

Probabilistic Model Checking

Alessandro Abate

Lecture 4, p2: Linear Temporal Logic

Modal logics

- ▶ based on propositional logic
- ▶ used to reason about objects with modalities (expressed via modal operators)
- ▶ in particular, modal operators qualify temporal expressions
- ▶ in this course we shall focus on two classes: LTL and CTL
 1. LTL: linear temporal logic
 2. CTL: computational tree logic
- ▶ extension to CTL*

Syntax of LTL

► $\varphi ::= \text{true} \mid a \mid \varphi \wedge \varphi \mid \neg\varphi \mid \bigcirc\varphi \mid \varphi \mathbf{U} \varphi, \quad a \in AP$

► alternative expression of more formulae

$$\begin{aligned}\varphi_1 \vee \varphi_2 &= \neg(\neg\varphi_1 \wedge \neg\varphi_2) \\ \varphi_1 \Rightarrow \varphi_2 &= \neg\varphi_1 \vee \varphi_2\end{aligned}$$

and of two temporal modalities

$$\begin{aligned}\diamond\varphi &= \text{true} \mathbf{U} \varphi \\ \square\varphi &= \neg\diamond\neg\varphi\end{aligned}$$

Alternative syntax in the literature

- ▶ you may encounter the following notations:

$$X\varphi : \bigcirc\varphi$$

$$F\varphi : \diamond\varphi$$

$$G\varphi : \square\varphi$$

(notation on left-hand side from [CGP99],
on right-hand side from [BK08])

- ▶ past operators are possible (though not strictly necessary)

Semantics of LTL

$$TS \models \varphi \text{ iff } \forall s \in I : s \models \varphi$$

(recall that I is the set of initial states), where

$$s \models \varphi \text{ iff } \forall \pi \in \text{Paths}(s) : \pi \models \varphi$$

Semantics of LTL

$$TS \models \varphi \text{ iff } \forall s \in I : s \models \varphi$$

(recall that I is the set of initial states), where

$$s \models \varphi \text{ iff } \forall \pi \in \text{Paths}(s) : \pi \models \varphi$$

and where (cf. LTL syntax)

$$\pi \models \text{true}$$

$$\pi \models a \text{ iff } a \in L(\pi[0])$$

$$\pi \models \varphi \wedge \psi \text{ iff } \pi \models \varphi \wedge \pi \models \psi$$

$$\pi \models \neg\varphi \text{ iff } \pi \not\models \varphi$$

$$\pi \models \bigcirc\varphi \text{ iff } \pi[1..] \models \varphi$$

$$\pi \models \varphi \text{ U } \psi \text{ iff } \exists i \geq 0 : \pi[i..] \models \psi \wedge \forall 0 \leq j < i : \pi[j..] \models \varphi$$

Alternative semantics of LTL

- ▶ let φ be an LTL formula over AP , inducing the LT property

$$\text{Words}(\varphi) = \{\sigma \in (2^{AP})^\omega \mid \sigma \models \varphi\}$$

where $(\sigma = A_0A_1\dots)$

$$\sigma \models \text{true}$$

$$\sigma \models a \Leftrightarrow a \in A_0$$

...

- ▶ $TS \models \varphi$ iff $\text{Traces}(TS) \subseteq \text{Words}(\varphi)$

Alternative semantics of LTL

- ▶ let φ be an LTL formula over AP , inducing the LT property

$$\text{Words}(\varphi) = \{\sigma \in (2^{AP})^\omega \mid \sigma \models \varphi\}$$

where $(\sigma = A_0A_1\dots)$

$$\sigma \models \text{true}$$

$$\sigma \models a \Leftrightarrow a \in A_0$$

...

- ▶ $TS \models \varphi$ iff $\text{Traces}(TS) \subseteq \text{Words}(\varphi)$
- ▶ $\varphi_1 \equiv \varphi_2$ if $\text{Words}(\varphi_1) = \text{Words}(\varphi_2)$

LTL properties for the traffic light model

- ▶ how to express
“the light is infinitely often red”
by an LTL formula?
- ▶ $\square\lozenge\text{red}$

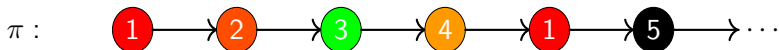
LTL properties for the traffic light model

- ▶ how to express
“the light is infinitely often red”
by an LTL formula?
- ▶ $\square \diamond \text{red}$

- ▶ how to express
“once green, the light cannot become immediately red”
by an LTL formula?
- ▶ $\square(\text{green} \Rightarrow \neg \bigcirc \text{red})$

Verification of LTL specs is over linear-time paths

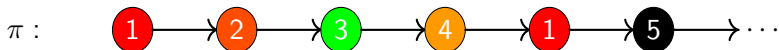
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models \text{red}$?

Verification of LTL specs is over linear-time paths

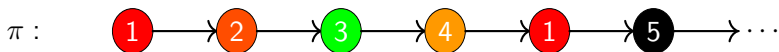
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models \text{red}$?
- ▶ answer: yes

Verification of LTL specs is over linear-time paths

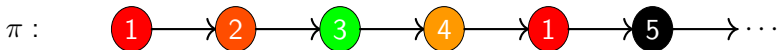
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models \text{○○red}$?

Verification of LTL specs is over linear-time paths

- ▶ back to the traffic light model, consider the following path:

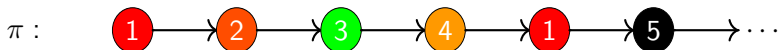


- ▶ question: $\pi \models \text{○○red}$?

- ▶ answer: no

Verification of LTL specs is over linear-time paths

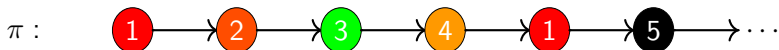
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models \text{red} \text{ U } \text{green}$?

Verification of LTL specs is over linear-time paths

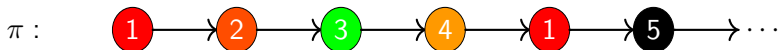
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models \text{red} \text{ U } \text{green}$?
- ▶ answer: yes, because $L(2) = \{\text{red}, \text{amber}\}$

Verification of LTL specs is over linear-time paths

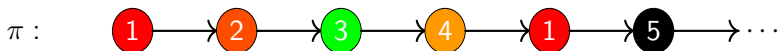
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models \diamond \text{black}$?

Verification of LTL specs is over linear-time paths

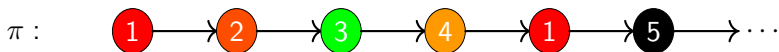
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models \diamond \text{black}$?
- ▶ answer: yes

Verification of LTL specs is over linear-time paths

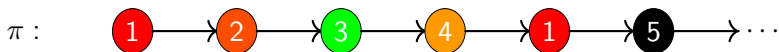
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models \Box \neg \text{red}$?

Verification of LTL specs is over linear-time paths

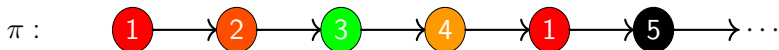
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models \square \neg \text{red}$?
- ▶ answer: no

Verification of LTL specs is over linear-time paths

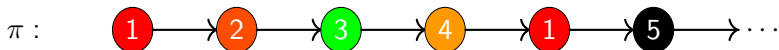
- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models (\diamond \text{black}) \text{ U } (\bigcirc \text{red})$?

Verification of LTL specs is over linear-time paths

- ▶ back to the traffic light model, consider the following path:



- ▶ question: $\pi \models (\diamond \text{black}) \text{ U } (\bigcirc \text{red})$?
- ▶ answer: yes

Expansion laws

- ▶ describe temporal modalities recursively
- 1. formula $\varphi \text{ U } \psi$ is a solution of $k = \psi \vee (\varphi \wedge \text{O}k)$

Expansion laws

► describe temporal modalities recursively

1. formula $\varphi \text{ U } \psi$ is a solution of $k = \psi \vee (\varphi \wedge \text{O}k)$

2. similarly,

$$\diamond\psi = \text{true U } \psi = \psi \vee (\text{true} \wedge \text{O}(\text{true U } \psi)) = \psi \vee \text{O}\diamond\psi$$

Expansion laws

► describe temporal modalities recursively

1. formula $\varphi \text{ U } \psi$ is a solution of $k = \psi \vee (\varphi \wedge \text{O}k)$

2. similarly,

$$\diamond\psi = \text{true U } \psi = \psi \vee (\text{true} \wedge \text{O}(\text{true U } \psi)) = \psi \vee \text{O}\diamond\psi$$

3. also $\square\psi = \neg\diamond\neg\psi = \psi \wedge \text{O}\square\psi$

Weak-Until and PNF

- ▶ weak-until is dual of until:

$$\varphi W \psi = (\varphi U \psi) \vee \Box \varphi$$

- ▶ it holds that

$$\neg(\varphi U \psi) = (\varphi \wedge \neg\psi) W (\neg\varphi \wedge \neg\psi)$$

Definition

Weak-Until Positive Normal Form for LTL: for $a \in AP$

$$\varphi ::= \text{true} \mid \text{false} \mid a \mid \neg a \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \bigcirc \varphi \mid \varphi U \varphi \mid \varphi W \varphi$$

- ▶ each LTL formula admits an equivalent in w-u PNF form

Classes of LTL specifications

- ▶ question: what class of LTL formulas capture *invariants*?

Classes of LTL specifications

- ▶ question: what class of LTL formulas capture *invariants*?
- ▶ answer: $\Box\varphi$, where $\varphi ::= \text{true} \mid a \mid \varphi \wedge \varphi \mid \neg\varphi$

Classes of LTL specifications

- ▶ question: what class of LTL formulas capture *invariants*?
- ▶ answer: $\Box\varphi$, where $\varphi ::= \text{true} \mid a \mid \varphi \wedge \varphi \mid \neg\varphi$
- ▶ example: $\Box\neg\text{red}$

Classes of LTL specifications

- ▶ question: how is the class of *safety properties* characterized?

Classes of LTL specifications

- ▶ question: how is the class of *safety properties* characterized?
- ▶ answer: “nothing bad ever happens”

Classes of LTL specifications

- ▶ question: how is the class of *safety properties* characterized?
- ▶ answer: “nothing bad ever happens”
- ▶ example: “every red light is immediately preceded by amber”
- ▶ question: how can we express this property in LTL?

Classes of LTL specifications

- ▶ question: how is the class of *safety properties* characterized?
- ▶ answer: “nothing bad ever happens”
- ▶ example: “every red light is immediately preceded by amber”
- ▶ question: how can we express this property in LTL?
- ▶ answer: $\neg \text{red} \wedge \square(\bigcirc \text{red} \Rightarrow \text{amber})$

Classes of LTL specifications

- ▶ question: how is the class of *liveness properties* characterized?

Classes of LTL specifications

- ▶ question: how is the class of *liveness properties* characterized?
- ▶ answer: “something good eventually happens”

Classes of LTL specifications

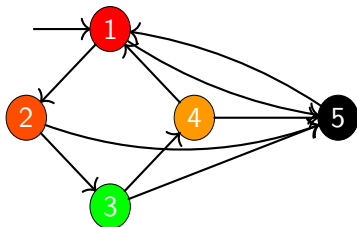
- ▶ question: how is the class of *liveness properties* characterized?
- ▶ answer: “something good eventually happens”
- ▶ example: “the light is infinitely often red”
- ▶ question: how can we express this property in LTL?

Classes of LTL specifications

- ▶ question: how is the class of *liveness properties* characterized?
- ▶ answer: “something good eventually happens”
- ▶ example: “the light is infinitely often red”
- ▶ question: how can we express this property in LTL?
- ▶ answer: $\Box\Diamond\text{red}$

Liveness: an example

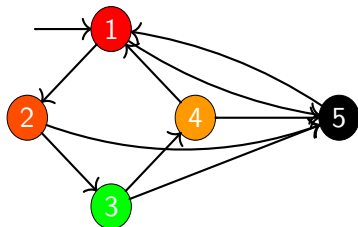
- ▶ consider traffic lights model



- ▶ question: is $\psi := \Box(\text{black} \Rightarrow \Diamond \text{red})$ a liveness property?

Liveness: an example

- ▶ consider traffic lights model



- ▶ question: is $\psi := \Box(\text{black} \Rightarrow \Diamond \text{red})$ a liveness property?
- ▶ answer: yes
- ▶ and in fact $TS \models \psi$

Fairness properties in LTL

- ▶ *unconditional fairness*: “every transition is infinitely often taken”

$$\Box \Diamond \Psi$$

- ▶ *strong fairness*: “if a transition is infinitely often enabled, then it is infinitely often taken”

$$\Box \Diamond \Phi \Rightarrow \Box \Diamond \Psi$$

- ▶ *weak fairness*: “if a transition is continuously enabled from a certain point in time, then it is infinitely often taken”

$$\Diamond \Box \Phi \Rightarrow \Box \Diamond \Psi$$

Fairness properties as LTL constraints

- ▶ consider LTL constraint *fair*;
$$\text{FairPaths}(s) = \{\pi \in \text{Paths}(s) \mid \pi \models \text{fair}\}$$
- $\text{FairPaths}(TS)$

Fairness properties as LTL constraints

- ▶ consider LTL constraint *fair*;
$$\text{FairPaths}(s) = \{\pi \in \text{Paths}(s) \mid \pi \models \text{fair}\}$$

→ $\text{FairPaths}(TS)$

- ▶ consider LTL specification φ ;
$$s \models_{\text{fair}} \varphi \Leftrightarrow \forall \pi \in \text{FairPaths}(s), \pi \models \varphi$$

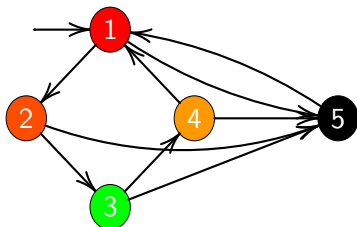
→ $TS \models_{\text{fair}} \varphi$

Fairness properties as LTL constraints

- ▶ consider LTL constraint *fair*;
 $FairPaths(s) = \{\pi \in Paths(s) \mid \pi \models fair\}$
→ $FairPaths(TS)$
- ▶ consider LTL specification φ ;
 $s \models_{fair} \varphi \Leftrightarrow \forall \pi \in FairPaths(s), \pi \models \varphi$
→ $TS \models_{fair} \varphi$
- ▶ fairness constraints are easily embedded with LTL verification:
 $TS \models_{fair} \varphi \Leftrightarrow TS \models (fair \Rightarrow \varphi)$

Fairness: an example

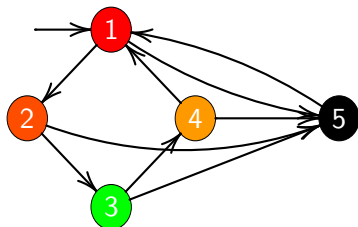
- ▶ consider the traffic lights model



- ▶ question: “is the traffic light infinitely often orange (amber and red)” under the strong fairness condition (if a transition is infinitely often enabled then it is infinitely often taken)?

Fairness: an example

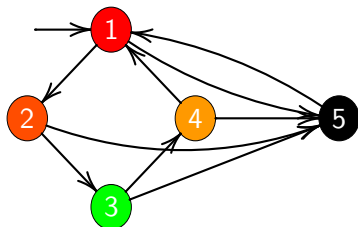
- ▶ consider the traffic lights model



- ▶ question: “is the traffic light infinitely often orange (amber and red)” under the strong fairness condition (if a transition is infinitely often enabled then it is infinitely often taken)?
- ▶ answer: no

Fairness: an example

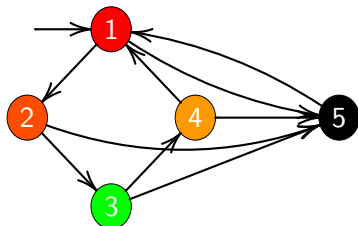
- ▶ consider the traffic lights model



- ▶ question: “is the traffic light infinitely often orange (amber and red)” under the strong fairness condition (if a transition is infinitely often enabled then it is infinitely often taken)?
- ▶ answer: no
- ▶ this fairness condition can be expressed in LTL as:
$$(\Box\Diamond\text{red}) \Rightarrow \Box\Diamond(\text{red} \wedge \bigcirc\text{orange})$$

Fairness: a second example

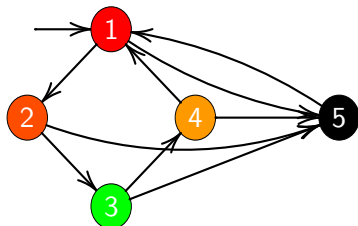
- ▶ consider the traffic lights model



- ▶ question: “is the traffic light infinitely often orange” under the weak fairness condition (if a transition is continuously enabled from a certain point in time then it is infinitely often taken)?

Fairness: a second example

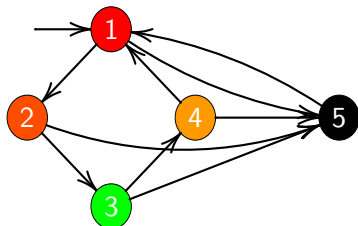
- ▶ consider the traffic lights model



- ▶ question: “is the traffic light infinitely often orange” under the weak fairness condition (if a transition is continuously enabled from a certain point in time then it is infinitely often taken)?
- ▶ answer: yes

Fairness: a second example

- ▶ consider the traffic lights model



- ▶ question: “is the traffic light infinitely often orange” under the weak fairness condition (if a transition is continuously enabled from a certain point in time then it is infinitely often taken)?
- ▶ answer: yes
- ▶ this fairness condition can be expressed in LTL as:
 $(\diamond \square \text{red}) \Rightarrow \square \diamond (\text{red} \wedge \bigcirc \text{orange})$

Expressiveness of LTL

- ▶ question: are there temporal properties that we cannot express in LTL?
- ▶ answer: yes
- ▶ example: “always a state satisfying a can be reached”
- ▶ consider expression

$$\forall \pi \in Paths(TS) : \forall m \geq 0 : \exists \pi' \in Paths(\pi[m]) : \exists n \geq 0 : \pi'[n] \models a$$

- ▶ there does not exist an LTL formula φ so that $TS \models \varphi$

LTL Quiz

- ▶ (semantics of negation)
- ▶ argue why $(TS \not\models \varphi) \neq (TS \models \neg\varphi)$

LTL Quiz

- ▶ (semantics of negation)
- ▶ argue why $(TS \not\models \varphi) \not\equiv (TS \models \neg\varphi)$
- ▶ and why instead $TS \models \neg\varphi \Rightarrow TS \not\models \varphi$

Today's reading material

- ▶ Section 5.1 of
 - ▶ Christel Baier and Joost-Pieter Katoen, *Principles of Model Checking*. The MIT Press. Cambridge, MA, USA. 2008.