

LESSON 12: ESTIMATION OF K_x

There are several methods to correctly estimate the dispersion coefficient K_x in the Gaussian zone:

i. Empirical Formulas

ii. Chatwin Method

iii. Moments Method

iv. Calibration Method

v. Velocity Field Method

vi. Graphic Method

*These Methods have been
described in the exercise lesson*

The literature provides several formulas based on the multiple regression analysis of experimental data.

- McQuivey & Keefer (1974):

$$K_x = 0.058 \frac{Q}{i_b B}$$

- Liu (1977):

$$K_x = \alpha \frac{U^2}{z_0 u_*} \quad \alpha = 0.18 \left(\frac{u_*}{U} \right)^{3/2}$$

- Seo & Cheong (1998)

$$K_x = 5.195 z_0 u_* \left(\frac{B}{z_0} \right)^{0.62} \left(\frac{u_*}{U} \right)^{1.428}$$

- Kashelipour & Falconer (2002):

$$K_x = 10.612 z_0 u_* \left(\frac{u_*}{U} \right)$$

Chatwin rearranges the fundamental solution proposed by Taylor for 1D Fickian type process as following:

$$C(x, t) = \frac{M}{A\sqrt{4\pi K_x t}} e^{-\frac{(x-Ut)^2}{4K_x t}}$$

$$e^{\frac{(x-Ut)^2}{4K_x t}} = \frac{M}{A\sqrt{4\pi K_x}} \frac{1}{C\sqrt{t}}$$

$$R = \frac{M}{A\sqrt{4\pi K_x}}$$

ln

$$\frac{(x - Ut)^2}{4K_x t} = \ln \frac{R}{C\sqrt{t}}$$



$$\frac{(x - Ut)^2}{4K_x} = t \ln \frac{R}{C\sqrt{t}}$$

And then:

$$\frac{x}{2\sqrt{K_x}} - \frac{U}{2\sqrt{K_x}} t = \sqrt{t \ln \frac{R}{C\sqrt{t}}} = C^*$$



Fictitious concentration

Often the amount of mass M is unknown. In this case it is useful rewriting the term R :

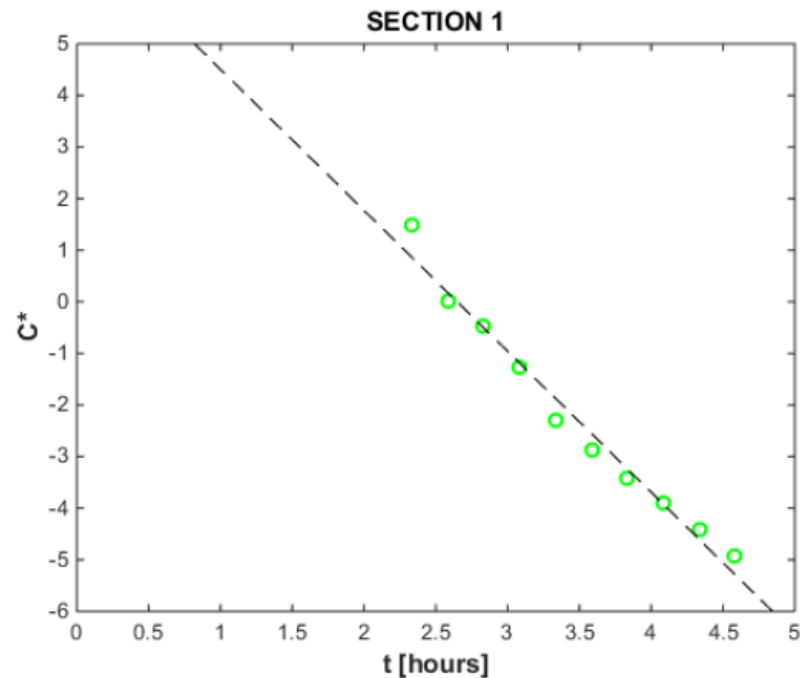
$$C_{max} = \frac{M}{A\sqrt{4\pi K_x t_{max}}} e^{-\frac{(x-Ut_{max})^2}{4K_x t_{max}}} \longrightarrow C_{max} t_{max} = \frac{M}{A\sqrt{4\pi K_x}} = R$$

And finally:

$$C^* = -\frac{U}{2\sqrt{K_x}} t + \frac{x}{2\sqrt{K_x}}$$

with:

$$\begin{cases} C^* = \sqrt{t \cdot \ln \frac{C_{max}\sqrt{t_{max}}}{C\sqrt{t}}} & t \leq t_{max} \\ C^* = -\sqrt{t \cdot \ln \frac{C_{max}\sqrt{t_{max}}}{C\sqrt{t}}} & t > t_{max} \end{cases}$$



K_x and U are calculated by the slope and the intercept of the dashed line

When the process of dispersion occurs in the Gaussian zone, the variance of the cloud increases linearly, i.e.:

$$\frac{d\sigma_x^2}{dt} = 2K_x$$

By applying the discretization method, it means:

$$K_x = \frac{1}{2} \frac{\sigma_x^2(t_2) - \sigma_x^2(t_1)}{t_2 - t_1}$$

Being:

$$\sigma_x^2(t_i) = \frac{\int_{-\infty}^{+\infty} [x - \mu_x(t_i)]^2 C(x, t_i) dt}{\int_{-\infty}^{+\infty} C(x, t_i) dt} \longrightarrow \text{Statistical moment of order II}$$

$$\mu_x(t_i) = \frac{\int_{-\infty}^{+\infty} x C(x, t_i) dt}{\int_{-\infty}^{+\infty} C(x, t_i) dt} \longrightarrow \text{Statistical moment of order I}$$

In the practice, it is easier measuring $C(x_i, t)$ rather than $C(x, t_i)$. Hence we need to use the temporal variance of the concentration in x_i , $\sigma_t^2(x_i)$.

Fisher in 1966 demonstrated that:

$$K_x = \frac{1}{2} U_0 \frac{\sigma_t^2(x_2) - \sigma_t^2(x_1)}{\bar{t}_2 - \bar{t}_1}$$

where

$$\bar{t}_i = \frac{A}{M} \int_0^{+\infty} t C(x_i, t) dt \quad \longrightarrow \quad \begin{array}{l} \text{Statistical moment of order I.} \\ \text{It is the time of the centroid in } x_i \end{array}$$

$$\sigma_t^2(x_i) = \frac{A}{M} \int_0^{+\infty} [t - \bar{t}_i]^2 C(x_i, t) dt \quad \longrightarrow \quad \text{Statistical moment of order II}$$

$$U_0 = \frac{x_2 - x_1}{\bar{t}_2 - \bar{t}_1} \quad \longrightarrow \quad \begin{array}{l} \text{Mean velocity of the cloud} \\ \text{centroid between } x_1 \text{ and } x_2 \end{array}$$

The Calibration method is one of the most reliable methods to determine the mean velocity U and the dispersion coefficient K_x .

The Calibration method assumes the Taylor solution being valid, i.e. for lumped insertion:

$$C(x, t) = \frac{M}{A\sqrt{4\pi K_x t}} e^{-\frac{(x-Ut)^2}{4K_x t}}$$

Generally, the distribution depends on the initial distribution of C , then we can consider:

$$\frac{dM}{A} = C(\xi, t_1)d\xi \longrightarrow \text{Amount of mass per unit area due to the concentration } C \text{ in the section } \xi \text{ at time } t_1.$$

By the fundamental solution:

$$dC = \frac{C(\xi, t_1)d\xi}{\sqrt{4\pi K_x(t-t_1)}} e^{-\frac{(x-\xi-U(t-t_1))^2}{4K_x(t-t_1)}}$$

New reference system

New reference time

Distribution of C due to the contribution $C(\xi, t_1)d\xi$

By integrating along x all the contributions of the generic distribution $C(\xi, t_1)$, we find:

$$C(x, t) = \int_{-\infty}^{+\infty} \frac{C(\xi, t_1)}{\sqrt{4\pi K_x(t - t_1)}} e^{-\frac{(x-\xi-U(t-t_1))^2}{4K_x(t-t_1)}} d\xi$$

It is worth noting that if we know $C(x, t_1)$, i.e. $C(\xi, t_1)$, we can evaluate $C(x, t)$ and thus $C(x, t_2)$, where t_1 is the initial condition time and t_2 a time of interest of the problem!

The calibration method uses this property, but it is focused on the temporal distribution of C , instead of its spatial distribution, i.e.:

$$C(x, t_1) \rightarrow C(x, t_2)$$

$$C(x_1, t) \rightarrow C(x_2, t)$$

This operation is not trivial and it needs of some assumptions. There are two main solutions:

- i. Approximation of the Frozen Cloud
- ii. Hayami Method

Let's see the approximation of the Frozen Cloud

It is worth noting that given $C(x, t)$:

- Spatial distribution ($t = t_n$). The peak of concentration has the following characteristics:

$$x_{max} = x_g = Ut_n$$

$$C_{max} = \frac{M}{A\sqrt{4\pi K_x t_n}} = \frac{M}{A\sqrt{4\pi K_x x_{max}/U}}$$

C_{max} is in x_g !

- Temporal distribution ($x = x_n$).

$$t_{max} \rightarrow \frac{dC}{dt} = 0 \quad \longrightarrow \quad t_{max} = \sqrt{\frac{K_x^2}{U^4} + \frac{x_n^2}{U^2}} - \frac{K_x}{U^2} \quad \text{Time of the peak of concentration in } x_n$$

$$C = \frac{M}{A\sqrt{4\pi K_x t}} \cdot e^{-\frac{(x_n - Ut)^2}{4K_x t}} = f \cdot g \quad \longrightarrow \quad \frac{dC}{dt} = f g' + f' g = 0$$

$$f = \frac{M}{A\sqrt{4\pi K_x t}} \quad \longrightarrow \quad f' = -\frac{1}{2} \frac{M 4\pi K_x}{A\sqrt{4\pi K_x t}} \frac{1}{4\pi K_x t} = -\frac{1}{2t} \frac{M}{A\sqrt{4\pi K_x t}} = -\frac{1}{2t} f$$

$$g = e^{-\frac{(x_n - Ut)^2}{4K_x t}} \quad \longrightarrow \quad g' = -\frac{d}{dt} \left[\frac{(x_n - Ut)^2}{4K_x t} \right] e^{-\frac{(x_n - Ut)^2}{4K_x t}} = -\left[\frac{-2(x_n - Ut)Ut - (x_n - Ut)^2}{4K_x t^2} \right] g = -\frac{U^2 t^2 - x_n^2}{4K_x t^2} g$$

$$\frac{dC}{dt} = -\left(\frac{U^2 t^2 - x_n^2}{4K_x t^2} + \frac{1}{2t} \right) f g = 0 \quad \longrightarrow \quad \frac{U^2 t^2 - x_n^2 + 2K_x t}{4K_x t^2} = 0 \quad \longrightarrow \quad t_{max} = \frac{-2K_x + \sqrt{4K_x^2 + 4U^2 x_n^2}}{2U^2}$$

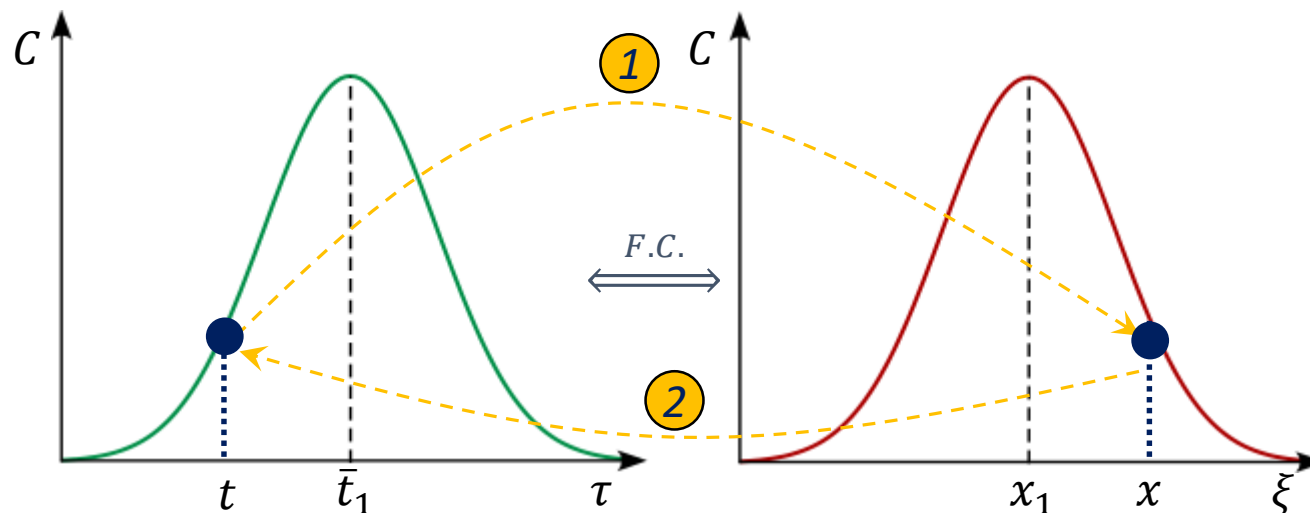
$$t_g = \bar{t} = \frac{\int_0^\infty tC(x_n, t)dt}{\int_0^\infty C(x_n, t)dt} = \frac{x_n}{U} + 2 \frac{K_x}{U^2} \quad \text{Time of the centroid in } x_n$$

The peak of concentration time and the centroid time are different: $t_{max} \neq \bar{t}$

The Frozen Cloud (F.C.) approximation assumes that the advection is much greater than dispersion, i.e. $Pe \gg 1$. It implies that:

$$\frac{K_x}{U^2} \ll \frac{x_n}{U} \longrightarrow \bar{t} \cong t_{max} = \frac{x_n}{U}$$

Under this assumption, we can link temporal C distribution in a given section x_1 and spatial C distribution in a given time $\bar{t}_1$ as following:

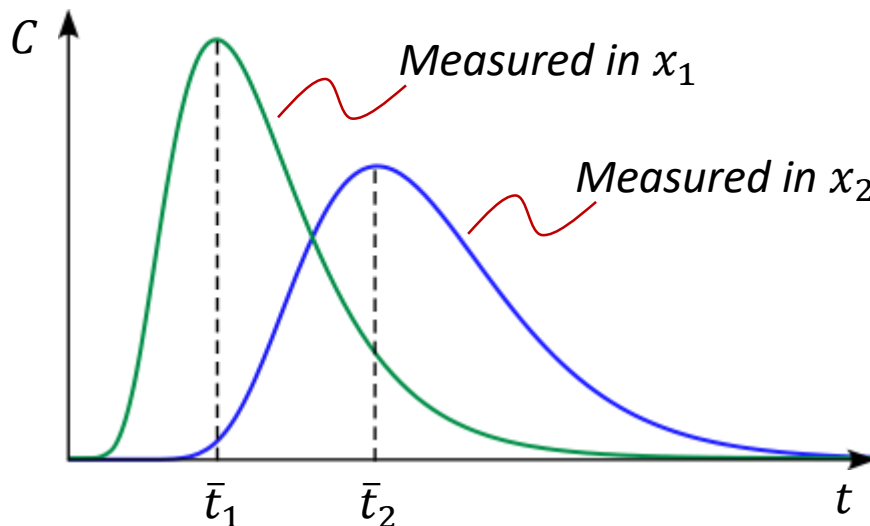


Let's analyze the concentration which is highlighted by blue circle in the two planes.

① $C(x_1, t) \longrightarrow C(x, \bar{t}_1)$ *The position x is reached travelling with U for $\Delta t = \bar{t}_1 - t$*
 $C(x_1 + U(\bar{t}_1 - t), \bar{t}_1)$ *The spatial distribution is expressed in t*

② $C(x, \bar{t}_1) \longrightarrow C(x_1, t)$
 $C\left(x_1, \bar{t}_1 - \frac{x - x_1}{U}\right)$ *The temporal distribution is expressed in x*

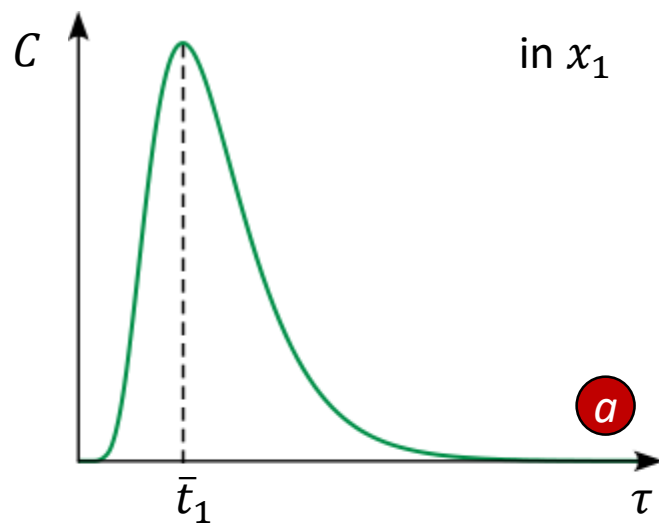
The variables transformation is then given by: $x = x_1 + U(\bar{t}_1 - t)$



In the practice:

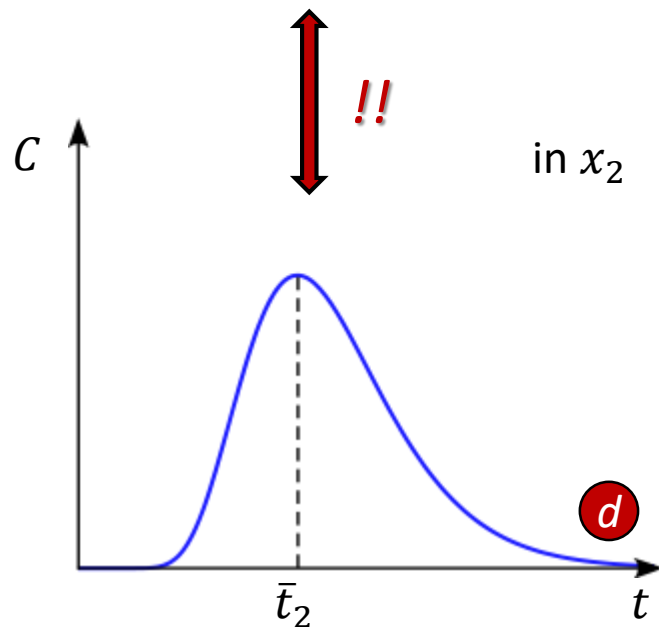
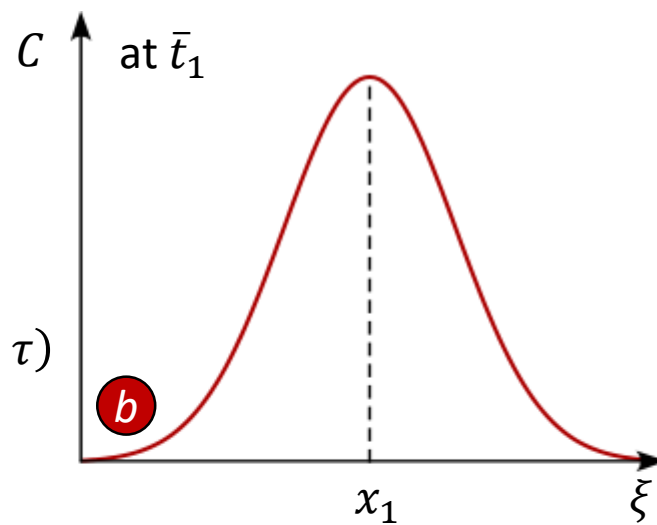
$$C(x_1, t) \overset{?}{\Longleftrightarrow} C(x_2, t)$$

The solution of the problem provides K_x and U



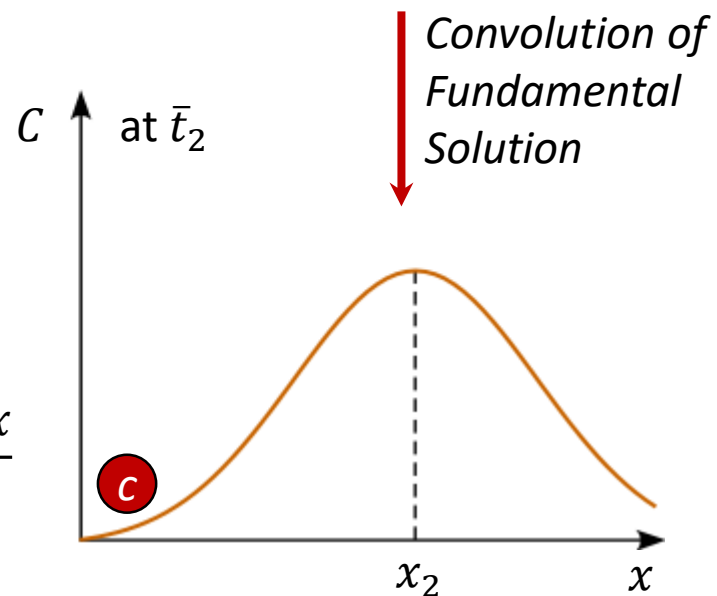
Frozen Cloud

$\xi = x_1 + U(\bar{t}_1 - \tau)$



Frozen Cloud

$t = \bar{t}_2 + \frac{x_2 - x}{U}$



a → **b**

$$C(x_1, \tau) \rightarrow C(\xi, \bar{t}_1)$$

It is the initial condition of the dispersion equation

b → **c**

$$C(x, t) = \int_{-\infty}^{+\infty} \frac{C(\xi, \bar{t}_1)}{\sqrt{4\pi K_x(t - \bar{t}_1)}} e^{-\frac{(x - \xi - U(t - \bar{t}_1))^2}{4K_x(t - \bar{t}_1)}} d\xi$$

↓ $t = \bar{t}_2$

$$C(x, \bar{t}_2) = \int_{-\infty}^{+\infty} \frac{C(\xi, \bar{t}_1)}{\sqrt{4\pi K_x(\bar{t}_2 - \bar{t}_1)}} e^{-\frac{(x - \xi - U(\bar{t}_2 - \bar{t}_1))^2}{4K_x(\bar{t}_2 - \bar{t}_1)}} d\xi \quad (*)$$

c → **d**

$$C(x, \bar{t}_2) \rightarrow C(x_2, t)$$

The distribution in (d) as function of the distribution in (a) can be estimated by replacing in (*) the variables transformations due to the Frozen Cloud, that are:

$$\begin{cases} \xi = x_1 + U(\bar{t}_1 - \tau) \\ x = x_2 + U(\bar{t}_2 - t) \end{cases}$$

In the latter the centroid position x_2 depends on the centroid position x_1 as following:

$$x_2 = x_1 + U(\bar{t}_2 - \bar{t}_1)$$

Then: $x = x_2 + U(\bar{t}_2 - t) = x_1 + U(\bar{t}_2 - \bar{t}_1) + U(\bar{t}_2 - t)$

$$x = x_1 + U(2\bar{t}_2 - \bar{t}_1 - t)$$

We can express the difference $x - \xi$ as:

$$x - \xi = x_1 + U(2\bar{t}_2 - \bar{t}_1 - t) - x_1 - U(\bar{t}_1 - \tau)$$

$$\longrightarrow x - \xi = U(2\bar{t}_2 - 2\bar{t}_1 - t + \tau) \quad (**)$$

The **(**)** into **(*)** yields:

$$C(x_2, t) = \int_{-\infty}^{+\infty} \frac{C(\xi, \bar{t}_1)}{\sqrt{4\pi K_x(\bar{t}_2 - \bar{t}_1)}} e^{-\frac{(U(2\bar{t}_2 - 2\bar{t}_1 - t + \tau) - U(\bar{t}_2 - \bar{t}_1))^2}{4K_x(\bar{t}_2 - \bar{t}_1)}} d\xi$$

$$C(x_2, t) = \int_{-\infty}^{+\infty} \frac{C(\xi, \bar{t}_1)}{\sqrt{4\pi K_x(\bar{t}_2 - \bar{t}_1)}} e^{-\frac{U^2(\bar{t}_2 - \bar{t}_1 - t + \tau)^2}{4K_x(\bar{t}_2 - \bar{t}_1)}} d\xi$$

To conclude the demonstration, we need of expressing the initial concentration distribution in terms of temporal concentration distribution. It is useful noting that:

$$\frac{dM}{A} = C(\xi, \bar{t}_1) d\xi = C(x_1, \tau) U d\tau$$

And finally:

$$\longrightarrow C(x_2, t) = \int_{-\infty}^{+\infty} \frac{C(x_1, \tau) U}{\sqrt{4\pi K_x (\bar{t}_2 - \bar{t}_1)}} e^{-\frac{U^2 (\bar{t}_2 - \bar{t}_1 - t + \tau)^2}{4K_x (\bar{t}_2 - \bar{t}_1)}} d\tau$$

The first attempt for U can be:

- $U = \frac{x_2 - x_1}{\bar{t}_2 - \bar{t}_1}$

- $U \cong \frac{2}{3} U_M$

 *Flow velocity which is measured on the free surface*

Another method to determine the pair (K_x, U) was proposed by Hayami.

For Hayami the concentration distribution C_H considering the insertion point in x_1 is:

$$C_H(x, t) = C(x, t) \frac{x - x_1}{Ut}$$


Taylor solution



$$C_H(x, t) = \frac{M(x - x_1)}{A U t \sqrt{4\pi K_x t}} e^{-\frac{(x - Ut)^2}{4K_x t}}$$

The solution in the section of interest x_2 is the sum of the contribute $C(x_1, \tau)Ud\tau$ inserting in x_1 during the time τ :



$$C(x_2, t) = \int_{-\infty}^{+\infty} \frac{C(x_1, \tau)(x_2 - x_1)}{(t - \tau)\sqrt{4\pi K_x(t - \tau)}} e^{-\frac{[x_2 - x_1 - U(t - \tau)]^2}{4K_x(t - \tau)}} d\tau$$

Being $C = \frac{M}{A}$

The methods described above are effective only when the solute and insertion mode have some characteristics

Solute:

- Negligible bio-chemicals reactions
- Negligible adsorption by sediments
- Negligible toxicity
- High solubility
- Neutrally buoyant, i.e. $\gamma_s \cong \gamma_w$
- Easy to chemically analyze
- Dye
- Cheap



Sodium Chloride

Magnesium Sulfate

Sodium Nitrate

Sodium Dichromate

Rhodamine

} *Most
common*

The modality of solute insertion depends on the variables of interest that one wants to estimate.

Variables	Modality
U (between two sections)	• Lumped insertion • Step insertion
k_z k_y	• Continuous insertion
k_x K_x	• Lumped insertion