

# LECTURE 19, May 16, 2023

confirm: lecture extra schedule: May 31, 12.30  
room 2BC60.

## LINEAR-QUADRATIC DIFFERENTIAL GAMES

$$\dot{y} = Ay + B_1 a + B_2 b, \quad t \leq T, \quad a = a_1 \in \mathbb{R}^{m_1}, \quad b = a_2 \in \mathbb{R}^{m_2}$$

$i=1,2$

$$J^i(x, t, a_1(\cdot), a_2(\cdot)) := - \int_t^T \left[ y(s)^T \frac{M_i}{2} y(s) + \frac{|a_i(s)|^2}{2} \right] ds + y(T)^T \frac{Q_i}{2} y(T)$$

Pre-Hamiltonians:

$$\Phi^A(a, b, x, p_1) = p_1^T (Ax + B_1 a + B_2 b) - \frac{x^T M_1 x}{2} - \frac{|a|^2}{2} \xrightarrow{-\infty} \text{as } |a| \rightarrow +\infty$$

$\Rightarrow \exists$  UNIQUE MAX in  $a$

$$\Phi^B(a, b, x, p_2) = p_2^T (Ax + B_1 a + B_2 b) - \frac{x^T M_2 x}{2} - \frac{|b|^2}{2} =$$

$$= p_2^T B_2 b - \frac{|b|^2}{2} + \text{terms indep. of } b \xrightarrow{-\infty} \text{STR. CONCAVE in } b$$

$\Rightarrow \exists$  UNIQUE MAX in  $b$

$\Rightarrow \left( \arg \max_a \Phi^A, \arg \max_b \Phi^B \right)$  is the UNIQUE NASH  
equil. of  $(\Phi^A, \Phi^B, A, B)$ .

$$D_a \left( p_1^T B_1 a - \frac{|a|^2}{2} \right) = B_1^T p_1 - a = 0 \Leftrightarrow a = B_1^T p_1$$

$u_1^\#(x, p_1) = \text{linear in } p_1, \text{ continuous.}$

$$D_b (P_2^T B_2 b - \frac{|b|^2}{2}) = B_2^T P_2 - b = 0 \Leftrightarrow b = B_2^T P_2 = u_2^\#(x, P_2) \text{ linear in } P_2 \Rightarrow \text{out.}$$

$\Rightarrow$  Hyp # is verified!

Write the system of PDEs

$$\begin{cases} \frac{\partial w_1}{\partial t} + D_x w_1 \cdot (Ax + B_1 \overbrace{B_1^T D_x w_1}^{u_1^\#(P_1)} + B_2 \overbrace{B_2^T D_x w_2}^{u_2^\#(P_2)}) = \frac{x^T M_1 x}{2} + \frac{|B_1^T D_x w_1|^2}{2} \\ \frac{\partial w_2}{\partial t} + D_x w_2 \cdot (\dots) = \frac{x^T M_2 x}{2} + \frac{|B_2^T D_x w_2|^2}{2} \end{cases}$$

$$w_1(x, T) = \frac{x^T Q_1 x}{2}, \quad w_2(x, T) = \frac{x^T Q_2 x}{2}$$

ANSATZ:  $w_i(x, t) = \frac{x^T K_i(t) x}{2} \quad i=1, 2$

$K_i(t) \in \text{Sym}(n)$ ,  $K_i \in C^1$  in time.

$D_x w_i = K_i(t) x$ ,  $\frac{\partial w_i}{\partial t} = \frac{x^T \dot{K}_i(t) x}{2}$   $j = 3-i = \begin{cases} 2 & \text{if } i=1 \\ 1 & \text{if } i=2 \end{cases}$

Plug into the system

$$x^T \frac{\dot{K}_i}{2} x + K_i x \cdot (Ax + \underbrace{B_i B_i^T}_{=: S_i} K_i x + \underbrace{B_j B_j^T}_{=: S_j} K_j x) = \frac{x^T M_i x}{2} + \frac{|B_i^T K_i x|^2}{2}$$

$$\frac{1}{2} x^T K_i B_i B_i^T K_i x = \frac{1}{2} x^T K_i S_i K_i x$$

$$x^T \left( \frac{\dot{K}_i}{2} + \frac{K_i A + A^T K_i}{2} + \underbrace{K_i S_i K_i}_{K_i S_i K_i + K_j S_j K_i} \right) x = x^T \left( \frac{M_i}{2} - \frac{K_i S_i K_i}{2} \right) x \quad \forall x$$

$\Leftrightarrow \dot{K}_i + K_i(A + S_j K_j) + (A^T + K_j S_j) K_i = M_i - K_i S_i K_i \quad i=1, 2$

$$(RDS) \begin{cases} \dot{K}_1 = Q_1 - K_1 S_1 K_1 - \underbrace{K_1 (A + S_2 K_2)}_{\text{coupling terms}} - \underbrace{(A^T + K_2 S_2)}_{\text{coupling terms}} K_1 \\ \dot{K}_2 = Q_2 - K_2 S_2 K_2 - \underbrace{K_2 (A + S_1 K_1)}_{\text{coupling terms}} - \underbrace{(A^T + K_1 S_1)}_{\text{coupling terms}} K_2 \\ K_1(T) = Q_1, \quad K_2(T) = Q_2 \end{cases}$$

Backward Cauchy problem for 2 matrix RICCAT ODES.

Thm. If  $\exists$  sol.  $K_i \in C'((t_0, T), \text{Sym}(n))$ , cont. at  $t=T$ ,  $i=1, 2$  of (RDS) in  $(t_0, T)$ . Then  $w_i(x, t) = \frac{x^T K_i(t) x}{2}$  solve

the system of HJB equations in the Verif. Thm. &

$u_i^*(x, t) = B_i^T K_i(t) x$   $i=1, 2$  form a Nash equil. for the LQ diff. game.

Moreover such sol.  $K_i \exists$  for some  $t_0 < T$ .

Proof. We saw  $u_i^*(p_i) = B_i^T p_i$ ,  $D_x w_i = K_i(t) x \Rightarrow$  candidate Nash feedback equil. are  $u_i^*(x, t) = B_i^T K_i(t) x$ .

Is it an admissible pair of feedbacks? The system

becomes

$$\begin{cases} \dot{y}(t) = A y(t) + B_1 B_1^T K_1(t) y(t) + B_2 B_2^T K_2(t) y(t) \\ y(t) = x \end{cases} \quad \text{linear (non-autonomous) homogen. system of ODES.}$$

$\Rightarrow \forall x \in \mathbb{R}^n, t \in (t_0, T)$  it has a unique sol. in  $(t_0, T]$ .

$\Rightarrow (u_1^*, u_2^*)$  is admissible  $\xrightarrow{\text{Verif. Thm.}}$  it is a NASH EQ.

Last thing. (RDS) has a sol. : use local  $\exists$  thm for ODES,

must check  $K_i(t) \in \text{Sym}(n) \forall t$ .

HW: check  $K_1^T, K_2^T$  solves (RDS)  $\Leftrightarrow K_i^T = K_i$   $i=1,2$ .

0-SUM DIFF. GAMES.

$$\begin{cases} \dot{y} = f(y, a, b) \\ y(t) = x \end{cases} \quad J = \int_t^T \ell(y(s), a(s), b(s)) ds + g(y(T))$$

A maximises  $J$ , B min  $J$ . Special

case of the general one:  $\ell_A = \ell$ ,  $\ell_B = -\ell$ ,  $g_A = g$ ,  $g_B = -g$

Simplified Pre-Hamiltonian:

$$\bar{\Phi}(a, b; x, p) = p \cdot f(x, a, b) + \ell(x, a, b)$$

Hypothesis  $\#$   $b$ 's:  $\exists (u_1^\#, u_2^\#): \mathbb{R}^n \times \mathbb{R}^n \rightarrow A \times B$  CONTINUOUS  
 $(x, p) \mapsto (u_1^\#, u_2^\#)(x, p)$

a SADDLE point of the 0-sum game  $(A, B, \bar{\Phi})$ .

$(x, p)$  parameters, i.e.

$$u_1^\#(x, p) \in \arg \max_a \bar{\Phi}(a, u_2^\#; x, p)$$

$$u_2^\#(x, p) \in \arg \min_b \bar{\Phi}(u_1^\#, b; x, p)$$

Def.  $(u_1^*, u_2^*)$  admissible feedbacks is a SADDLE POINT for the diff. game starting at  $(x, t)$  if.

$$J(x, t; u_A^*, u_2^*) \leq J(x, t; u_1^*, u_2^*) \leq J(x, t; u_1^*, u_B^*)$$

$\forall (u_A^*, u_2^*)$  admiss.

$\forall (u_1^*, u_B^*)$  admiss.

Cor. (Verification thm. for 0-sum d.g.) Supp.  $\exists w \in C^1((t_0, T))$

cont. at  $t=T$  solution of

(IE) Isaacs eq.  $\left\{ \begin{array}{l} \frac{\partial w}{\partial t} + D_x w \cdot f(x, u_1^\#, u_2^\#) + l(x, u_1^\#, u_2^\#) = 0 \\ u_i^\# = u_i^\#(x, D_x w) \\ w(x, T) = g(x) \end{array} \right. \quad \text{and}$

$(u_1^*, u_2^*)(x, t) = (u_1^\#(x, D_x w(x, t)), u_2^\#(x, D_x w(x, t)))$  is a pair

of admissible feedbacks  $\Rightarrow (u_1^*, u_2^*)$  is a SADDLE POINT of D.G. among admiss. feedbacks.

Pf. Use Verif. thm. for Nash equil.  $w_1 = w, w_2 = -w$

CLAIM:  $(w_1, w_2)$  solves the HJ system of the general

case: Eq. 1

$$\frac{\partial w_1}{\partial t} + \max_a \{ D_x w_1 \cdot f(x, a, u_2^\#) + l(x, a, u_2^\#) \} = 0$$

is satisfied because  $u_1^\# \in \arg \max_a \{ l(a, u_2^\#; x, D_x w) \}$  by #1's.

Eq. 2 Take - (IE)

$$-\frac{\partial w}{\partial t} - D_x w \cdot f - l(\cdot) = 0$$

$\underbrace{\quad\quad\quad}_{\frac{\partial w_2}{\partial t}} \quad \underbrace{\quad\quad\quad}_{D_x w_2} \quad \underbrace{\quad\quad\quad}_{l_B}$

$$\Rightarrow \frac{\partial w_2}{\partial t} + D_x w_2 \cdot f(x, u_1^\#, u_2^\#) + l_B(x, u_1^\#, u_2^\#) = 0$$

\$ by Ass. # bis. :

$$u_2^\# \in \arg \min_b \left\{ \underbrace{D_x w}_- \cdot f(x, u_1^\#, b) + \underbrace{l(x, u_1^\#, b)}_- \right\}$$

$$= \arg \max_b \left\{ D_x w_2 \cdot f(x, u_1^\#, b) + l_B(x, u_1^\#, b) \right\}$$

\$\Rightarrow\$ \$w\_2\$ satis. 2<sup>nd</sup> eq. of the system for Nash equil.  
 Gen. Verif. thm. \$\Rightarrow\$ \$(u\_1^\#, u\_2^\#)\$ admi. is also a Nash Equil.

\$\Rightarrow\$ \$(u\_1^\#, u\_2^\#)\$ is a saddle of the 0-sum diff. game.

### COMMENTS ON ISAACS' EQUATION.

$$\Phi = p \cdot f(x, a, b) + l(x, a, b)$$

$$\text{Hyp \# bis} \Rightarrow \Phi(u_1^\#, u_2^\#; x, p) =$$

$$= \max_a \min_b \Phi(a, b; x, p) = \min_b \max_a \Phi(a, b; x, p)$$

(I) \$\xrightarrow{a}\$ Isaacs' condition.

(IE) can be re-written as (I1)

$$\frac{\partial w}{\partial t} + \max_a \min_b \left\{ D_x w \cdot f(x, a, b) + l(x, a, b) \right\} = 0$$

and a

$$\frac{\partial w}{\partial t} + \min_b \max_a \left\{ \dots \right\} = 0 \quad \text{(I2)}$$

Remark # bis \$\Rightarrow\$ (I) (I2)

\$\bullet\$ (I1) and (I2) are upper & lower Isaacs' eqs.

they coincide if (I).

Application 1: L-Q, 0-sum diff games.

$$\dot{y} = Ay + B_1 a + B_2 b \quad B_1 \in \mathbb{M}_{n \times m_1}, \quad B_2 \in \mathbb{M}_{n \times m_2}$$

$$a(\cdot) \in L^2([0, T], \mathbb{R}^{m_1}), \quad b(\cdot) \in L^2([0, T], \mathbb{R}^{m_2})$$

$$J = - \int_t^T \left( y(s)^T \frac{M}{2} y(s) + \frac{|a(s)|^2}{2} - \frac{|b(s)|^2}{2} \right) ds + y(T)^T \frac{Q}{2} y(T)$$

$M, Q \in \text{Sym}(n)$ . 1st player MAXes, 2nd pl. MINes.

Ex HW check. Hyp #bis holds, compute  $u_1^\#, u_2^\#$

•  $w(x, t) = x^T K(t) x$  solves (IE)  $\Leftrightarrow$  K sat.

$$(RDE-02) \quad \begin{cases} \dot{K} = M - KA - A^T K + K(B_2 B_2^T - B_1 B_1^T) K \\ K(T) = 0 \end{cases}$$

Q:  $\exists$  unique sol of  $\uparrow$  in  $[0, T]$ ?

Cor If  $Q \geq 0$ ,  $M \leq 0$ ,  $B_2 B_2^T - B_1 B_1^T \geq 0 \Rightarrow (RDE-02)$  has a sol  $w \in C^1((-\infty, T], \text{Sym}(n)) \Rightarrow$  diff. game has a saddle among admissible feedbacks  $\forall$  initial  $t \leq T$ .

Pf Use the thm. for opt. control: it's enough to check  $\exists B : \underbrace{B_2 B_2^T - B_1 B_1^T}_N = B B^T$  "B square root of N"

this is true because  $N \geq 0$ .  $\square$

## Application 2 A model of ADVERTISING in a DUOPOLY

Ref [Jorgensen-Zaccour],  $y_1, y_2 \in [0, 1]$  are the % of market of 2 firms in competition.

ASS.: DUOPOLY  $y_1 + y_2 = 1$   $\alpha_i =$  advertising effort of firm  $i$

Dynamics (Lanchester dgl.)

$$\dot{y}_i = \alpha_i (1 - y_i) - \alpha_j y_i \quad i = 1, 2$$

Payoff = Income  $J^i(x, t; \alpha_1, \alpha_2) = \int_t^T \left( y_i z_i - \frac{\alpha_i^2}{2} \right) ds + R_i y_i(T)$

$z_i =$  unitary price  $> 0$

$$R_i \geq 0$$

$$\alpha_i \geq 0$$

HW. Reformulate it as a 0-sum game  $y = y_1$ ,  $y_2 = 1 - y$  Find:  $J = \dots$

- Write pre-Ham.  $\Phi$ , check Hyp. # bis & compute  $u_i^{\#}$  (Hint: treat separately  $p \geq 0$  &  $p \leq 0$ )
- Look for solution of (IE)  $\rightarrow$  it is reasonable to restrict to  $w_x \geq 0$ , so (IE) simplifies
  - ▶ Ansatz:  $w(x, t) = k(t)x + c(t)$ , find a system of ODEs for  $k, c$  that can be solved explicitly.