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Radio-frequency network analysis

Lecture #15

Electronic measurements

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Scattering parameters

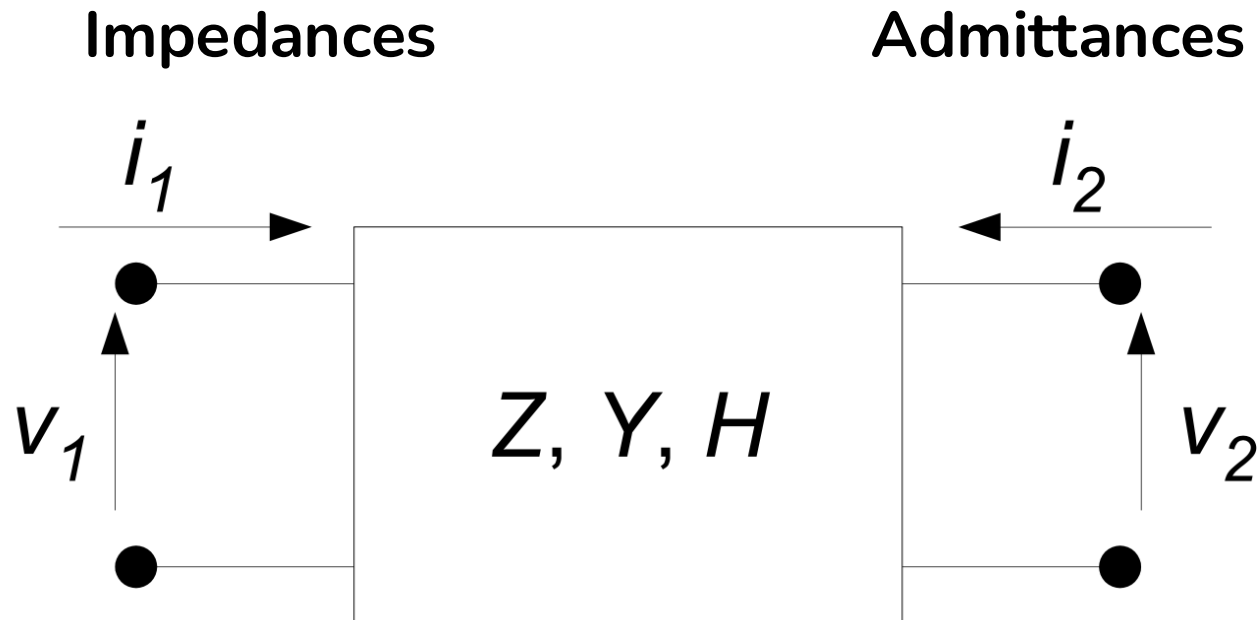
- **Two-port linear devices** → Linear equations expressing the link among voltages and currents

$$v_1 = z_{11}i_1 + z_{12}i_2$$

$$i_1 = y_{11}v_1 + y_{12}v_2$$

$$v_2 = z_{21}i_1 + z_{22}i_2$$

$$i_1 = y_{21}v_1 + y_{22}v_2$$





Scattering parameters

- **Transistors** → Linearized equations → hybrid parameters

$$v_1 = h_{11}i_1 + h_{12}v_2$$

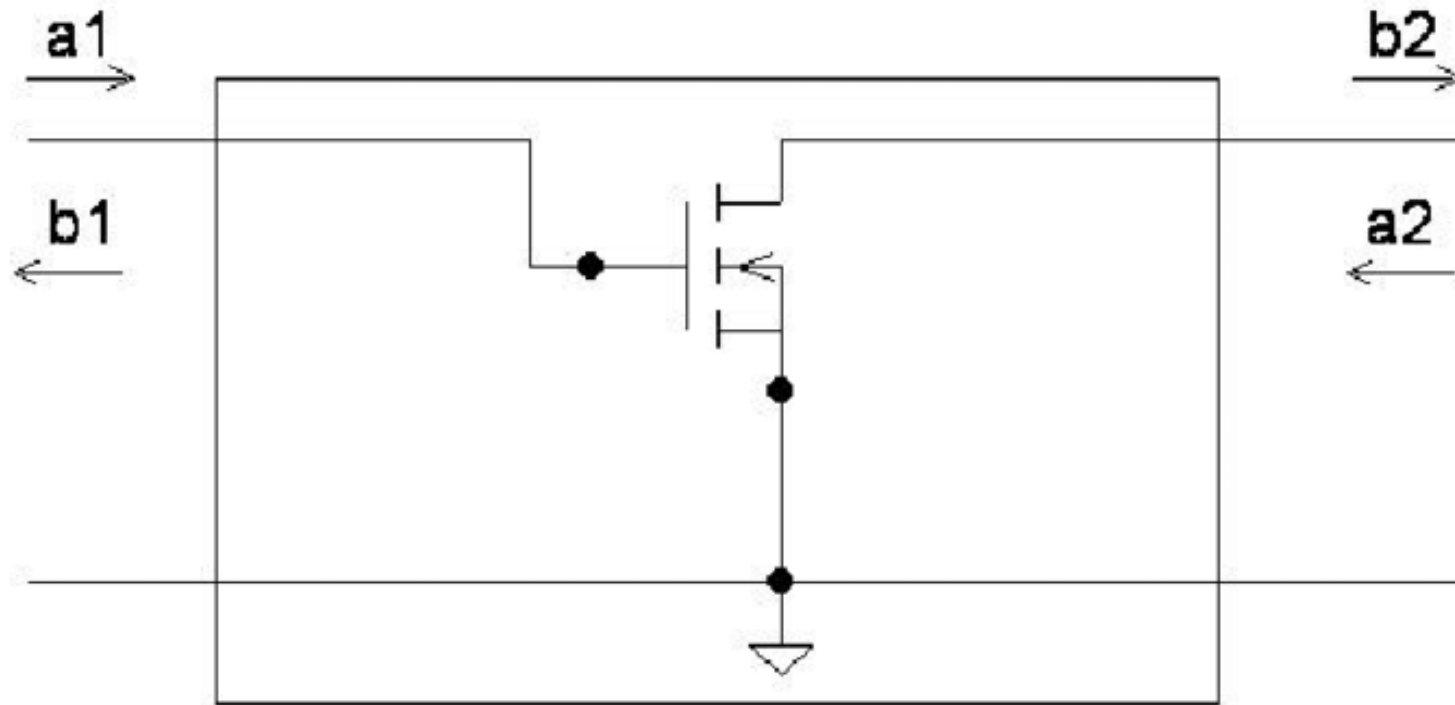
$$i_2 = h_{21}i_1 + h_{22}v_2$$

- h_{11} impedance
- h_{22} admittance
- h_{12} and h_{21} dimensionless parameters
- h_{11} determined measuring voltage v_1 and current i_1 at port 1 when port 2 is short-circuited ($v_2 = 0$)
- h_{22} determined measuring voltage v_2 and current i_2 at port 2 when port 1 is an open circuit ($i_1 = 0$)



Scattering parameters

- Two port model of a transistor

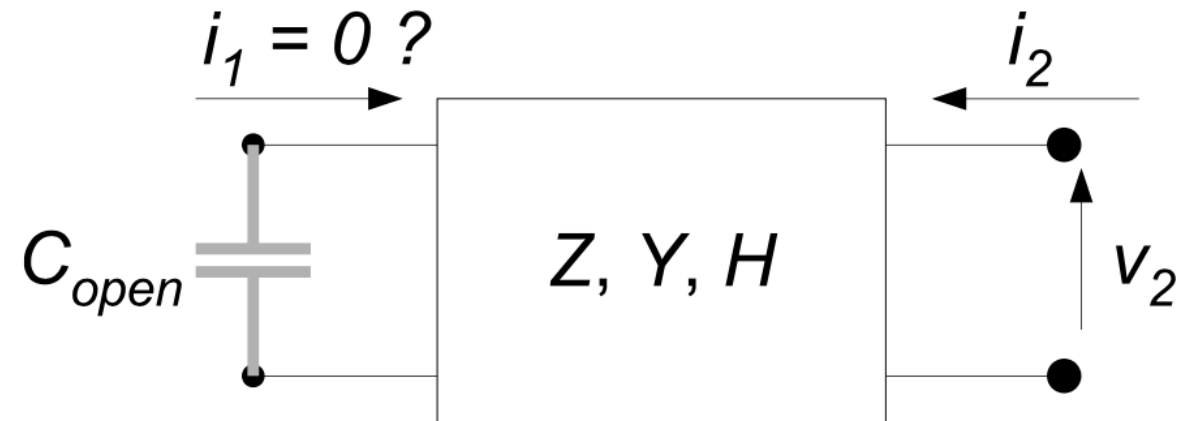
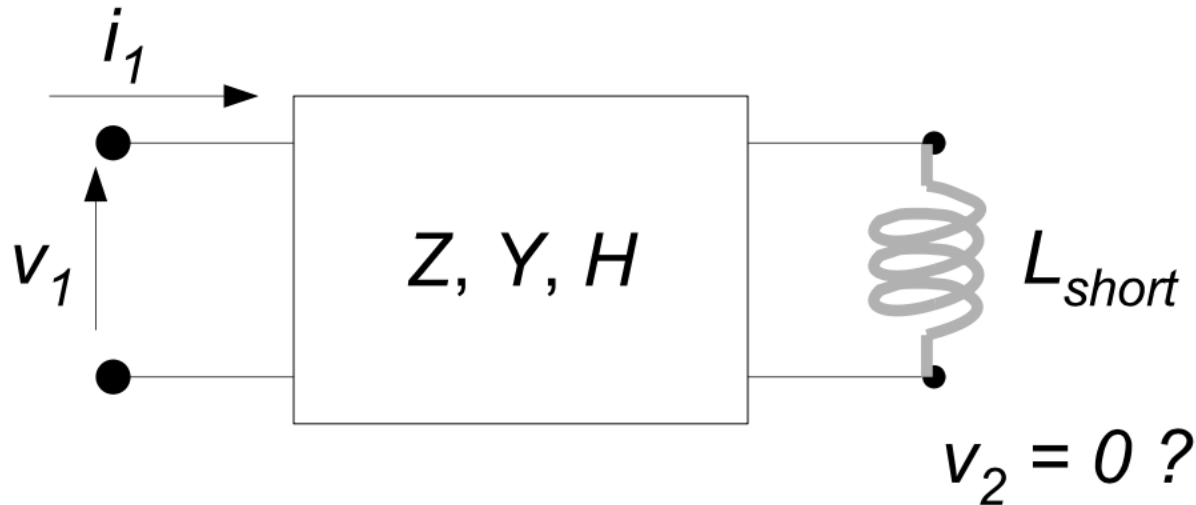




Scattering parameters

- **Real conditions:**

- a small inductance L_{short} is introduced between terminals when port 2 is short-circuited
- a small capacitance C_{open} is found between terminals when port 1 is left open





Scattering parameters

- **High frequencies:**
 - **Adverse effects on accuracy** due to these parameters
 - **Signal reflections** at the terminations
- **High-frequency electronic circuits:** impedance-matched systems → ideally, signals propagate unaltered from one functional block to the next without reflection
- A two-port device might be characterized by just one parameter
 - **Attenuation (passive device)**
 - **Amplification (active device)**
- **Reflections** → Reflection coefficient Γ



Scattering parameters

- Measurements on **high-frequency devices under test** operating in **impedance matching conditions**:
 - Test conditions are less difficult to be set
 - Measurements are referred to test conditions that are closer to the normal operation of the device
- Measurements need to be referred to a different set of parameters:
 - Incident wave V_i
 - Reflected wave V_r
- V complex number \rightarrow **phasor** of a sinusoidal waveform



Scattering parameters

$$v(t) = \sqrt{2} \cdot |V| \cos(2\pi f t + \angle V) = \Re[\sqrt{2} \cdot |V| \cdot e^{j2\pi f t}]$$

- f generic **frequency value**
- $|V|$ sinewave **root mean-square value**
- Z_0 **characteristic impedance**

$$\text{Incident power} \quad \frac{|V_i|^2}{Z_0}$$

$$\text{Reflected power} \quad \frac{|V_r|^2}{Z_0}$$



Scattering parameters

- Normalized values referred to V_i and V_r :

$$a = \frac{V_i}{\sqrt{Z_0}}$$

$$b = \frac{V_r}{\sqrt{Z_0}}$$

- Two port equations:

$$b_1 = s_{11}a_1 + s_{12}a_2$$

$$b_2 = s_{21}a_1 + s_{22}a_2$$



- s_{11} , s_{12} , s_{21} , s_{22} **scattering parameters** (s-parameters)
- $|a|^2$ and $|b|^2$ incident and reflected power



Scattering parameters

$$s_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0} \quad \text{from which } s_{11} = \left. \frac{V_{r1}}{V_{i1}} \right|_{V_{i2}=0} = \Gamma_1$$

Complex **reflection** coefficient

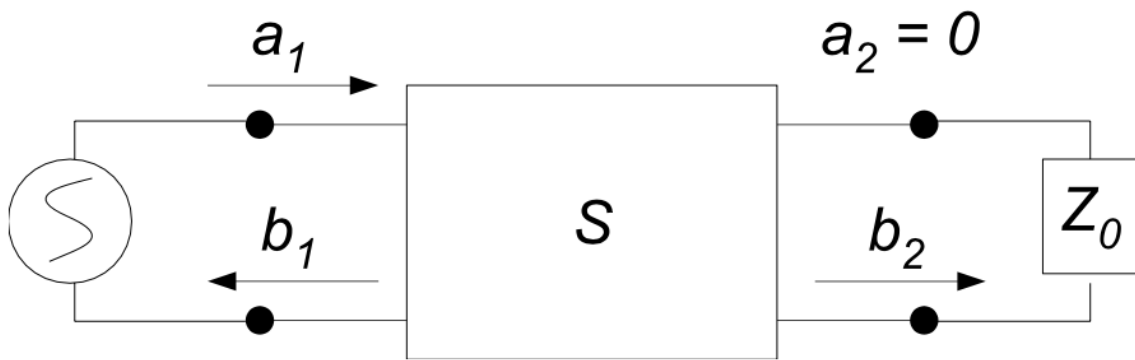
$$s_{21} = \left. \frac{b_2}{a_1} \right|_{a_2=0} \quad \text{from which } s_{21} = \left. \frac{V_{r2}}{V_{i1}} \right|_{V_{i2}=0}$$

Complex **transmission** coefficient

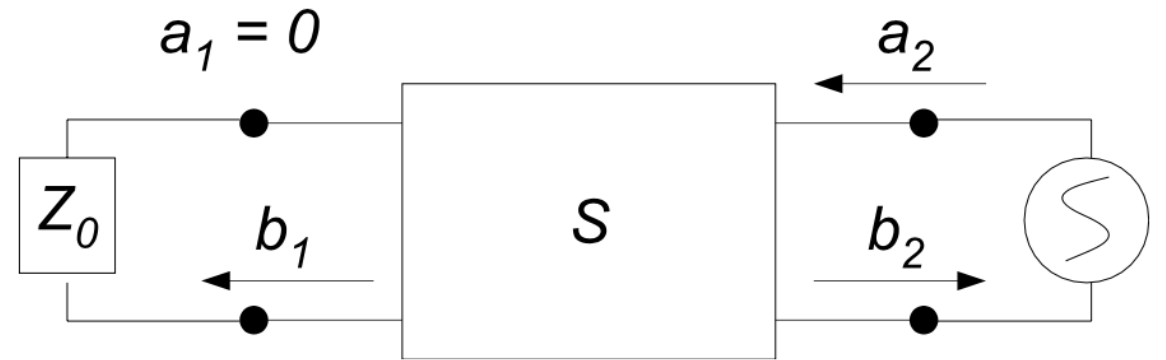


Scattering parameters

- Determination of s_{11} and s_{21} :
 - A **matched generator** providing the incident wave V_{i1} at port 1
 - A **load impedance** Z_0 on the opposite port 2, to ensure that wave b_2 , “outgoing” from port 2, is not reflected back
 - **Two measuring units** for waves V_{r1} and V_{r2} on both ports



(a) measurement configuration, port 1



(b) measurement configuration, port 2



Scattering parameters

- Crucial requirements:
 - Values of s-parameters are **complex numbers** that are determined as ratios of two vectors. This requires the capability to measure both a **magnitude ratio and a phase difference** (between reflected and incident wave)
 - At any point along a transmission line measured voltage is the (vector) superposition of V_i and V_r . The two components can only be separated on the basis of their **propagation direction**
 - Frequencies for s-parameter measurement may range from a **few MHz to several tens of GHz**



Network analyzers



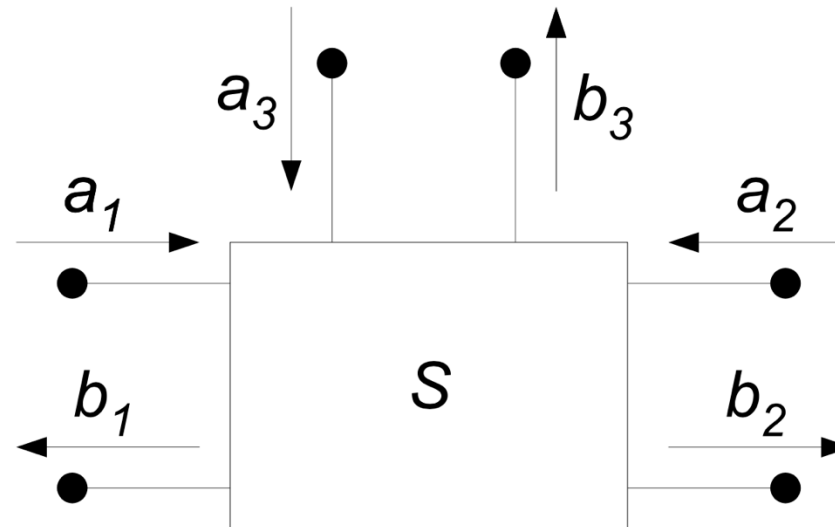
Directional coupler

- Separates the incident and reflected waves
- **Three-port s-parameter model**

$$b_1 = s_{11}a_1 + s_{12}a_2 + s_{13}a_3$$

$$b_2 = s_{21}a_1 + s_{22}a_2 + s_{23}a_3$$

$$b_3 = s_{31}a_1 + s_{32}a_2 + s_{33}a_3$$

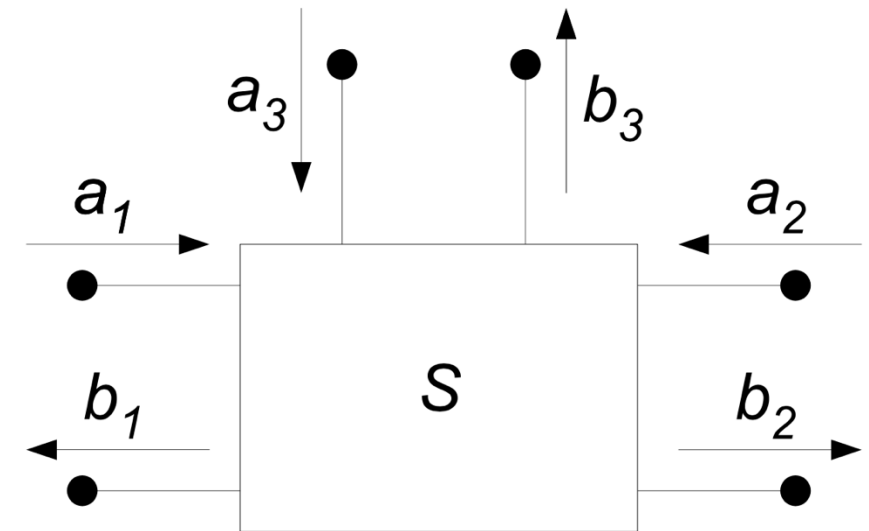


- The directional coupler is placed **between the matched generator** providing the test sinewave and **one port of the device under test**
- **Termination impedance** for port 3 is $Z_0 \rightarrow$ No reflection, $a_3 = 0$



Directional coupler

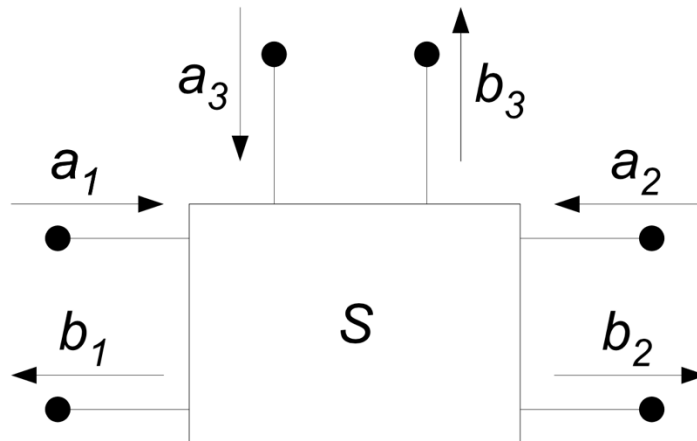
- Parameters of a directional coupler:
 - Coupling factor**, defined by the power ratio: $\frac{|b_3|^2}{|a_2|^2}$ with $a_1 = 0, a_3 = 0 \rightarrow |s_{32}|^2$
 - Reverse coupling factor**, or **isolation**, defined by the power ratio: $\frac{|b_3|^2}{|a_1|^2}$ with $a_2 = 0, a_3 = 0 \rightarrow |s_{31}|^2$
 - Insertion loss**, defined by the power ratio: $\frac{|b_2|^2}{|a_1|^2}$ with $a_2 = 0, a_3 = 0 \rightarrow |s_{21}|^2$





Directional coupler

- **Passive device** $\rightarrow |s_{32}| \leq 1$ for all s-parameters
- All parameters are expressed in dB
- “Minus” sign is usually omitted \rightarrow implied in terms like “loss” or “attenuation”
- **Directivity:** capability to separate the incident wave from the reflected wave and present at port 3 an output proportional only to the latter





- Assume **that total reflection** occurs at port 2, so that $a_2 = b_2$
- Coupler output at port 3:

$$b_3 = s_{31}a_1 + s_{32}b_2 = s_{31}a_1 + s_{32}s_{21}a_1$$

- $s_{32}s_{21}a_1$ **coupling with port 2**
- $s_{31}a_1$ “undesired” **direct coupling of port 1 to port 3**
- **Power** measured at port 3:

$$P_3 = (|s_{32}| \cdot |s_{21}| \cdot |a_1|)^2 + (|s_{31}| \cdot |a_1|)^2 = |s_{32}|^2 \cdot |b_2|^2 \left[1 + \frac{|s_{31}|^2}{|s_{32}|^2 \cdot |s_{21}|^2} \right]$$



$$P_3 = (|s_{32}| \cdot |s_{21}| \cdot |a_1|)^2 + (|s_{31}| \cdot |a_1|)^2 = |s_{32}|^2 \cdot |b_2|^2 \left[1 + \frac{|s_{31}|^2}{|s_{32}|^2 \cdot |s_{21}|^2} \right]$$

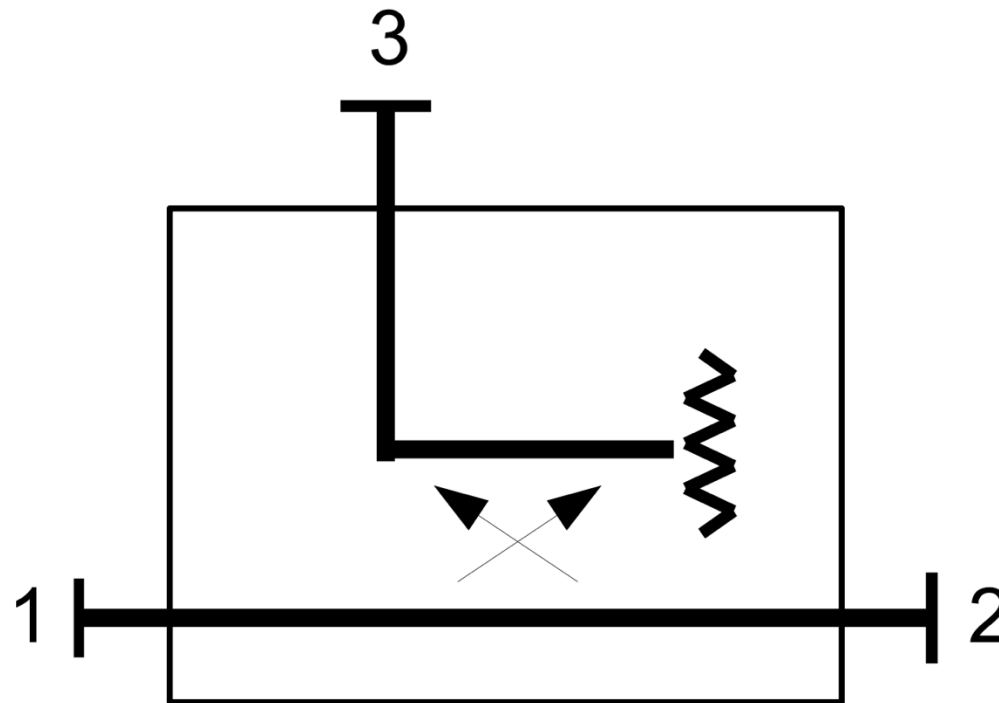
- **Proportional to the power** $|b_2|^2$ reflected into port 2, times the coupling factor s_{32}
- The term in square brackets in should be as close to 1 as possible
- **Directivity**: indication of the influence of power from the generator on the measurement of reflected waves
- Ratio of the isolation factor to the product between coupling factor and insertion loss

$$\begin{aligned} \text{Directivity}_{[dB]} &= -20 \log_{10} \frac{|s_{31}|^2}{|s_{32}|^2 \cdot |s_{21}|^2} = \\ &= \text{Isolation}_{[dB]} - \text{Coupling}_{[dB]} - \text{Insertion loss}_{[dB]} \end{aligned}$$



Directivity

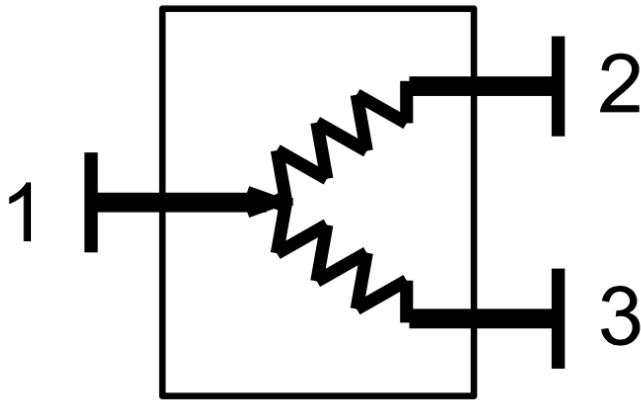
- Directivity is defined as a **power ratio** → no phase characteristic
- Complete characterization of the measuring system input-output behaviour (magnitude and phase) → **preliminary calibration phase**





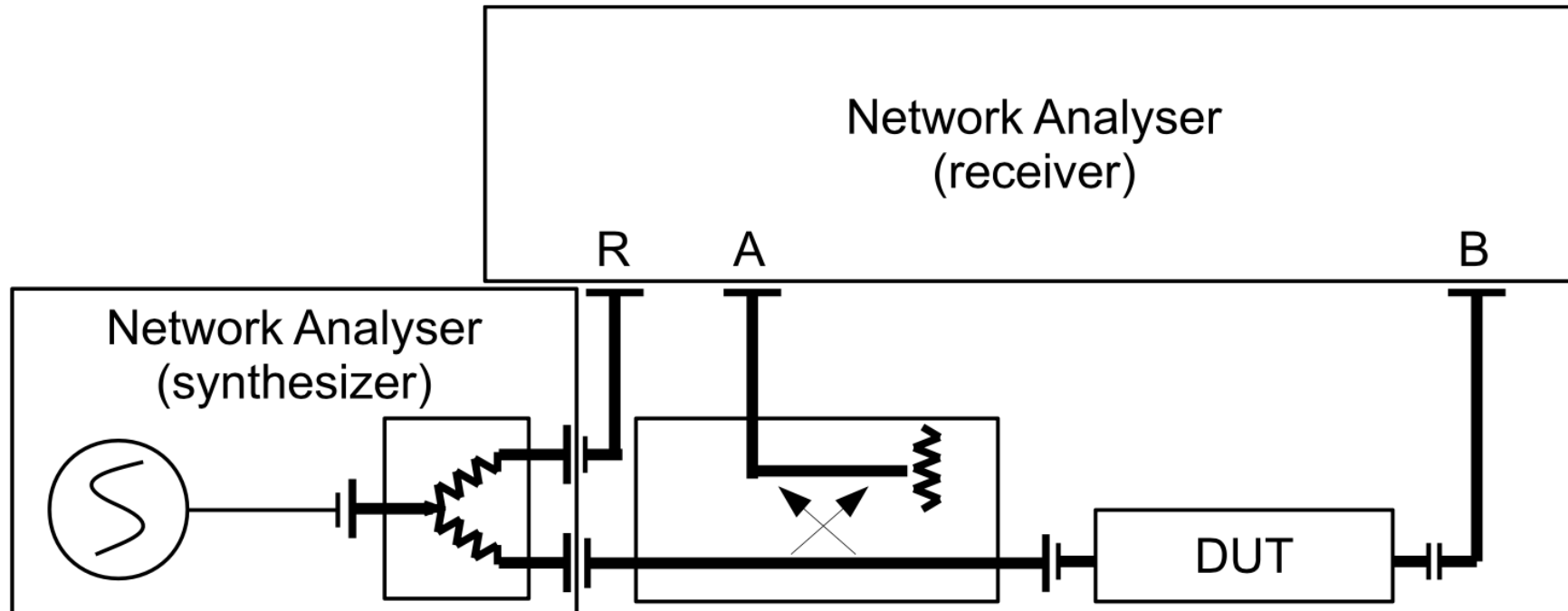
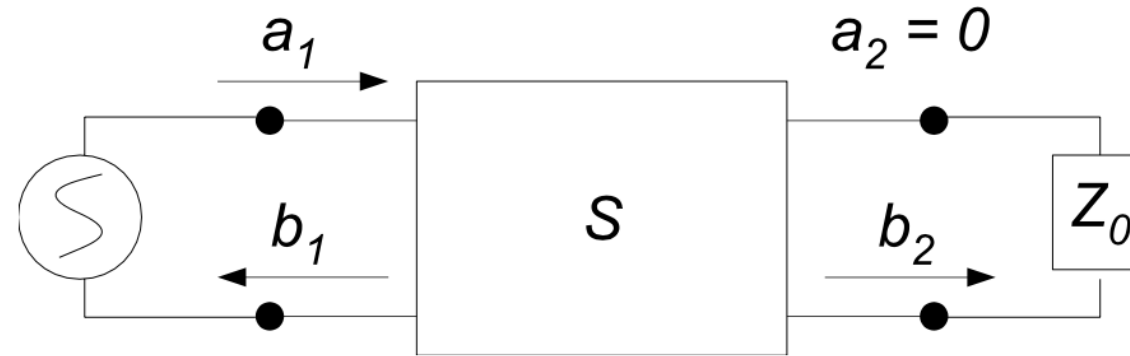
Power splitter

- Passive circuit which **divides the power input** into equal parts at the two outputs, while ensuring impedance matching
- Fully characterized by a set of three equations with **9 s-parameters**
- Ideal operation: **half of the input power** is found at each of the two output ports, corresponding to a 3 dB attenuation



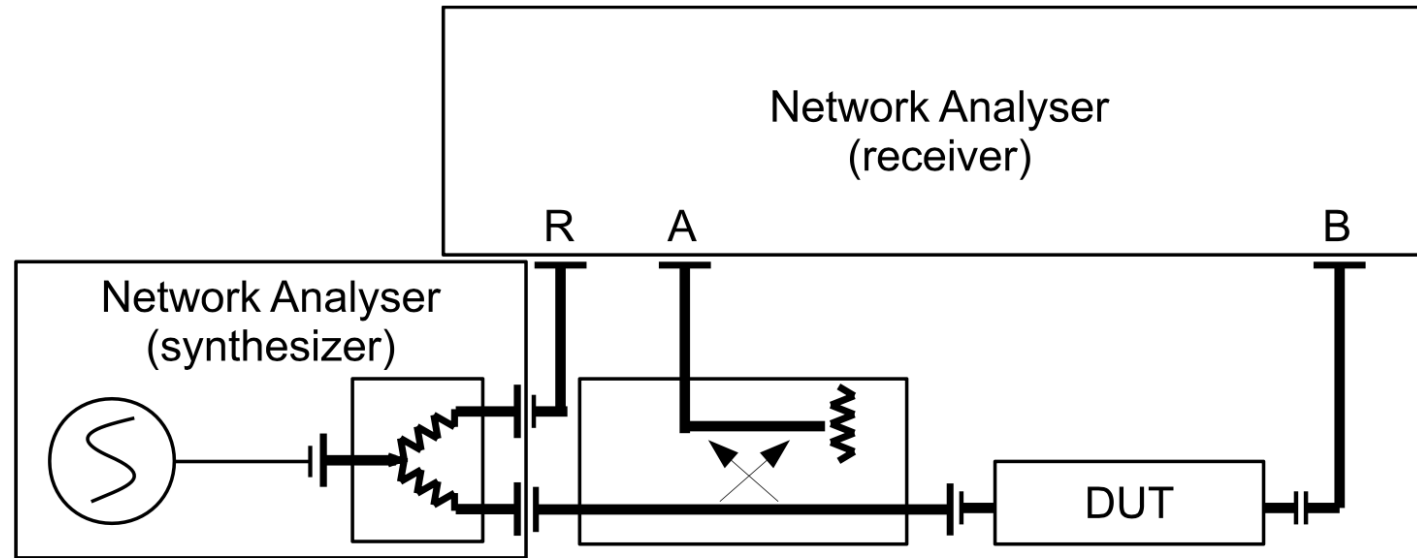


Vector network analyzer





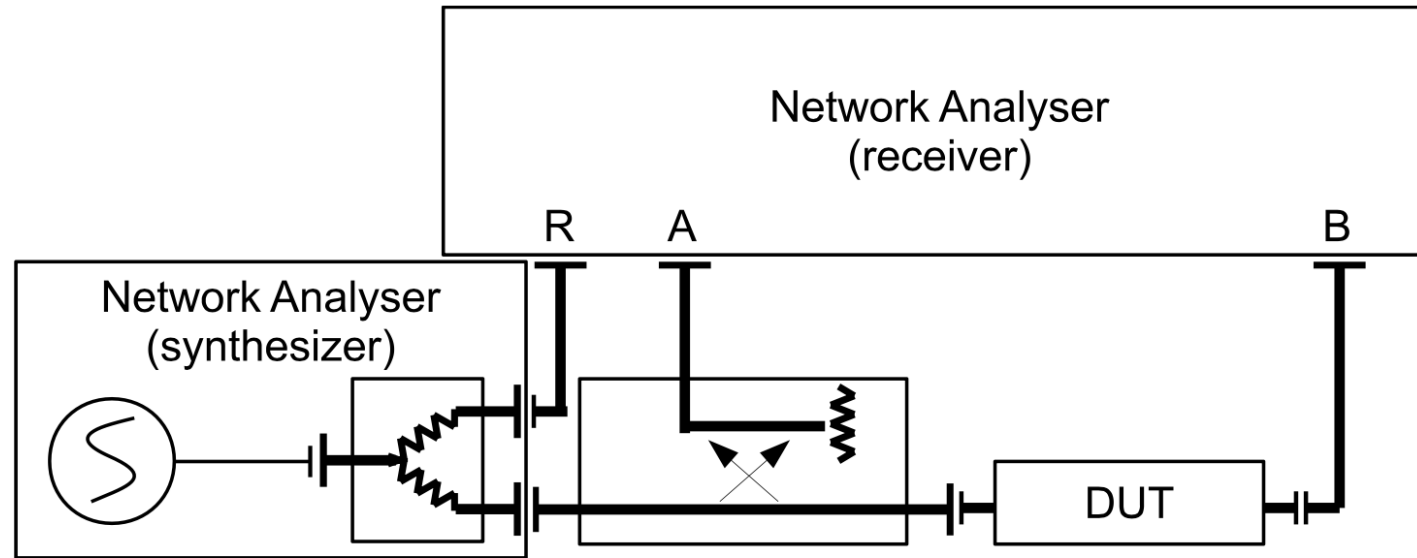
Vector network analyzer



- A, B and R **measurement inputs**
- Through the power splitter, the signal from the radio-frequency generator is sent **both to R and to the DUT**
- Responses from the DUT are measured, respectively, at **input B** for transmission and at **input A** for reflection



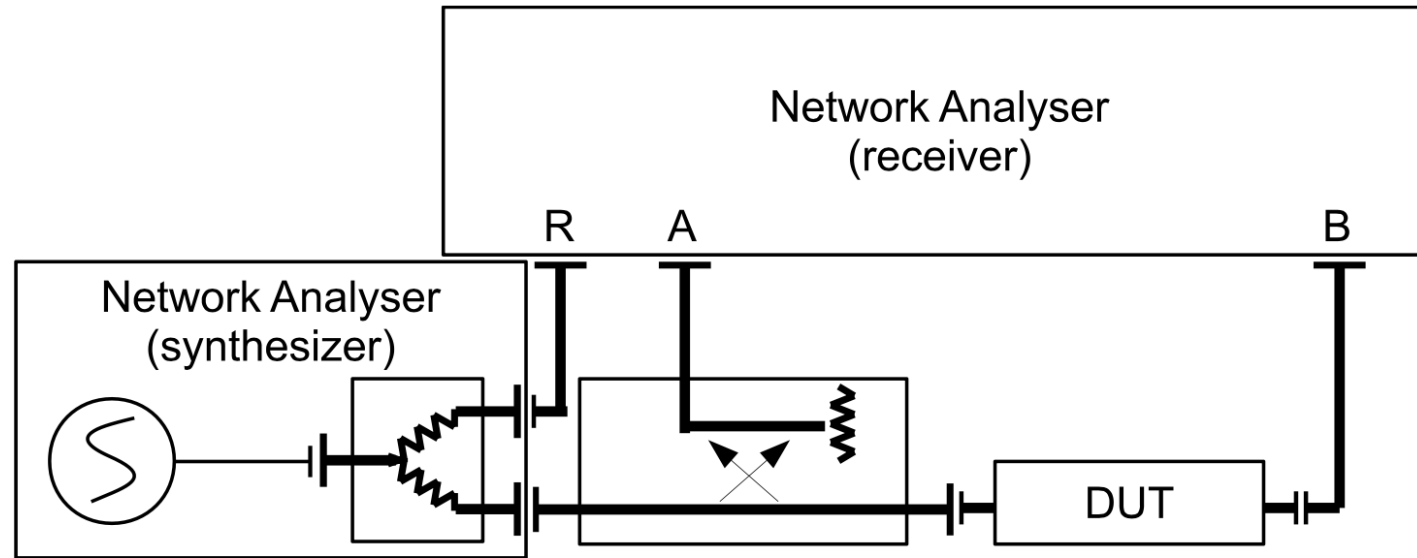
Vector network analyzer



- Signal power at the DUT input is **lower than power measured at input R** because of the **insertion loss** of the directional coupler
- Power measured at input A is **proportional to power reflected by the DUT**. The coupling factor of the directional coupler also has to be considered



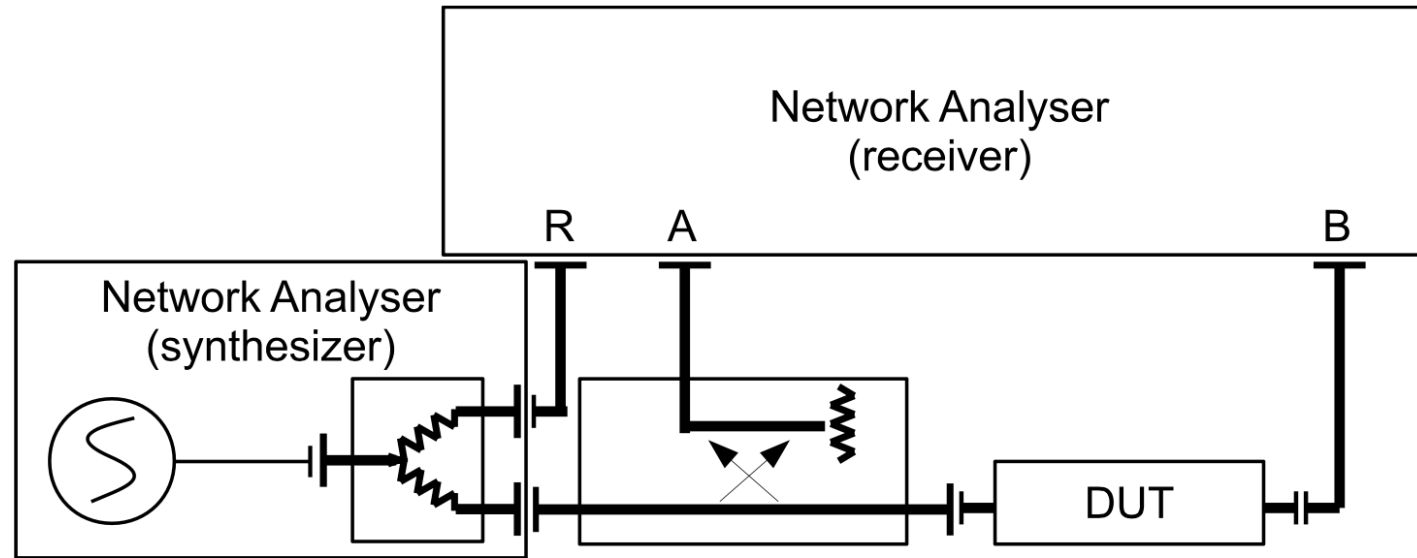
Vector network analyzer



- **Synthesizer:** generates a variable frequency sinewave with controlled, stable amplitude, that provides the input stimulus to the device under test. Frequency may vary between a minimum value of about 100 kHz and a maximum value that may reach up to around a hundred GHz



Vector network analyzer



- **Receiver:** measures sinewave magnitudes and phases at each of the three input channels. Indicating by V_R , V_A and V_B the resulting three phasors, measurements of the complex transmission coefficient s_{21} and of the complex reflection coefficient s_{11} are given by the two ratios:

$$\hat{s}_{21} = \frac{V_B}{V_R} \qquad \hat{s}_{11} = \frac{V_A}{V_R}$$

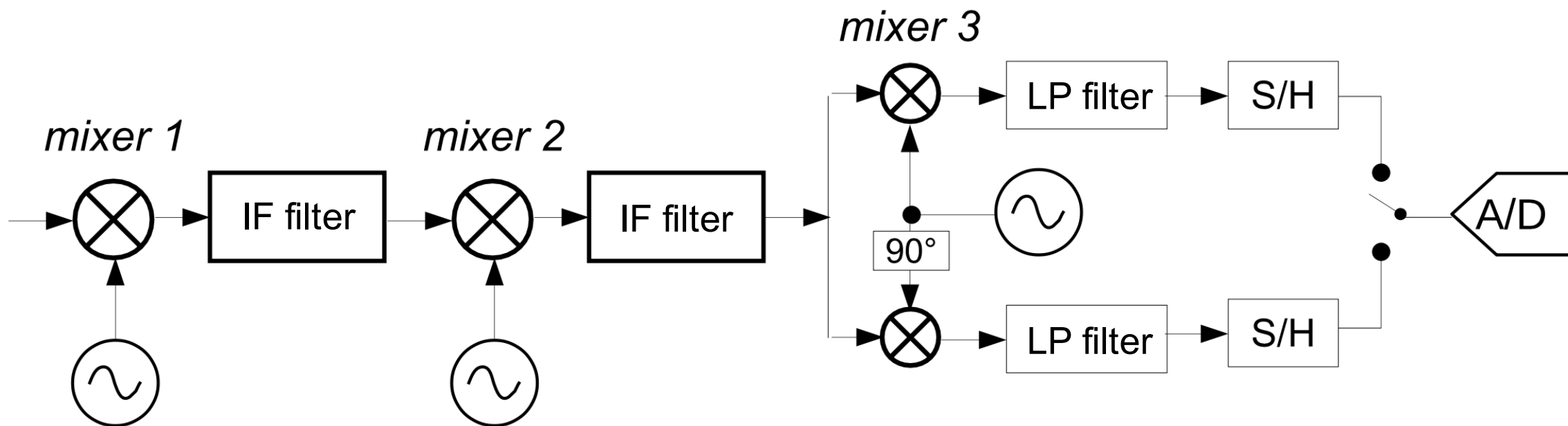


Vector network analyzer

- **Accurate phase measurement** → No distortion
- DUT (e.g. radio-frequency amplifier) **may add distortion** even when designed to operate as a linear device
- **Non-linearities should be avoided** → the aim of network analyzer measurements is the determination of parameters in a linear model
- The response of analyzed devices may depend quite significantly on **frequency** → large amplitude dynamics (at least 100 dB)



Network analyzer Receiver

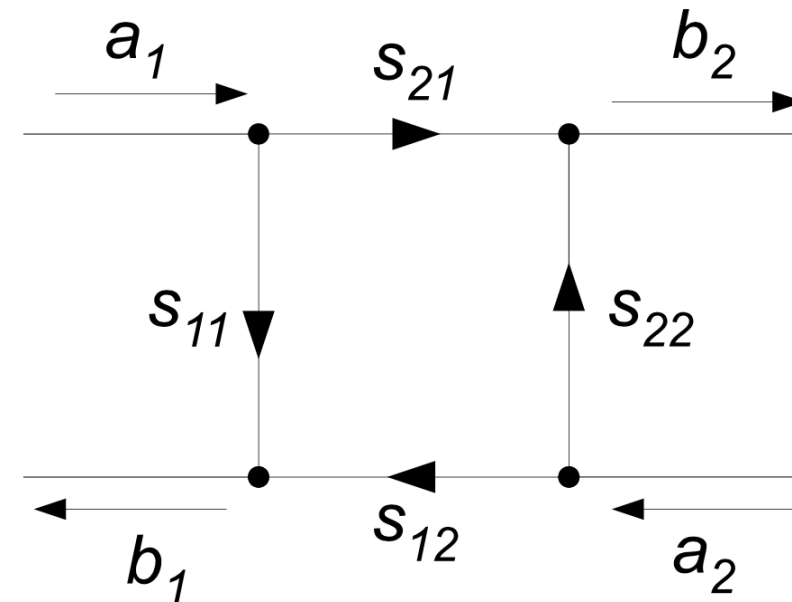


- Swept-frequency spectrum analyzer → **Superheterodyne**
- Three **cascaded mixer stages** → high frequency selectivity and wide amplitude dynamics
- The outputs of the final mixer stage are then **sampled and digitized**
- Input frequency is known → synthesizer and receiver frequencies are tuned



Measurement set-up calibration

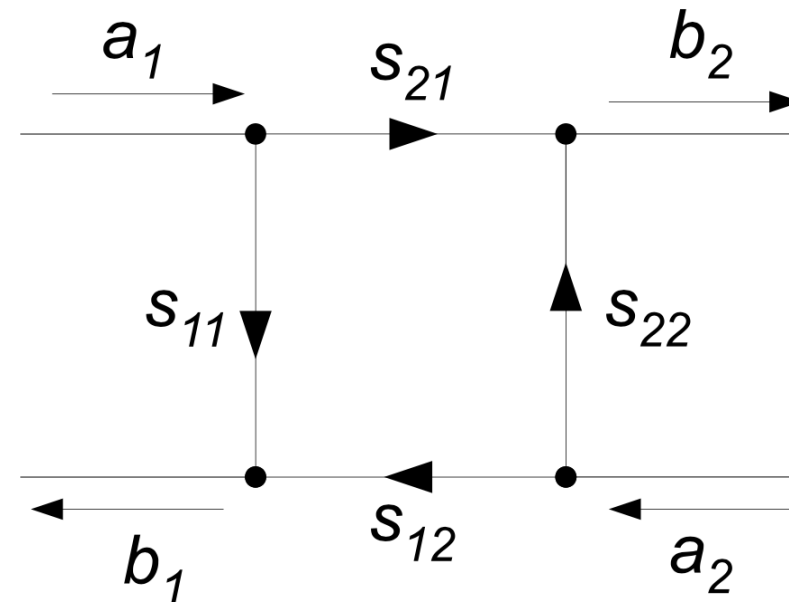
- **System calibration** → ensure the accuracy of measurement results
- **Radio-frequency measurements** → At high frequencies the influence of minor elements such as cables and connectors may become significant
- In network analyzers system calibration is essential to guarantee the validity of results





Measurement set-up calibration

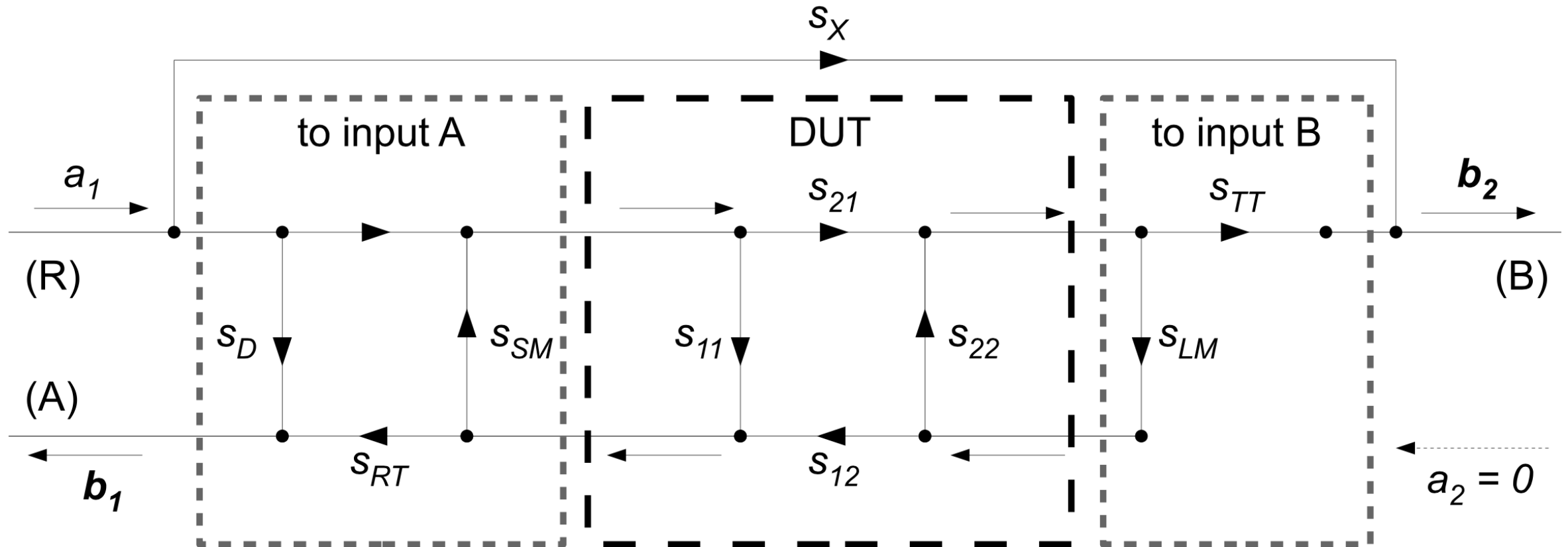
- Quantities a and b propagate along **arcs**, whose orientation is shown by arrows
- Nodes** are summing points, with arcs converging towards a node or spreading out from it, according to orientation
- Parameter s_{ij} denotes that if a_j is the quantity entering an arc, its output will be $s_{ij}a_j$





Measurement set-up calibration

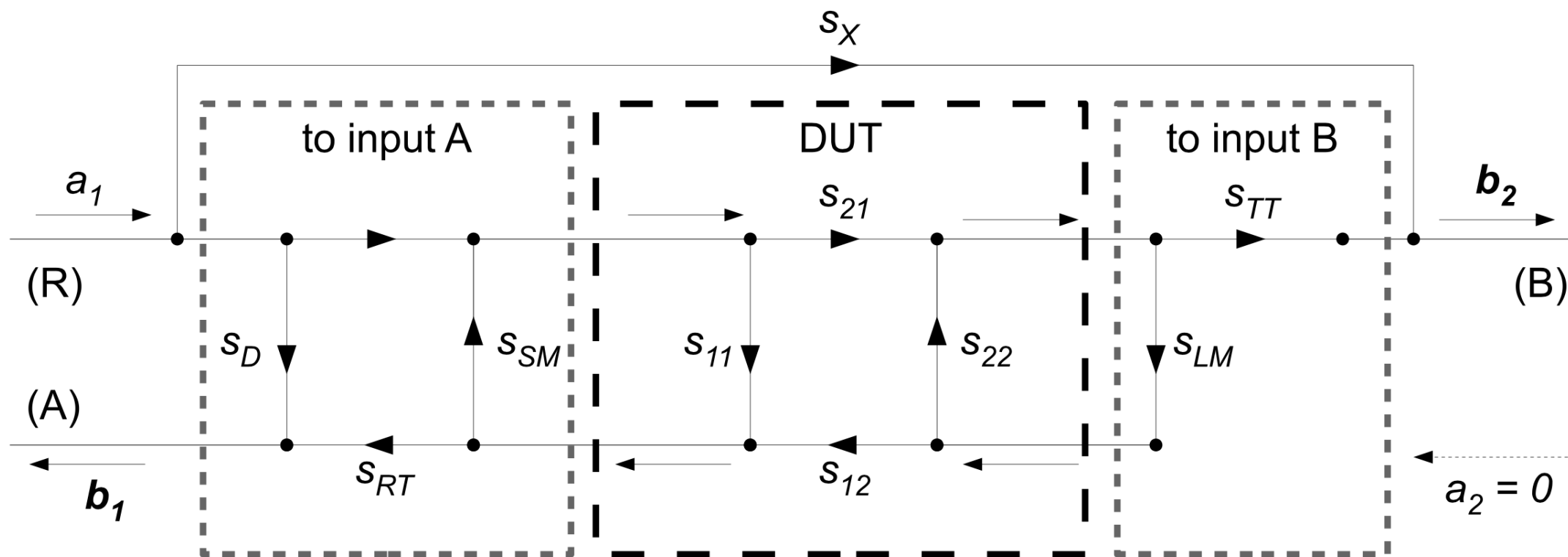
- Factors affecting the measurement result
- Effects of test set-up non-ideality





Measurement set-up calibration

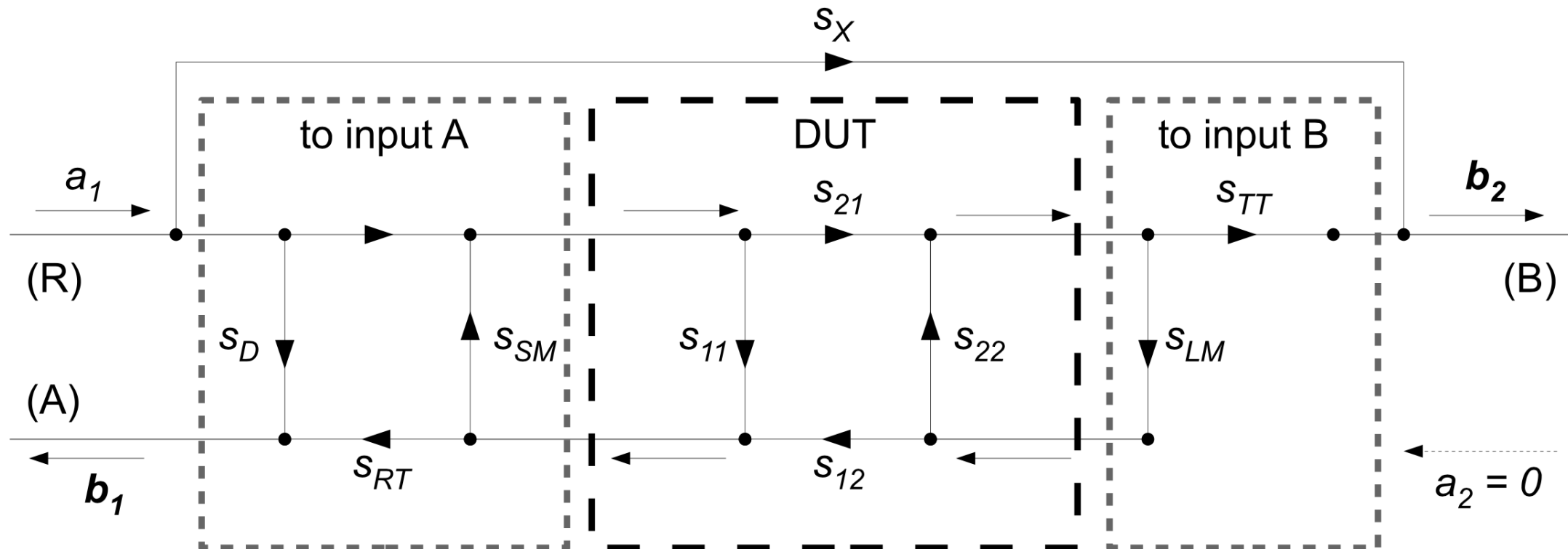
- s_D : limitations in the **directivity** of the **directional coupler**, that affect input A of the network analyzer. It is a complex parameter, which allows to also consider the effects on the measurement of phase





Measurement set-up calibration

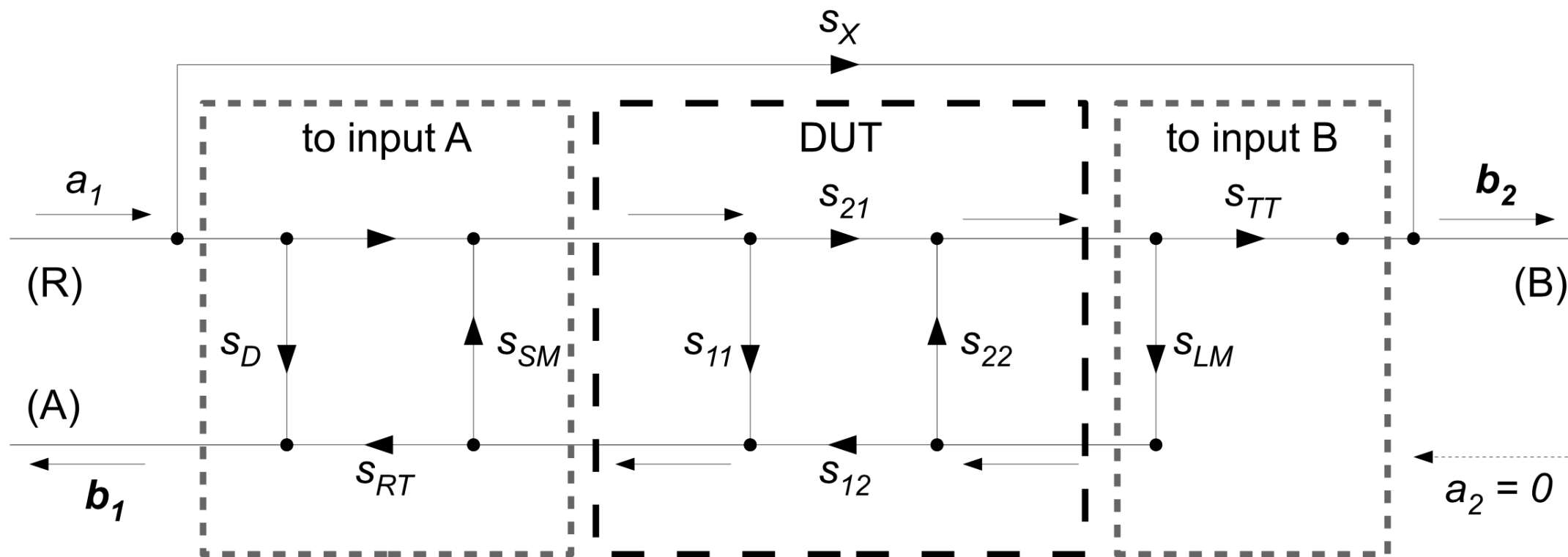
- s_{SM} and s_{LM} : possible effects of impedance mismatch between the measuring system and DUT ports (impedances not corresponding to Z_0). On the synthesizer side this is called **source mismatch**. Similarly, **load mismatch** (LM) may occur on the side of the termination load





Measurement set-up calibration

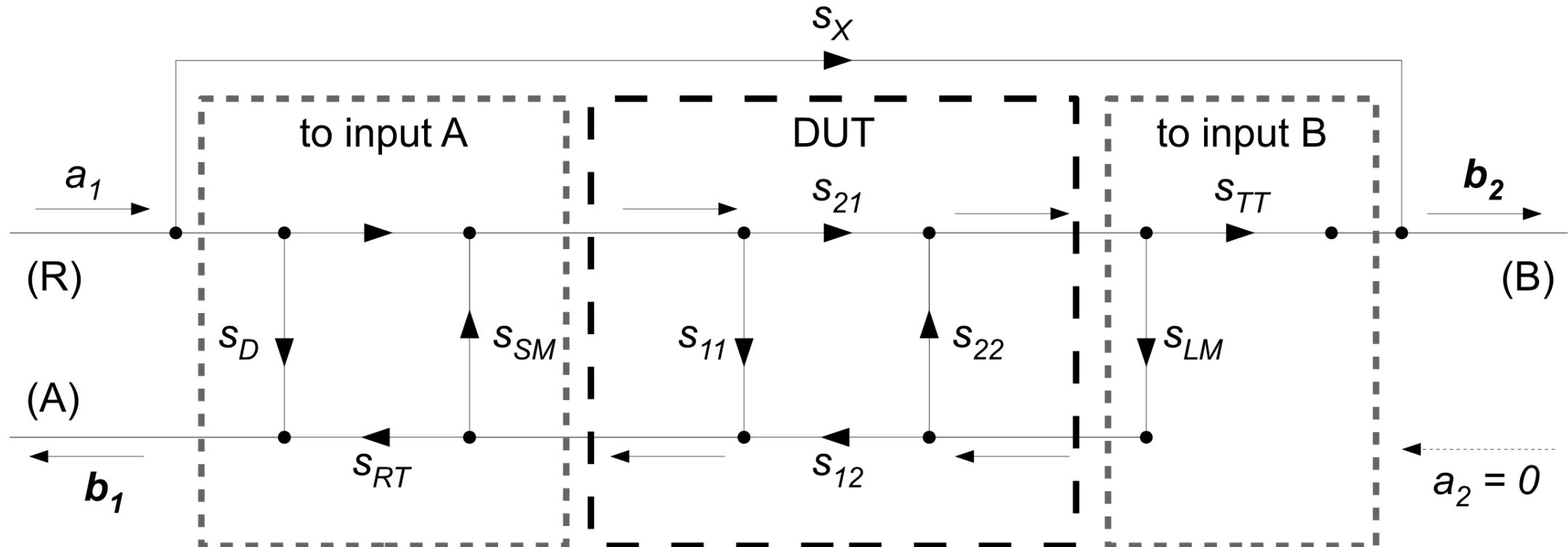
- s_{RT} and s_{TT} : **tracking errors** caused by differences between the frequency responses of input channels A and R (in this case, **reflection tracking**), or of channels B and R (**transmission tracking**)





Measurement set-up calibration

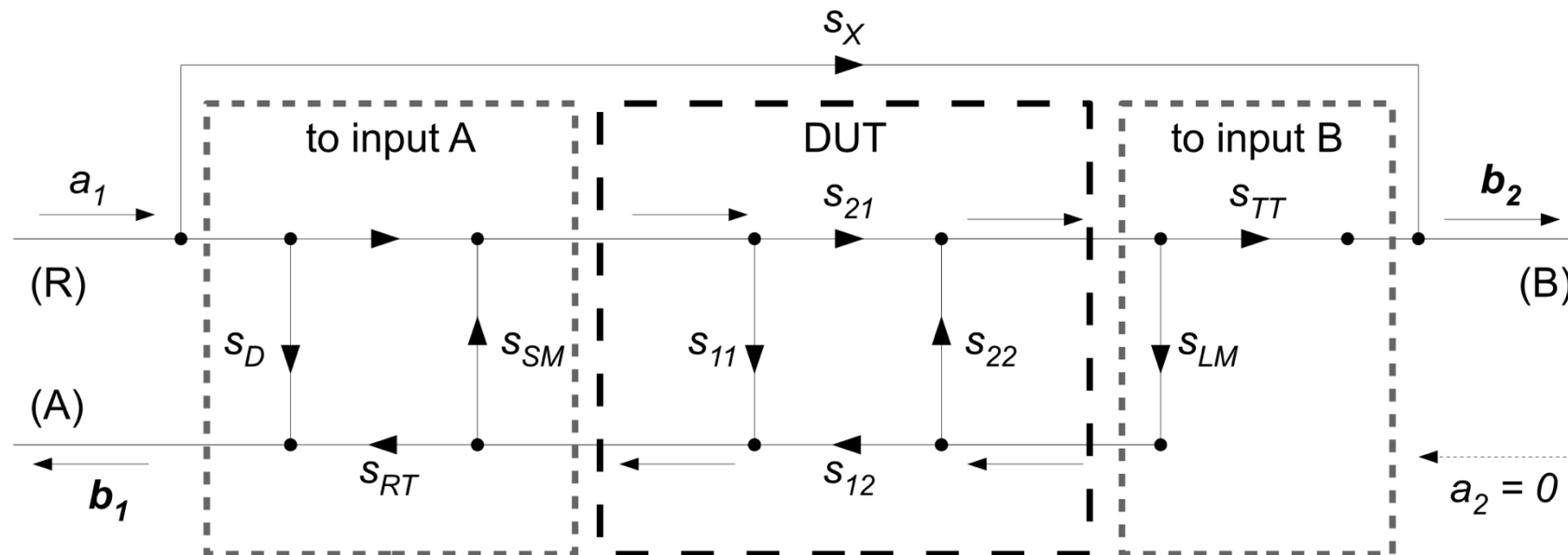
- s_X : **crosstalk** effects caused by undesired coupling between the DUT ports






Measurement set-up calibration

- 6 parameters (dependent on frequency) → calibration the test set-up in the configuration where the input stimulus is sent to DUT port 1
- 6 parameters for port 2
- **12 complex parameters** at each frequency





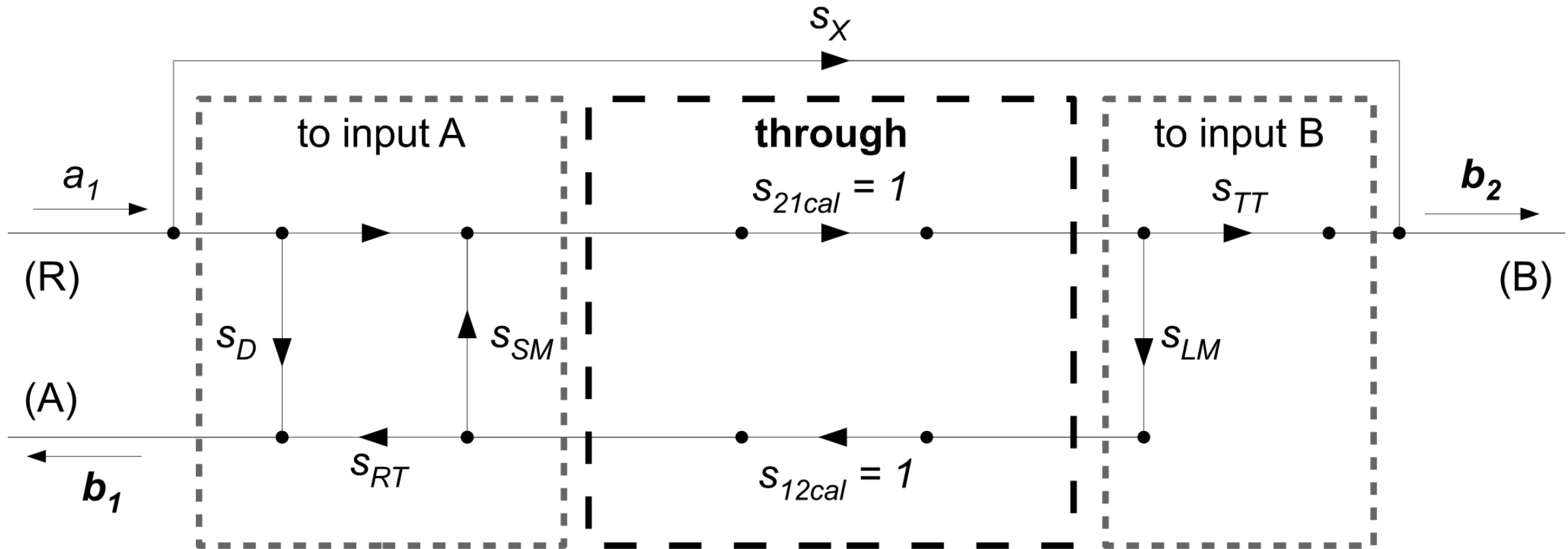
Measurement set-up calibration

- Commonly used calibration method → set of reference conditions by means of four circuit elements:
 - Short circuit (S)
 - Open circuit (O)
 - Load impedance of known value, usually Z_0 (load, L)  SOLT
 - Matched line (through, T)
- **Calibration:** set of equations correlating measurements to calibration parameters only



Measurement set-up calibration

- Example: use of a length of matched line (**through**) as the calibration reference

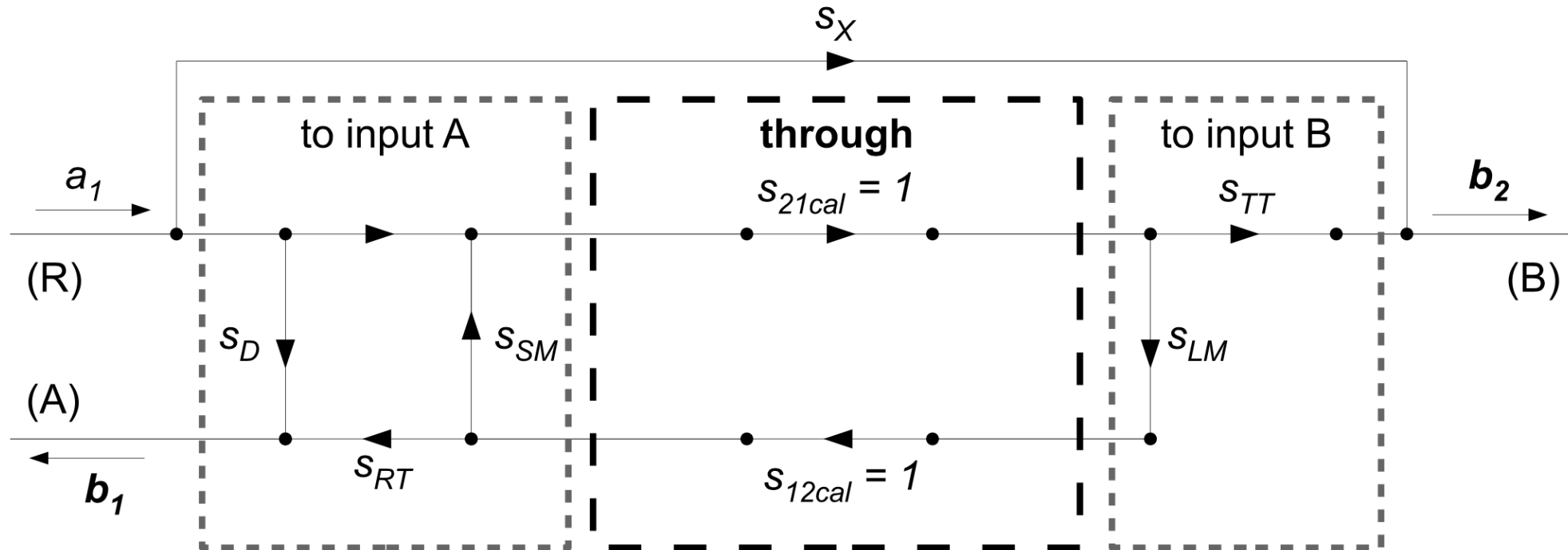






Measurement set-up calibration

- **Ideal through:** frequency response having unit magnitude and linear phase characteristic proportional to the line length
- Correction factors based on the measured response can be calculated and stored as calibration data





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