

# **Numerical Methods for Astrophysics:**

## **PARTIAL DIFFERENTIAL EQUATIONS (PDEs)**

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# Partial Differential Equations (PDEs). Concept

**PDEs: differential equations that involve more than 1 variable**

**PDEs ARE UBIQUITOUS IN PHYSICS/ASTROPHYSICS**

**Examples:**

– wave equation 
$$-\frac{1}{c^2} \frac{\partial^2 \psi}{\partial t^2} + \nabla^2 \psi = 0$$

– where Laplacian operator in Cartesian coordinates is

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

**Other examples: diffusion equation, Laplace equation, Schrodinger equation, gravitational-wave equation, stellar interior equations**

# Partial Differential Equations (PDEs). Concept

**1. BOUNDARY-VALUE PDE PROBLEMs:**  
we know only boundary conditions

If there is **NO TIME EVOLUTION**, simple case:  
**STATIONARY SOLUTION**

can be solved with **FINITE-DIFFERENCE METHODS (FDMs)**

**2. INITIAL-VALUE PDE PROBLEMs:**  
we know initial conditions

but PDE evolves with time

can be solved with FDMs but requires one more trick

# Partial Differential Equations (PDEs). Boundary-value problem with finite-difference methods (FDMs)

Practical example, Laplace's equation:  $\nabla^2 \phi = 0$

In cartesian coordinates  $\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0$

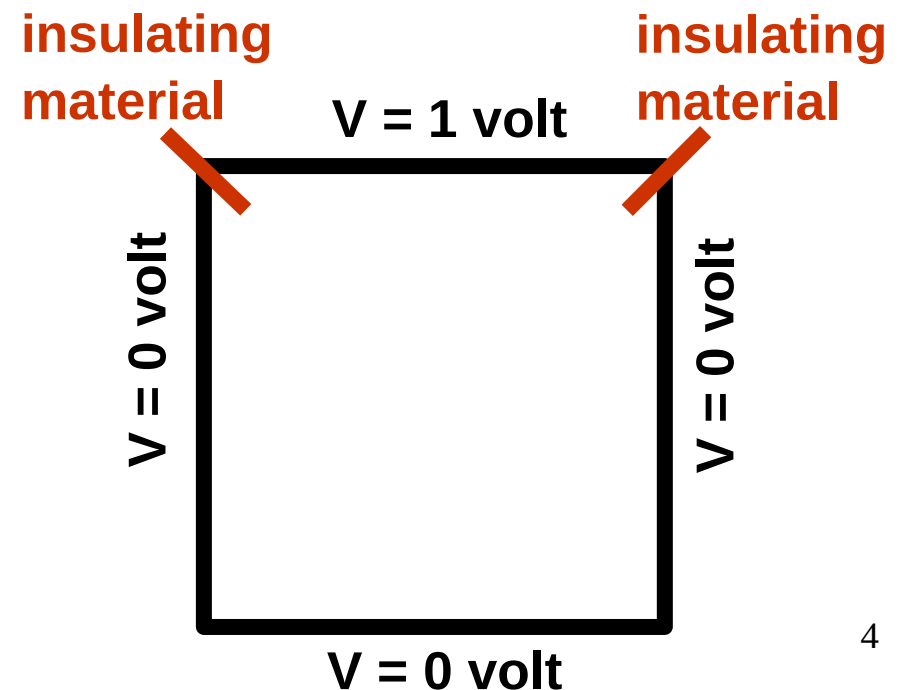
where  $\phi$  is the electrostatic potential in absence of electric charges

**NO TIME DEPENDENCE!**

e.g. the case of a 2-dimensional empty box with conducting walls

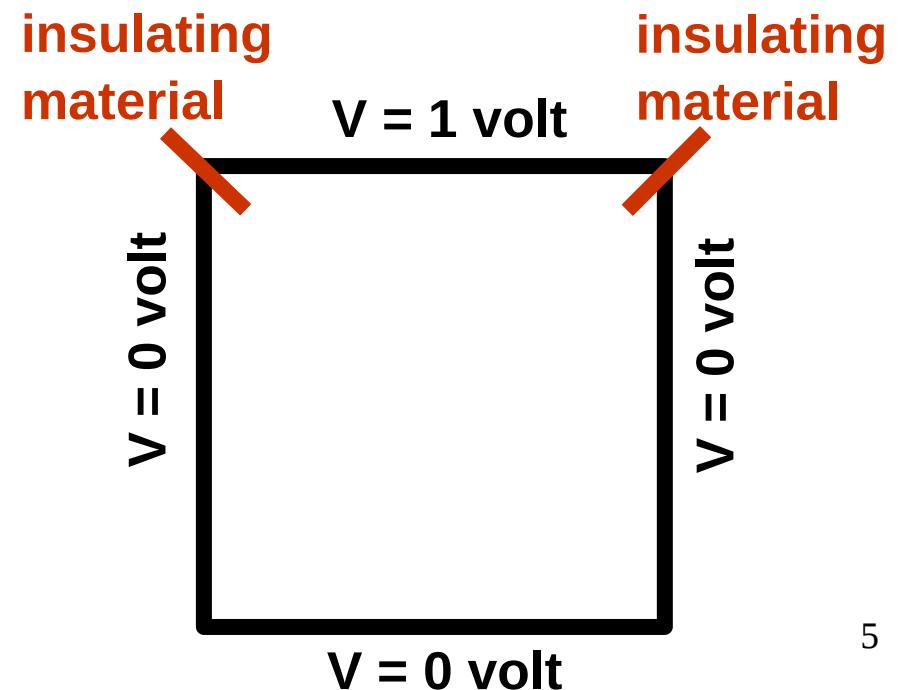
top wall  $V = 1$  volt

other walls (insulated from top wall)  
 $V = 0$  volt



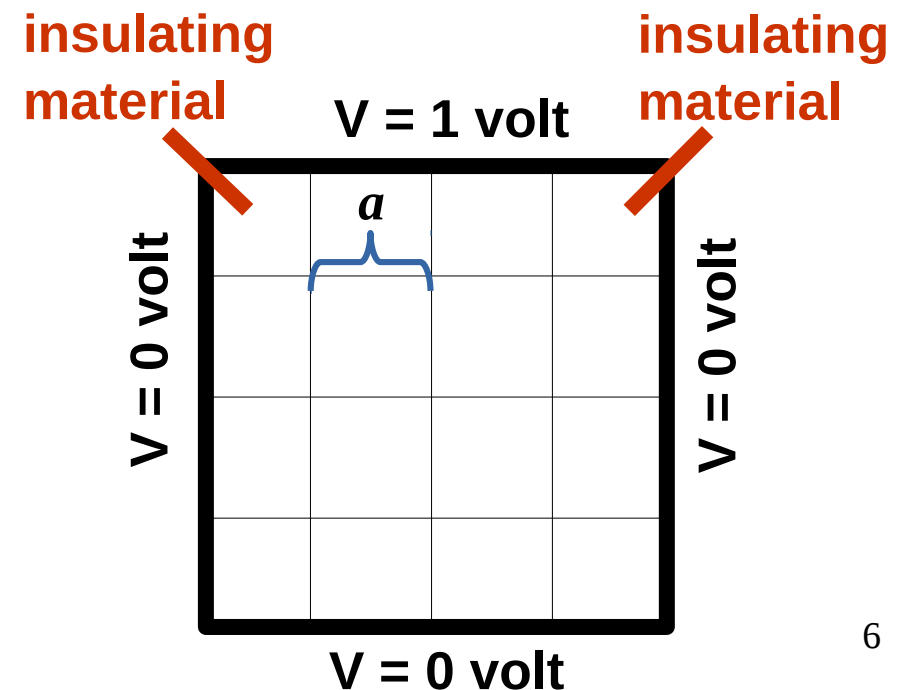
# Partial Differential Equations (PDEs). Boundary-value problem with finite-difference methods (FDMs)

- divide box into a GRID of points separated by  $a$
- $a$  can be fixed or variable – let's make it fixed for simplicity



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- use numerical solution of PARTIAL DERIVATIVES (chapter 7) to rewrite Laplace equation

$$\frac{\partial^2 \phi}{\partial x^2} \simeq \frac{1}{a^2} [\phi(x + a, y) + \phi(x - a, y) - 2\phi(x, y)]$$
$$\frac{\partial^2 \phi}{\partial y^2} \simeq \frac{1}{a^2} [\phi(x, y + a) + \phi(x, y - a) - 2\phi(x, y)]$$

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- substitute these back to the main equation

$$\frac{1}{a^2} [\phi(x + a, y) + \phi(x - a, y) + \phi(x, y + a) + \phi(x, y - a) - 4\phi(x, y)] = 0$$



# Partial Differential Equations (PDEs). Boundary-value problem with finite-difference methods (FDMs)

- remove  $1/a^2$  and reshuffle bringing the term  $\phi(x,y)$  to the left-hand side

$$\phi(x, y) = \frac{1}{4} [\phi(x + a, y) + \phi(x - a, y) + \phi(x, y + a) + \phi(x, y - a)]$$

→ we can derive the value of  $\phi(x,y)$  at any point in the grid, provided that we solve **a set of linear equations**

i.e. solving PDEs with a finite difference method is equivalent to solving systems of linear equations

**WHAT METHOD TO SOLVE LINEAR EQUATIONS CAN WE USE?**

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## WHAT METHOD TO SOLVE LINEAR EQUATIONS CAN WE USE?

We simplified derivatives with NUMERICAL derivatives: our model will always be a huge simplification

→ just go for a **very simple, ITERATIVE APPROACH, like the RELAXATION technique** we have seen for non-linear eqs. (but can be used also for linear eqs, of course) and can be easily generalized to a **system of equations**

# Partial Differential Equations (PDEs). Boundary-value problem with finite-difference methods (FDMs)

- Steps to solve the equations:

1. assign the boundary values  $\phi[0, :] = 1$

$$\phi[M, :] = \phi[0 : M, 0] = \phi[0 : M, M] = 0$$

2. assign to all the other points of the grid a guess value, e.g. zero

$$\phi[i, j] = 0 \quad \text{if } i \neq (0, M) \text{ and } j \neq (0, M)$$

3. solve the equation below by iteration (like relaxation)

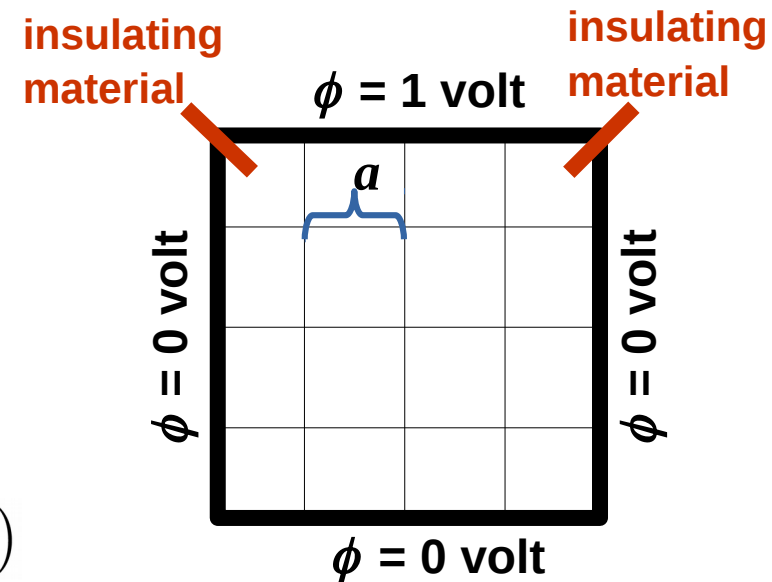
$$\phi(x, y) = \frac{1}{4} [\phi(x + a, y) + \phi(x - a, y) + \phi(x, y + a) + \phi(x, y - a)]$$

or apply the over-relaxation

$$\phi(x, y) = \frac{(1 + \omega)}{4} [\phi(x + a, y) + \phi(x - a, y) + \phi(x, y + a) + \phi(x, y - a)] - \omega \phi(x, y)$$

try with  $\omega = 0.9$  and then reduce  $\omega$  if the result does not converge

$\omega > 0.9$  is often non-stable



# Partial Differential Equations (PDEs). Boundary-value problem with finite-difference methods (FDMs)

Where the relaxation formula comes from?

**Define**  $\Delta\phi(x, y) \equiv \phi_{\text{new}}(x, y) - \phi(x, y)$

**& define**  $\phi_{\omega}(x, y) = \phi(x, y) + (1 + \omega) \Delta\phi(x, y)$

**Combining the two of them:**

$$\phi_{\omega}(x, y) = \phi(x, y) + (1 + \omega) [\phi_{\text{new}}(x, y) - \phi(x, y)]$$

**Expressing in terms of  $\phi_{\text{new}}$ :**  $\phi_{\text{new}}(x, y) = \frac{1}{(1 + \omega)} \phi_{\omega}(x, y) + \frac{\omega}{(1 + \omega)} \phi(x, y)$

**Substituting to the left-hand term of**

$$\phi_{\text{new}}(x, y) = \frac{1}{4} [\phi(x + a, y) + \phi(x - a, y) + \phi(x, y + a) + \phi(x, y - a)]$$

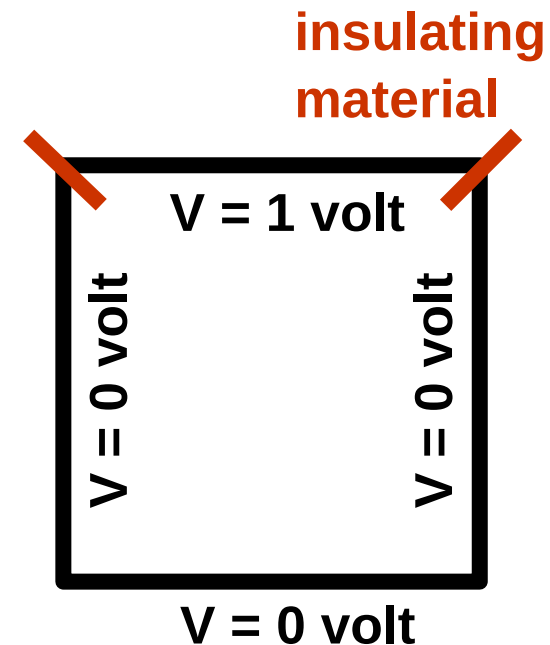
**and rearranging, we get:**

$$\phi_{\omega}(x, y) = \frac{(1 + \omega)}{4} [\phi(x + a, y) + \phi(x - a, y) + \phi(x, y + a) + \phi(x, y - a)] - \omega \phi(x, y)$$

# Partial Differential Equations (PDEs). Exercise

## EXERCISE:

Consider an empty 2D box with conducting walls. The boundary conditions are that one wall is kept at voltage  $V = 1$  volt (for example, the first row of the matrix is kept at voltage  $V = 1$  volt), while the other three walls are insulated from it and are at 0 volts. We want to calculate the potential  $\phi(x, y)$  at each point in the 2D box. Plot the result by using the function `matplotlib.pyplot.imshow()`.



## Partial Differential Equations (PDEs). Exercise

*Suggestions: Require a tolerance  $\delta = 10^{-3}$  (smaller tolerances require a significant computing time). For the definition of tolerance you can use*

```
delta=numpy.linalg.norm(phi-phiold)
```

*where  $\phi$  and  $\phi_{old}$  are the new and the old iteration of the matrix (this treats the two matrices as two vectors and calculates the norm of their difference).*

*Create a grid of  $(M + 1) \times (M + 1)$  cells, with  $M = 100$ . Rows 0 and  $M$  and columns 0 and  $M$  are the walls of the box (i.e. the boundaries) and must be assigned the given voltage. The result should look like Figure 49 and should require  $\approx 3000$  iterations to reach the required tolerance (for the above definition of tolerance).*

# Partial Differential Equations (PDEs). Exercise

*To produce the plot use:*

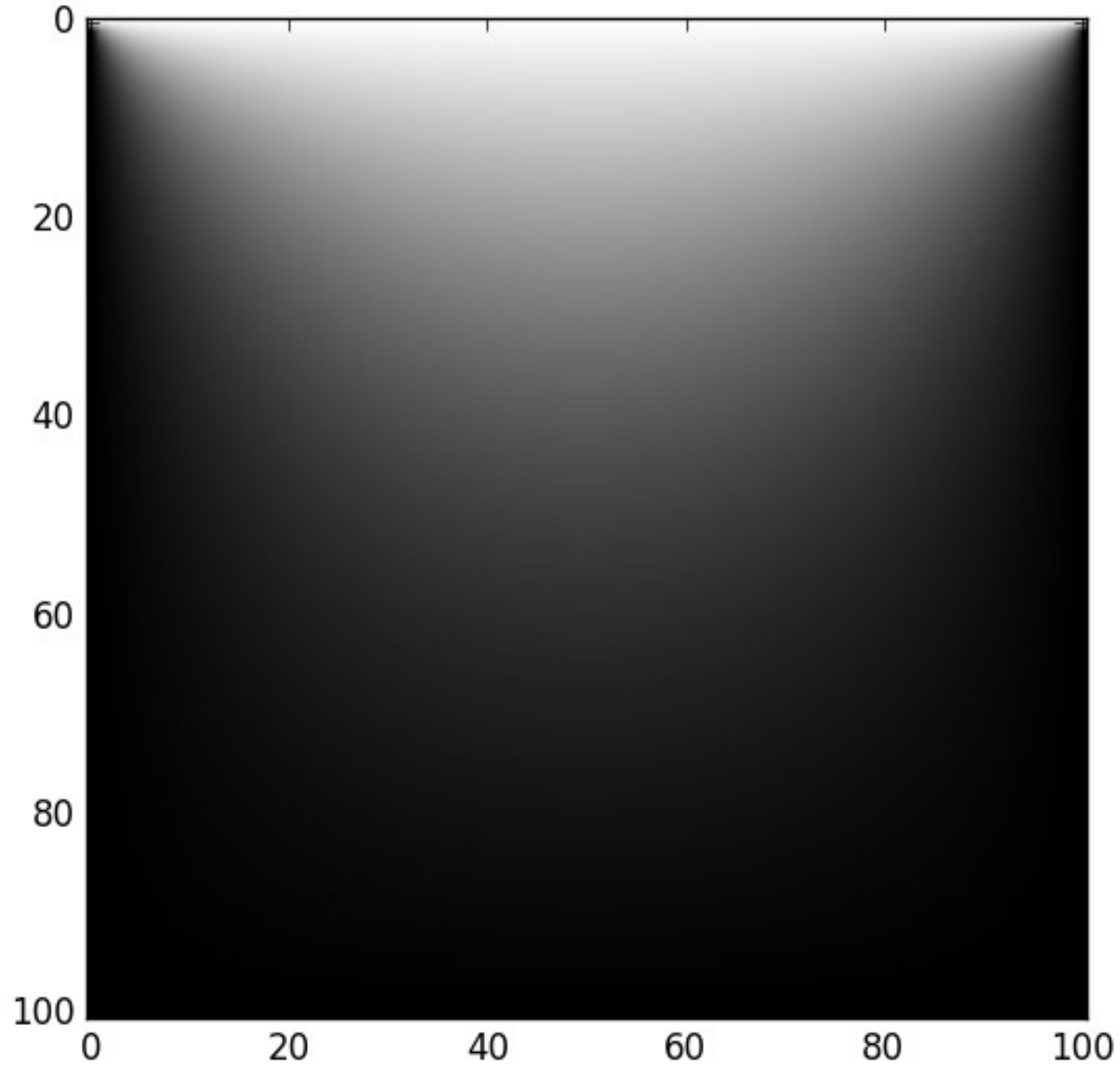
```
import matplotlib.pyplot as plt
plt.imshow(phi) #where phi is the final matrix
plt.gray()
plt.show()
```

Now, solve the same exercise with relaxation, as proposed in equation 233.

$$\phi(x, y) = \frac{(1 + \omega)}{4} [\phi(x + a, y) + \phi(x - a, y) + \phi(x, y + a) + \phi(x, y - a)] - \omega \phi(x, y)$$

*Suggestions: Choose  $\omega = 0.9$  (higher  $\omega$  might be unstable). With  $\omega = 0.9$  you should reach a tolerance of  $\delta = 10^{-3}$  in  $\approx 200 - 300$  iterations. The script is much faster with the **relaxation**.*

# Partial Differential Equations (PDEs). Exercise





# Partial Differential Equations (PDEs). Initial-value PDEs with finite difference methods

**INITIAL-VALUE PDEs:** PDEs for which we know the initial conditions and we must calculate the time evolution of one or more variables.

**Example: One-dimensional DIFFUSION EQUATION**  $\frac{\partial \phi}{\partial t} = D \frac{\partial^2 \phi}{\partial x^2}$

where  $\phi$  is  $\phi(x,t)$  = physical quantity that is diffusing in time and space (e.g. temperature, density of particles, etc)

$D$  = diffusion coefficient

Suppose we know the initial conditions

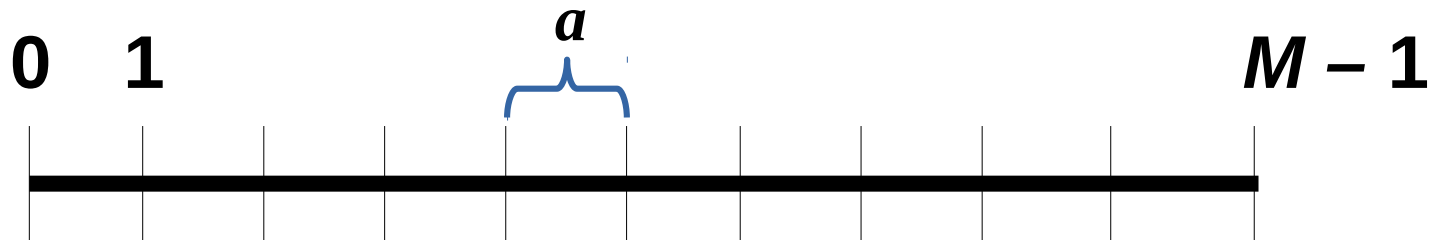
We will try to solve this with the forward-time centered-space (FTCS) method for initial-value PDEs

# Partial Differential Equations (PDEs). FTCS method

- First consider the spatial dependence of  $\phi(x,t)$  and write numerical derivative:

$$\frac{\partial^2 \phi}{\partial x^2} = \frac{\phi(x + a, t) + \phi(x - a, t) - 2\phi(x, t)}{a^2}$$

Where we chose a spatial step  $a$   
and we have gridded our spatial domain into a grid of  $M$  points



# Partial Differential Equations (PDEs). FTCS method

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Where we chose a spatial step  $a$   
and we have gridded our spatial domain into a grid of  $M$  points

- Substitute the above numerical derivative into the diffusion equation:

$$\frac{\partial \phi}{\partial t} = \frac{D}{a^2} [\phi(x + a, t) + \phi(x - a, t) - 2\phi(x, t)]$$

**We have a set of  $M$  ordinary differential equations, one per each point of the spatial grid**

# Partial Differential Equations (PDEs). FTCS method

We must solve a set of ordinary differential equations with one of the methods we learned

**WHICH ONE?**

# Partial Differential Equations (PDEs). FTCS method

We must solve a set of ordinary differential equations with one of the methods we learned

**WHICH ONE?**

A smart option is simply the **EULER'S METHOD**

because

1. we have a very large system of equations to solve
2. we have already done a huge approximation with the numerical derivatives in space

Euler's method equation:  $\phi(x, t + h) \simeq \phi(x, t) + h \frac{d\phi(x, t)}{dt}$

$$\longrightarrow \phi(x, t + h) \simeq \phi(x, t) + h \frac{\partial \phi(x, t)}{\partial t}$$

# Partial Differential Equations (PDEs). FTCS method

Diffusion equation written with finite differences

$$\star \frac{\partial \phi}{\partial t} = \frac{D}{a^2} [\phi(x+a, t) + \phi(x-a, t) - 2\phi(x, t)]$$

Euler's equation:  $\phi(x, t+h) \simeq \phi(x, t) + h \frac{\partial \phi(x, t)}{\partial t}$

Rewrite Euler's equation in terms of  $\partial \phi(x, t) / \partial t$ :

$$\star \frac{\partial \phi(x, t)}{\partial t} \simeq \frac{\phi(x, t+h) - \phi(x, t)}{h}$$

Substitute the eq.  $\star$  into diffusion equation  $\star$

$$\frac{\phi(x, t+h) - \phi(x, t)}{h} \simeq \frac{D}{a^2} [\phi(x+a, t) + \phi(x-a, t) - 2\phi(x, t)]$$

Multiply by  $h$  and nd rewrite in terms of  $\phi(x, t+h)$

$$\phi(x, t+h) \simeq \phi(x, t) + \frac{hD}{a^2} [\phi(x+a, t) + \phi(x-a, t) - 2\phi(x, t)]$$

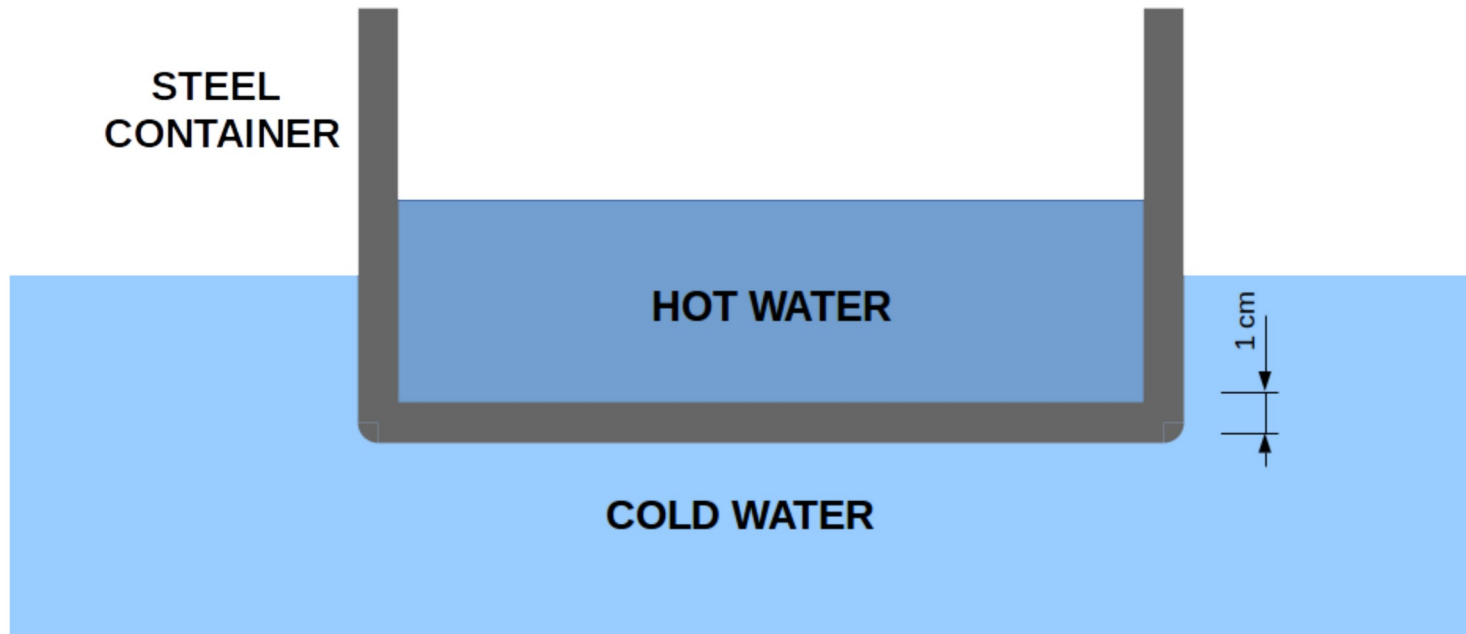
**basic equation of the forward-time centered-space (FTCS) method for initial-value PDEs, applied to diffusion equation.**

# Partial Differential Equations (PDEs). Exercise

## EXERCISE:

Write a python script to solve the diffusion equation with the FTCS method for the following system.

The flat base of a container made of 1 cm thick stainless steel is initially at a uniform temperature of  $T_0 = 293$  K. The container is placed in a bath of cold water at  $T_{\text{bath}} = 273$  K and is filled with hot water at  $T_{\text{hot}} = 323$  K. Calculate the temperature profile of the steel as a function of distance  $x$  from the hot side to the cold side (from 0 to 1 cm) and as a function of time. The system is shown in Figure 50.



# Partial Differential Equations (PDEs). Exercise

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Thermal conduction is described by the diffusion equation as

$$\frac{\partial T}{\partial t} = D \frac{\partial^2 T}{\partial x^2}, \quad (239)$$

where  $D = 4.25 \times 10^{-2} \text{ cm}^2 \text{ s}^{-1}$  for stainless steel. Use equation 238 to solve the problem.

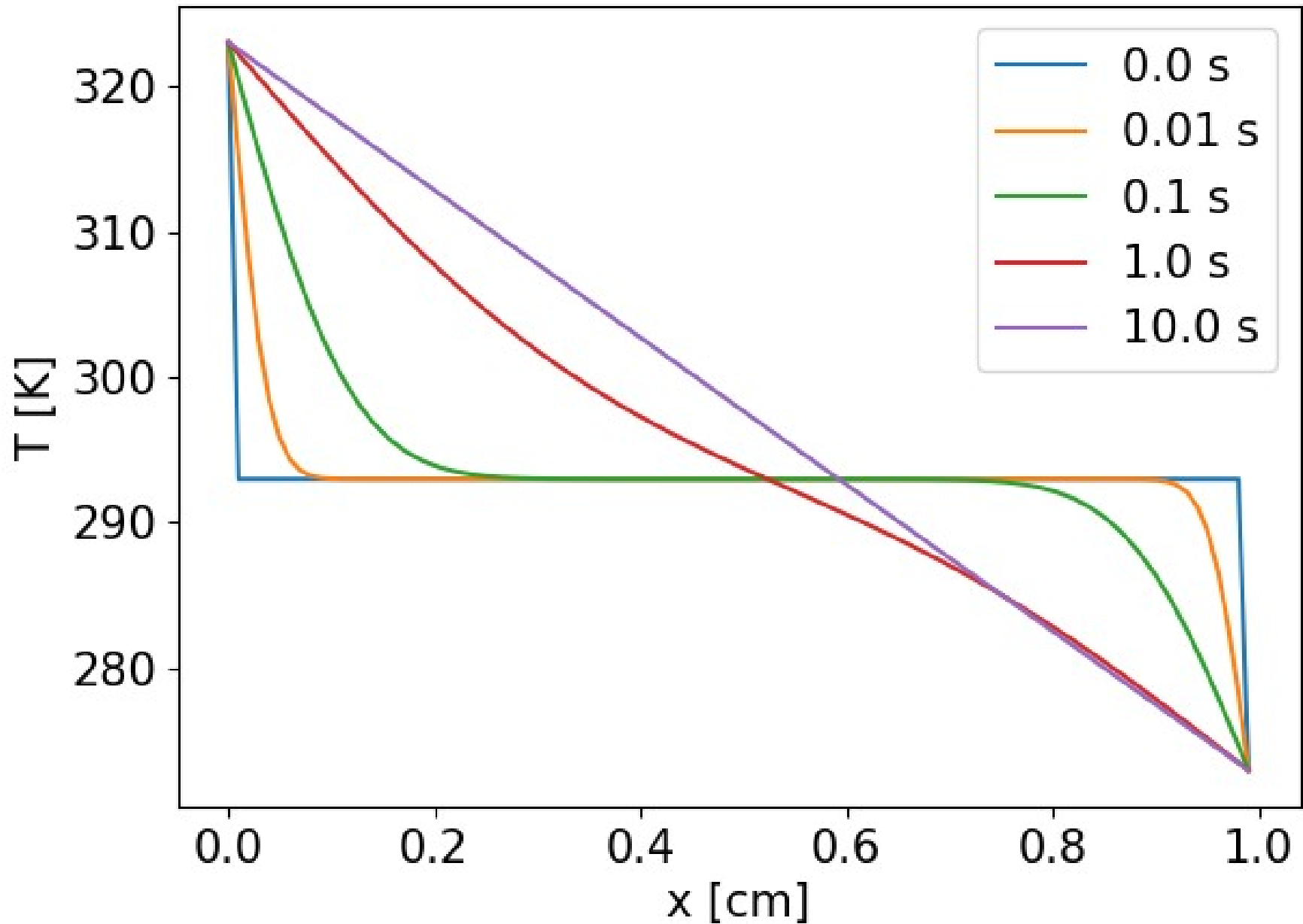
Plot the temperature profile of the steel as a function of  $x$  at four different times  $t = 0.01, 0.1, 1$  and  $10$  s.

The result should look like Figure 51.

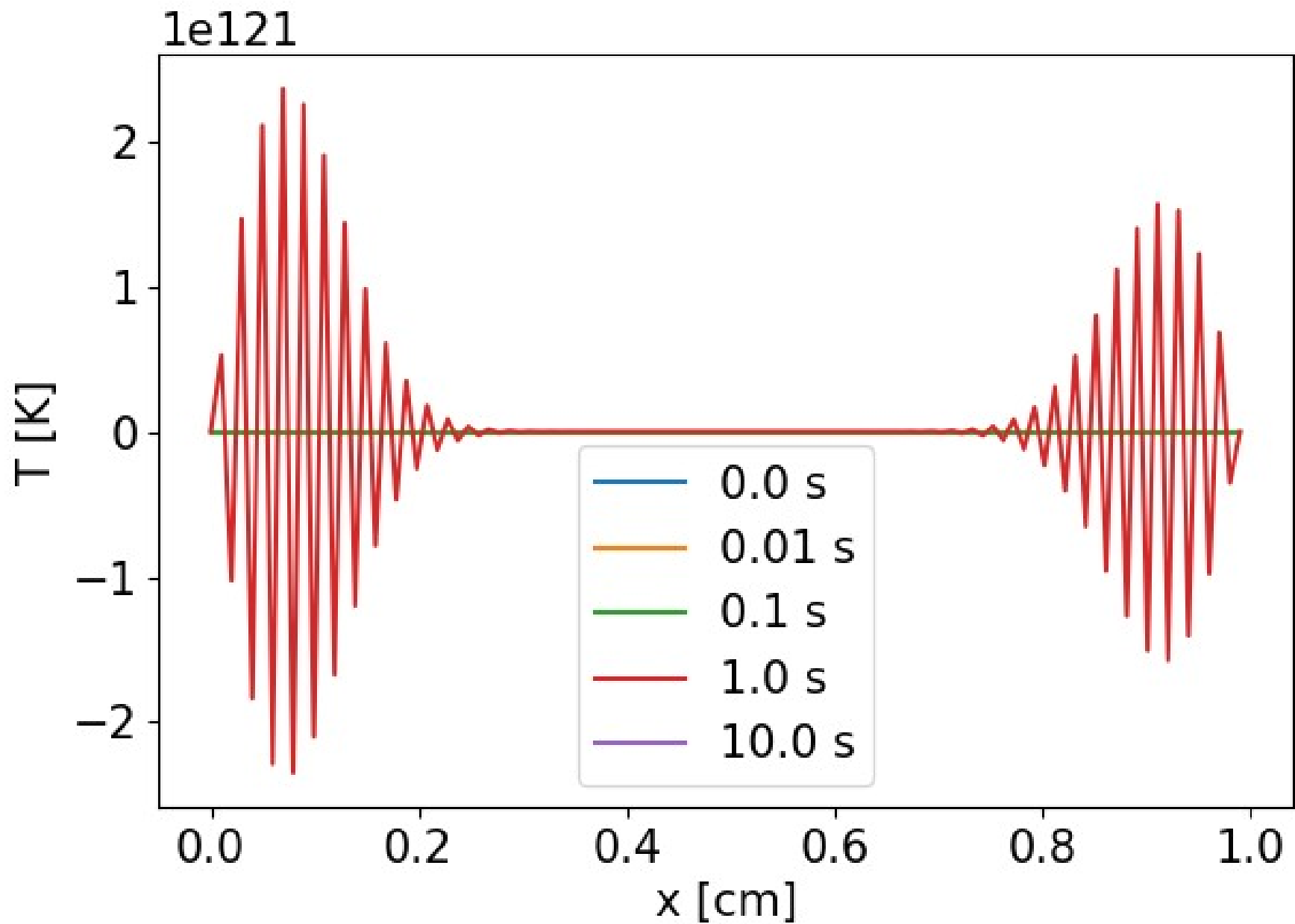
*Suggestion: use a spatial grid with  $M+1$  point, where  $M=100$ . Choose  $h=0.001$ . What happens if you change  $h$  and why?*



# Partial Differential Equations (PDEs). Exercise



# Partial Differential Equations (PDEs). Exercise



# Partial Differential Equations (PDEs). Exercise

## ADDITIONAL SUGGESTIONS for the EXERCISE:

- here you have both spatial step ( $a$ ) and temporal step ( $h$ )
- select spatial step  $a$  as  $a = L/N$   
where  $L$ =length of steel,  $N$ =# of grid points (suggested  $N=100$ )  
In this way **you control the resolution by simply changing  $N$**
- define a constant  **$const=D*h/(a*a)$**  and calculate it just once  
before the loops: you will reduce computing time and numerical errors
- you need **two loops**: an INNER one for the spatial calculation  
an OUTER one for the temporal calculation
- solve **with a loop over the spatial coordinates at each time-step**

$$\phi(x, t + h) \simeq = \phi(x, t) + \frac{h D}{a^2} [\phi(x + a, t) + \phi(x - a, t) - 2 \phi(x, t)]$$

- **SAVE RAM AND DO NOT unnecessarily COMPLICATE THE PROBLEM:**  
phi can be a matrix (over time and spatial position)  
but this requires more RAM + you are not able to generalize in 2D
- define phi as an array with one index for the spatial motion  
You can print the time steps of interest without using a matrix!