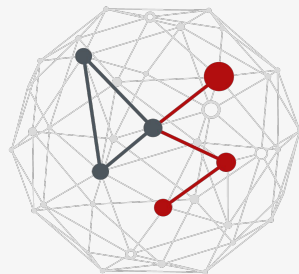


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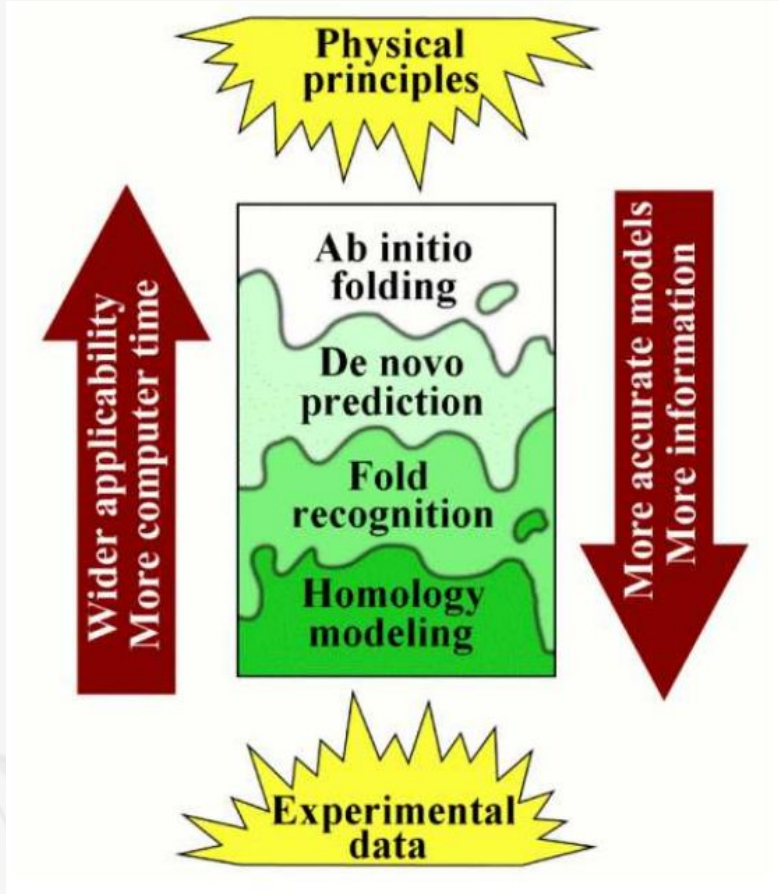
**DATA SCIENCE**  
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# **MOLECULAR DYNAMICS**

Master of Science in Data Science

**Damiano Piovesan**





- **De novo prediction / Ab initio**

- Secondary structure prediction; conformation of short fragments (Rosetta); molecular dynamics; Monte Carlo; quantum mechanics (unfeasible)
- Tough computation

- **Fold recognition**

- Try to fit with known folds
- The fold space is not completely known (50% success)

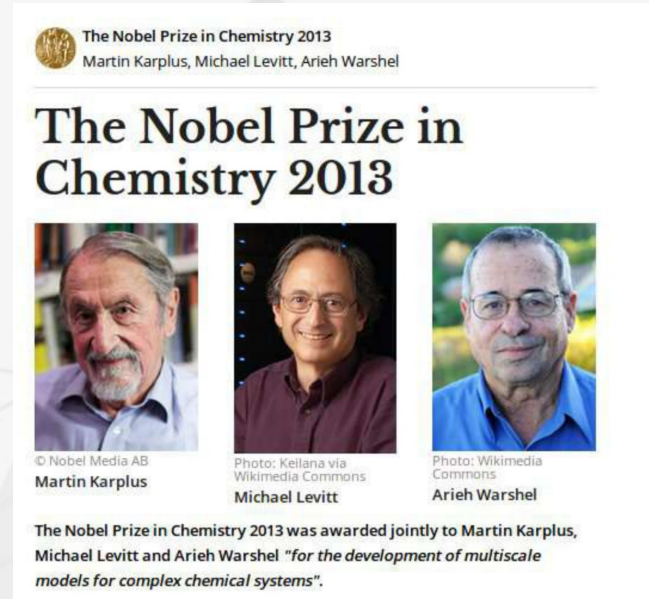
- **Homology modelling**

- Similar sequences have similar structures (+50% sequence identity)
- 40% of genes are not homologous to known structures




# Why study protein dynamics?

- "Flexibility" is a crucial aspect of protein function. An average protein structure alone cannot fully explain protein behavior
- Proteins are constantly exploring different configurations, which play a role in processes such as binding, catalysis, and allosteric regulation
- By analyzing the conformational changes between the active and inactive states of a protein, we can gain a better understanding of its function



The Nobel Prize in Chemistry 2013  
Martin Karplus, Michael Levitt, Arieh Warshel

## The Nobel Prize in Chemistry 2013



© Nobel Media AB  
Martin Karplus




Photo: Keilana via Wikimedia Commons  
Michael Levitt




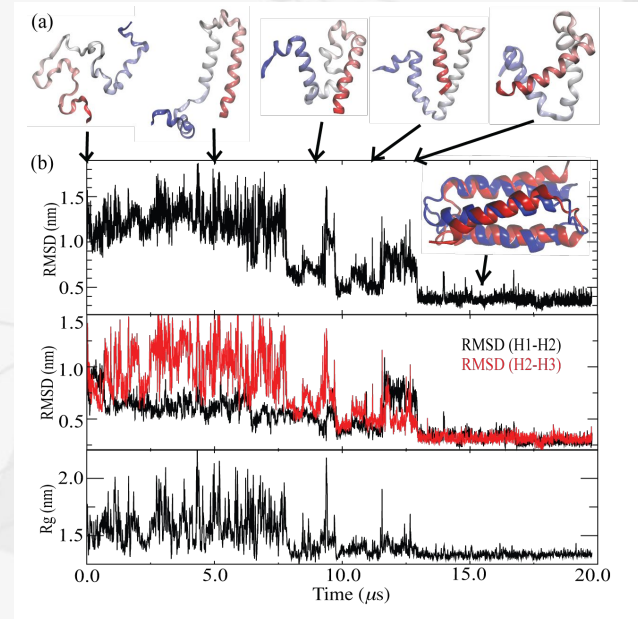
Photo: Wikimedia Commons  
Arieh Warshel

The Nobel Prize in Chemistry 2013 was awarded jointly to Martin Karplus, Michael Levitt and Arieh Warshel "for the development of multiscale models for complex chemical systems".



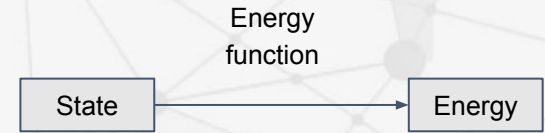
# Fields of application

- Modelling of protein structures
- Conformational sampling and flexibility analysis for thermodynamics (free energy) studies
- Incorporation of solvent effects in NMR and crystallography experiments
- Study of protein-protein interactions and the effects of mutations on protein complexes



# Energy functions

- A mathematical algorithm that inputs the **state of a system** and outputs the **energy**
- **System state** may include
  - Coordinates
  - Bonded structure
  - External elements (surface that repel, binding)
  - Empirical parameters (force fields, how energy works)
  - Charge, spin
- **Energy function** may include
  - Logic (if bonded..., if outside box...)
  - Arithmetic
  - Algebra (polynomial, exponential, log)
  - Calculus (derivatives, integrals)
  - Numerical procedures (advances, custom computer programs)
- **Energy function** can be
  - Simple or complex
  - Analytic or numerical
  - QM (law of physics)
  - MM (approximate) or other (empirical)
  - Ab initio or empirical
  - Atomistic or Coarse-grained



# Molecular Mechanics (MM)

A set of models which use an **empirical** (lot of parameters), **algebraic** (formulas), **atomistic** (individual atoms) energy function for chemical systems

$$E_{\text{total}} = E_{\text{bonded}} + E_{\text{non-bonded}}$$

$$E_{\text{bonded}} = E_{\text{bonds}} + E_{\text{angles}} + E_{\text{torsions}}$$

$$E_{\text{non-bonded}} = E_{\text{elst}} + E_{\text{vdw}}$$

Force field models

- Atoms: 3D point particles
- Structure: bonds, angles, torsions



# Molecular Mechanics (MM)

## Force fields vary in

- Energy function form
- Empirical parameters
- Simulation targets

## Limitations

- Up to 1M of atoms
- Up to  $10^{15}$  configurations
- Accuracy of energy
- Scope of parameters

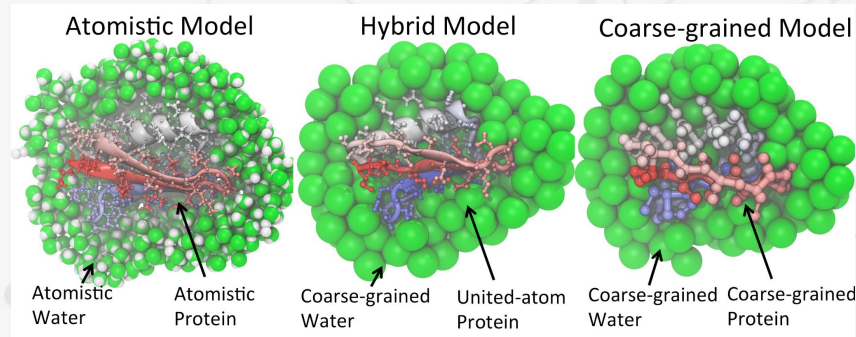
## Examples

- **AMBER**, assisted model building energy refinement (originally for DNA)
- **CHARM**, chemistry at harvard MM (Martin Karplus nobel 2013)
- **OPLS**, optimized potential for liquid simulations (small molecules)
- **GROMOS**, used by Gromacs software
- **MMFT**, Merk Molecular force field (pharmaceutical)



# Types of force fields

- **All-atom** force fields have parameters for every atom species, including mass, charge, and volume
- **United-atom** force fields treat hydrogen and carbon atoms as methyl and methylene groups, respectively, reducing the number of centers of interaction
- **Coarse-grained** force fields simplify the system by representing multiple atoms as spheres, allowing for simulations with longer timescales, often in the microseconds or longer range, while sacrificing some detail. This makes them computationally efficient.



# Force field parameters

An arbitrary constant whose value characterizes an element of a system

$$E_{total} = \sum_{bonds} K_b (r - r_{eq})^2 + \dots$$

## Units

$$E \rightarrow [\text{kcal/mol}] \quad r \rightarrow [\text{\AA}]$$

$$R_{eq} \rightarrow [\text{\AA}] \quad K_b \rightarrow [\text{kcal/mol} \times \text{\AA}^2]$$

## Example

O-H in H<sub>2</sub>O in AMBER95

$$R_{eq} = 0.960 \text{ \AA} \quad k_b = 553.0 \text{ kcal/mol} \times \text{\AA}^2$$

## Sources

- Structures → crystal, electron density
- Spectra (NRM) → IR (vibration freq. of bonds)
- Simulation → PES (potential energy surface, quantum mechanics)

## Desired properties

- General
- Transferable
- Accurate



# Bond stretch terms

$$E_{\text{bonds}} = \sum_{\text{bonds}} K_b (r - r_{\text{eq}})^2$$

## Parameters

$r_{\text{eq}}$  → equilibrium bond length

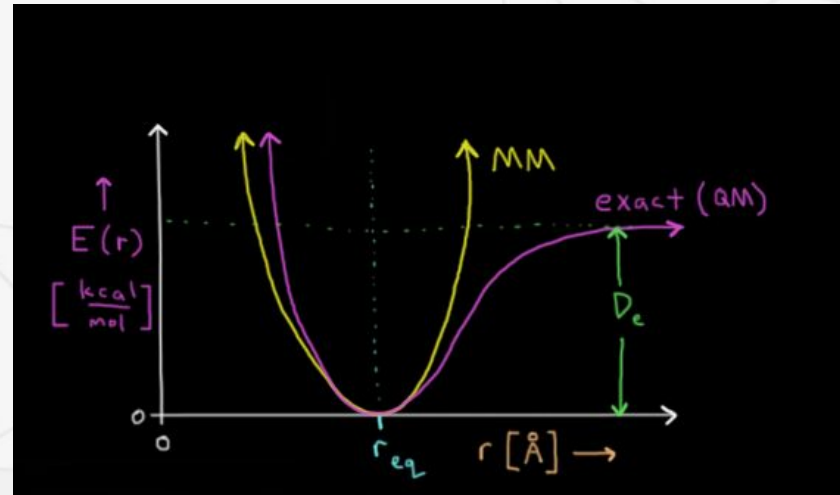
$K_b$  → bond spring constant

## Variables

$r$  → bond length

$D_e$  → dissociation energy

Typical  $K_b \approx 300\text{-}600 \text{ kcal/mol} \times \text{\AA}^2$



# Angle bend terms

$$E_{\text{angles}} = \sum_{\text{angles}} K_a (\theta - \theta_{\text{eq}})^2$$

## Parameters

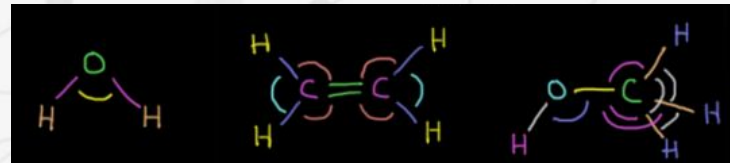
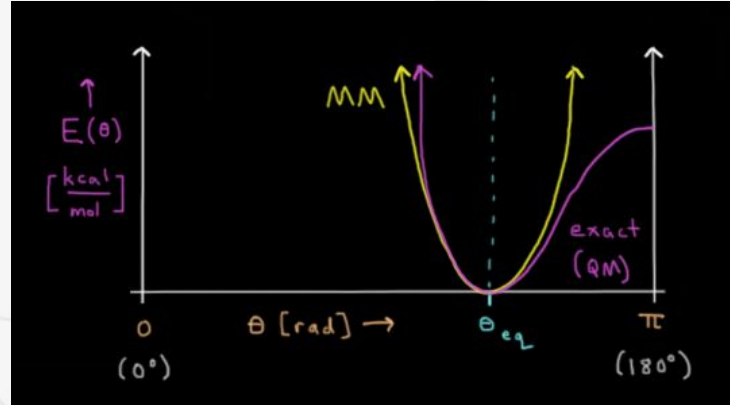
$\theta_{\text{eq}}$  → equilibrium bond angle [rad]

$\theta_a$  → angle spring constant

## Variables

$\theta$  → bond angle [rad],  $0 \leq \theta \leq \pi$

Typical  $K_a \approx 100\text{-}150 \text{ kcal/mol} \times \text{rad}^2$



# Van der Waals (non bonded) terms

$$E_{vdw} = \sum_{i=1}^N \sum_{j=i+1}^N \epsilon_{ij} \left[ \left( \frac{r_0}{r_{ij}} \right)^{12} - 2 \left( \frac{r_0}{r_{ij}} \right)^6 \right]$$

## Parameters

$\epsilon_{ij}$  → interaction strength [kcal/mol]

$r_0$  → van der Waals radius (Å)

## Variables

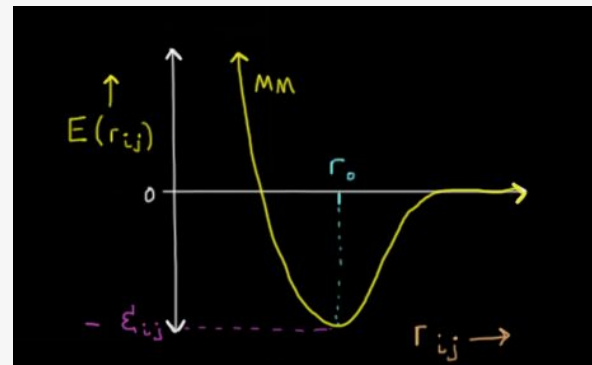
$r_{ij}$  → interatomic distance (Å)

## Short range ( $r_{ij} < r_0$ )

- Exchange / steric repulsion
- “<sup>12</sup>” term dominates

## Long range ( $r_{ij} > r_0$ )

- London dispersion attraction
- “<sup>6</sup>” term decay more slowly



How to define parameters for all possible pairs?

“Combining rules” →  $\epsilon_i, \epsilon_j$  atomic parameters

$$\epsilon_{ij} = \sqrt{\epsilon_i \epsilon_j}$$

“geometric mean”

$$r_0 = \frac{1}{2}(r_i + r_j)$$

“arithmetic mean”



# Electrostatics terms

$$E_{elst} = \sum_{i=1}^N \sum_{j=i+1}^N \frac{q_i q_j}{4\pi\epsilon_0 r_{ij}}$$

## Parameters

$q_i, q_j \rightarrow$  atomic partial charges (e)

$\epsilon_0$  permittivity of free space (constant)

## Variables

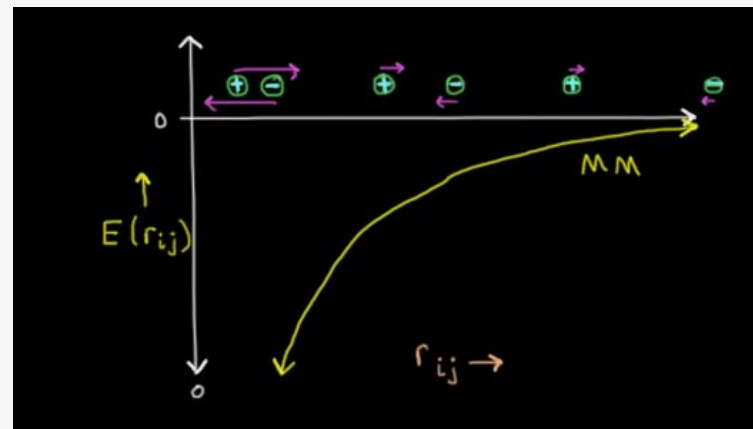
$r_{ij} \rightarrow$  interatomic distance (Å)

Same charge  $\rightarrow$  repulsion

Opposite charge  $\rightarrow$  attraction

Charge of the electron (e),  $1.6 \times 10^{-19}$  coulomb

$Q_{tot}$  usually is zero



$v_{dw} \propto \left(\frac{1}{r}\right)^6 \rightarrow$  quick decay

$e_{lst} \propto \left(\frac{1}{r}\right)^1 \rightarrow$  slow decay

Elst is rate limiting step of MM

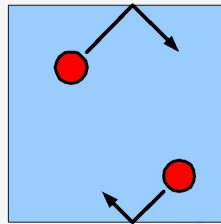
- $O(N)$  bonded terms
- $O(N^2)$  non-bonded terms



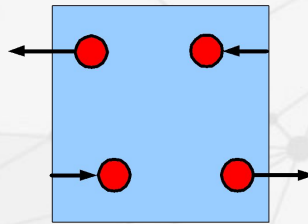
# Boundary conditions

The goal is to simulate an infinite system while using a finite simulation box

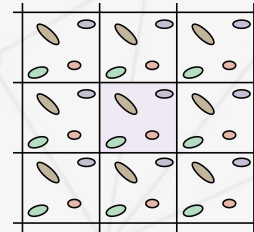
- Particles experience forces as if they were in a bulk fluid
- If a particle exits the simulation box, it is replaced by an image particle that enters from the opposite side. This maintains the continuity of the system and prevents the introduction of artificial boundary effects



Specular boundary condition



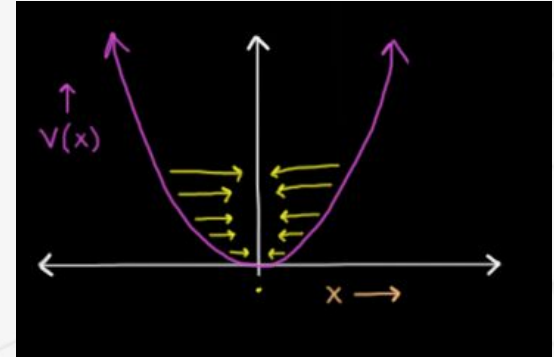
Periodic boundary condition



# Energy gradient

$V(x)$  → potential energy (example:  $\frac{1}{2} kx^2$ )

$F(x) = - \frac{dV(x)}{dx}$  → force (example:  $-kx$ )



**1D**

$V(x)$

→

**3D**

$V(x,y,z)$

**Notation**

$V = V(x_1, y_1, z_1, x_2, y_2, z_2, \dots, x_N, y_N, z_N)$

$= V(\vec{r}_1, \vec{r}_1, \dots, \vec{r}_N)$       $\vec{r}_i = (x_i, y_i, z_i)$

$= V(\vec{r}^{3N})$

N atoms

→

3N coordinates

**Gradient**

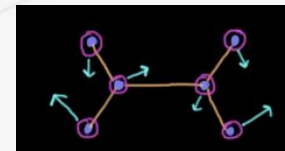
$$- \frac{dV(x)}{dx}$$

$$- \left( \frac{\partial V}{\partial x} \hat{x} + \frac{\partial V}{\partial y} \hat{y} + \frac{\partial V}{\partial z} \hat{z} \right)$$

$$- \nabla V(x,y,z)$$

$V(\vec{r}^{3N})$  → energy

$-\nabla V(\vec{r}^{3N})$  → force



# Energy minimization

$$\frac{dV(x)}{dx} = 0$$

→ “stationary point”

$$\frac{d^2V(x)}{dx^2}$$

$\left\{ \begin{array}{l} > 0 \text{ local minimum} \\ < 0 \text{ local maximum} \\ = 0 \text{ unknown (“saddle” point)} \end{array} \right.$

1D

→

3D

$$\frac{dV(x)}{dx} = 0$$

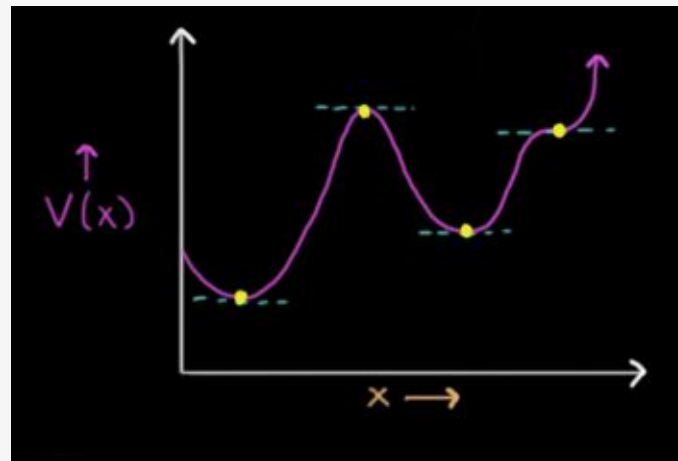
$$|\nabla V(\bar{\mathbf{r}}^{3N})| = 0$$

$$\frac{d^2V(x)}{dx^2} > 0$$

$$\{\lambda_H\} \geq 0, \quad H_{ij} = \frac{\partial^2 V(\bar{\mathbf{r}}^{3N})}{\partial q_i \partial q_j}$$

$H \rightarrow 3N \times 3N$  real, symmetric “Hessian matrix”

Local minima → All eigenvalues are  $\geq 0$



- Lowest  $V(\bar{\mathbf{r}}^{3N})$  among local minima → global minimum
- “Geometry Optimization” → algorithm to find the coordinates  $\{\bar{\mathbf{r}}^{3N}\}$  with the minimum energy

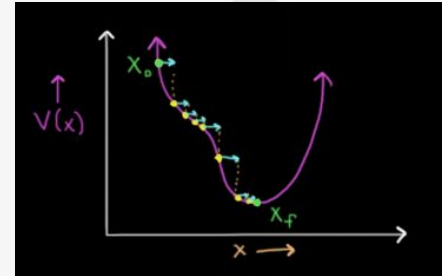


# Steepest descent

Method for obtaining local stationary points of a multi-dimensional function

Simple method for geometry optimization

1. Guess  $X_0$  "initial geometry"
2. Compute  $V(x_i)$  and  $\nabla V(x_i)$ , energy and gradient
3. Update  $x_{i+1} = x_i - \gamma_i \nabla V(x_i)$ , displacement
4. Check for convergence
  - a. If yes: done  $x_f = x_i$
  - b. If no: return to step 2



There are various methods for choosing  $\gamma_n$

Convergence checks

- $\|\nabla V(x_i)\| \approx 0$  gradient
- $|V(x_i) - V(x_{i-1})| \approx 0$  energy
- $\|x_i - x_{i-1}\| \approx 0$  displacement



# Molecular dynamics (MD)

Calculate system properties by propagating through **time** and averaging

- Classical Mechanics → Newton's Laws ( $F = ma$ )
- MM → conservative (total energy is conserved, kinetic + potential energy), time-independent

$$F = ma = m \frac{d^2(x)}{dt^2} = \frac{d}{dt} \left( m \frac{d(x)}{dt} \right) = \frac{d}{dt}(mv) = \frac{dp}{dt}$$

$$F = - \frac{dV(x)}{dx}$$

$$\frac{\partial p_{x_i}}{\partial t} = - \frac{\partial V}{\partial x_i}$$

$$p = mv = m \frac{dx(t)}{dt}$$

f = force  
 m = mass  
 a = acceleration  
 x = position / coordinates  
 p = momentum

Solve for all 3N coordinates

Can't solve exactly → approximate numerically



# Molecular dynamics

1. Assign initial  $x_0, p_0, t = 0$
2. Compute  $V(x_i)$  and  $\nabla V(x_i)$
3. Update  $x_{i+1} = x_i + 1/m p_i \Delta t$
4. Update  $p_{i+1} = p_i - \nabla V(x_i) \Delta t$
5. Repeat (steps 2-4) until  $t \geq t_f$
6. Compute desired properties

$$t = t + \Delta t$$

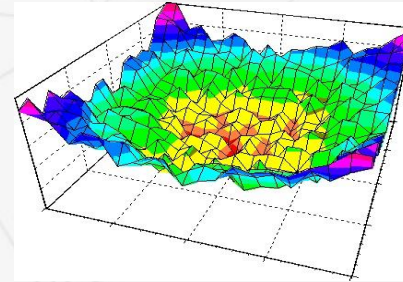
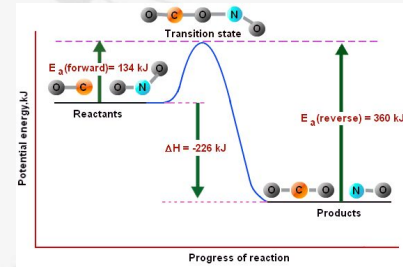
$\Delta t \rightarrow$  timestep ( $1\text{fs} = 10^{-15}\text{s}$ )

$t$  = time  
 $x$  = position / coordinates  
 $p$  = momentum (mv)  
 $m$  = mass  
 $V$  = potential energy  
 $\nabla V$  = energy gradient

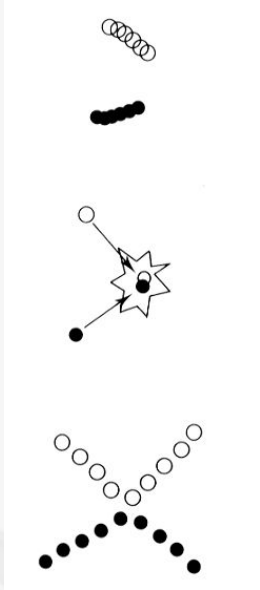


# Minimization Vs Molecular Dynamics

- All molecules can exist with relative atom placements that are energetically unfavorable, i.e. it requires input of energy to put a molecule into a particular conformation
- **Energy minimization** finds the closest minimal energy conformation, but may only identify **local minima** and not the global minimum
- The goal of **molecular dynamics** is not to reduce energy to the closest minimum energy conformation but to more or less **conserve energy** while allowing atoms to move about (while constrained by the forcefield)
- If allowed to proceed long enough, MD can sample different molecular conformations, especially if the amount of starting energy is high (e.g. "high temperature")



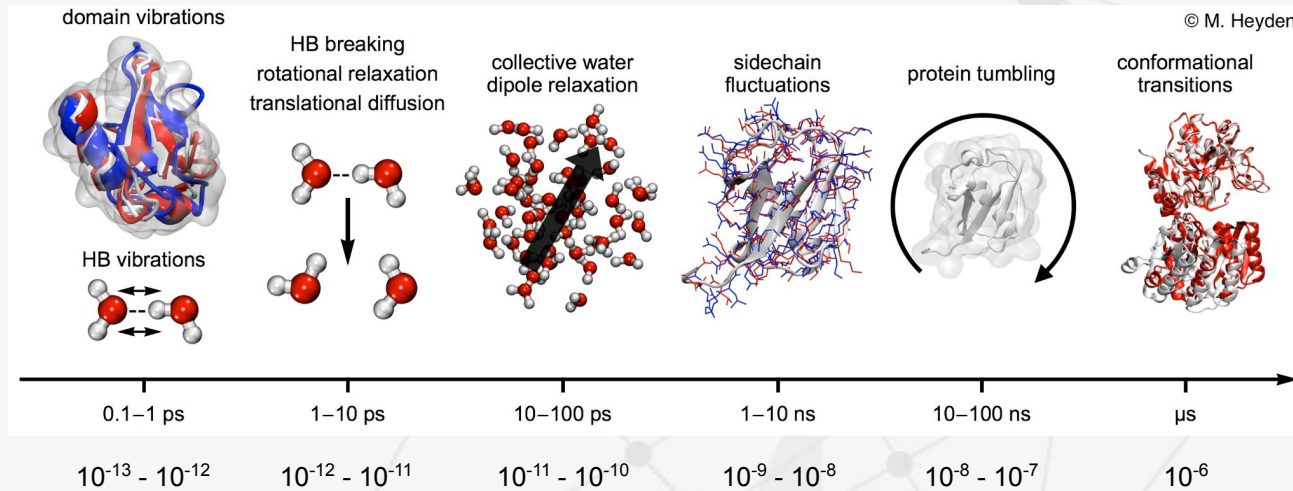
# The right simulation time



1. Too short – no variations are appreciated
2. Too long – errors derived from approximations
3. Fair compromise – acceptable errors, maximum speed



# Time scales



# Time scales

Rotation of buried sidechains	}		s	1
Local denaturations			ms	$10^{-3}$
Allosteric transitions			$\mu$ s	$10^{-6}$
Hinge bending	}		ns	$10^{-9}$
Rotation of surface sidechains			ps	$10^{-12}$
Elastic vibrations	}		fs	$10^{-15}$
Bond stretching				
Molecular dynamics timestep	→			

Final T → depends on goal

- Vibrations → 10 - 1,000 fs
- Conformation changes → ps - ns
- Diffusion / interaction → ns -  $\mu$ s
- Protein folding →  $\mu$ s - s



# Molecular Dynamics & Biology

- What can we simulate?
- What kind of information do we get?
- How can we use them to solve a biological problem?



# References & Links

**TMP Chem** (Trent Parker's YouTube channel)

<https://www.youtube.com/user/TMPChem>

Computational Chemistry

- 2.1, 2.2, 2.3
- 2.5, 2.6
- 2.9, 2.10
- 3.1, 3.2, 3.3
- 3.8

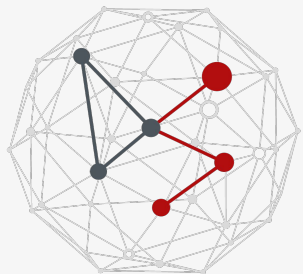


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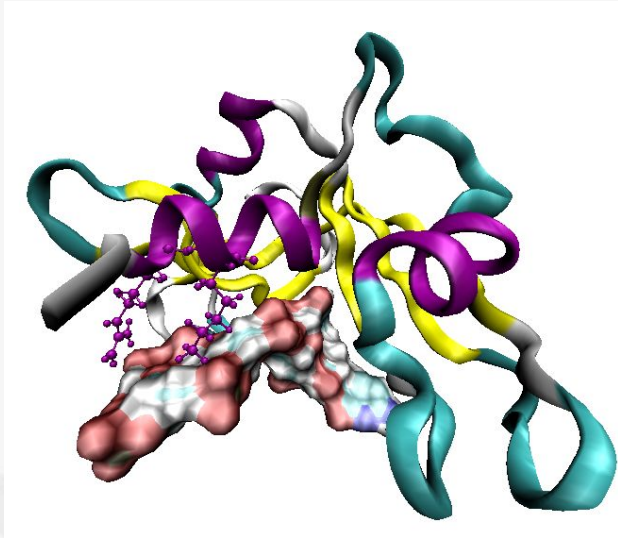
# **Biological Example: Human pancreatic ribonuclease**

Master of Science in Data Science

**Damiano Piovesan**



# Human pancreatic ribonuclease

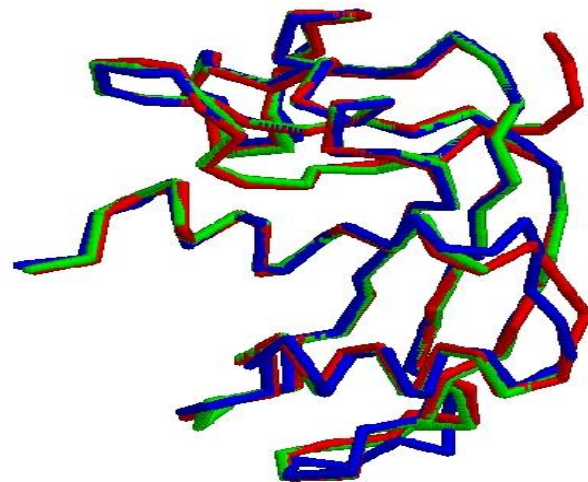


- Comparative study between the human pancreatic enzyme and Ribonuclease A
- MD to validate the reliability of a model

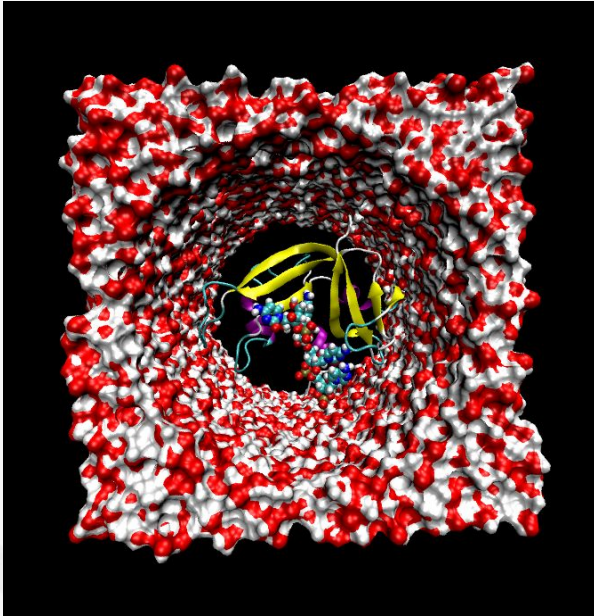


# Simulation setup

- Initial structures
  - RNase A bovine, 1RCN
  - The mutant HP-RNase, 1DZA
- Tested bound with 4 DNA nucleotides (ATAA)
- The structures are all very similar



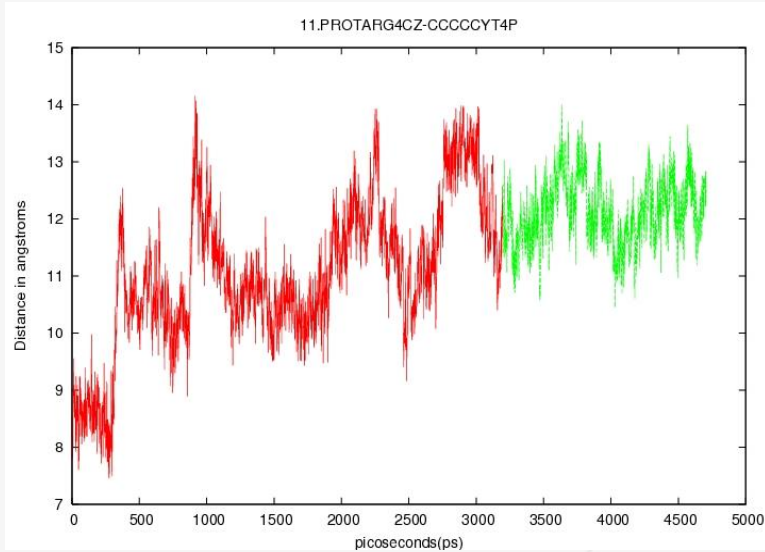
# Simulation parameters



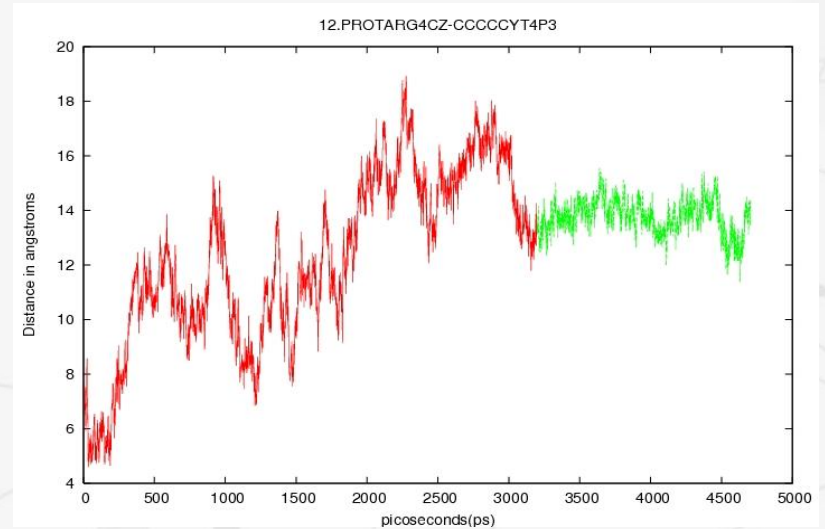
- Waterbox 65 Å (~30,000 atoms)
- Charmm force field, no extra parameters. NAMD/Vmd software
- PBC (periodic boundary conditions) with Particle Mesh Ewald for electrostatics
- 2 fs timestep, shake, NPT (constant-temperature/pressure) ensemble
- Progressive heating and no restriction for almost 1ns
- Simulation ~500ns



# Analysis of a MD simulation



HP-RNase



bovine RNase A

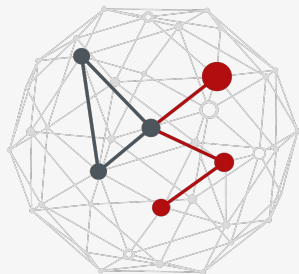


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- GROningen MACHine for Chemical Simulations
- Open source implementations of Gromos integrator
  - [www.gromacs.org](http://www.gromacs.org)

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