

# Linear Quadratic and Linear State games

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## Desirable characteristics:

- Analytical tractability
- Time consistency

## Special structures:

- Linear-Quadratic (LQ)
- Linear-State (LS)
- Exponential (E) – can be transformed into (LS)

## Linear dynamics and quadratic payoff functions

Ex: 2 players

$$\min J^1 = \frac{1}{2} \int_0^T e^{-rt} [g_1(x(t))^2 + g_2(u_1(t))^2] dt + \alpha_1(x(T))^2$$

$$\min J^2 = \frac{1}{2} \int_0^T e^{-rt} [m_1(x(t))^2 + m_2(u_2(t))^2] dt + \alpha_2(x(T))^2$$

$$\dot{x}(t) = a(t)x(t) + b(t)u_1(t) + c(t)u_2(t)$$

$$x(0) = 0$$

$$u_1(t), u_2(t) \in \mathcal{R}$$

Observation: Here there are homogeneous cost functions just to simplify computation

# Equilibria for LQ games

- **Analytical tractability**

OLNE and MNE easy to be obtained analytically

- **Time consistency**

OLNE NOT subgame perfect

MNE subgame perfect

Bressan (2011)

Dockner (2000)

Engwerda (2005) - LQ Dynamic Optimization and Differential Games

# OLNE for LQ game: Example (constant coefficients)

$$\begin{aligned}H_1^C(x, u_1, p_1, t) &= -\frac{1}{2}(g_1x^2 + g_2u_1^2) + p_1(ax + bu_1 + cu_2) \\H_2^C(x, u_1, p_1, t) &= -\frac{1}{2}(m_1x^2 + m_2u_2^2) + p_1(ax + bu_1 + cu_2)\end{aligned}$$

If  $T < +\infty$   $p_1(T) = 0$ ,  $p_2(T) = 0$

$\max_{u_i \in \mathcal{R}} H_i^C$

$$u_1(t) = \frac{b}{g_2}p_1(t) \quad u_2(t) = \frac{c}{m_2}p_2(t)$$

$$\dot{p}_1(t) = \frac{\partial H_1^C}{\partial x} = g_1x(t) + (r - a)p_1(t)$$

$$\dot{p}_2(t) = \frac{\partial H_2^C}{\partial x} = m_1x(t) + (r - a)p_2(t)$$

# Canonical System

$$\left\{ \begin{array}{l} \dot{x}(t) = ax(t) + \frac{b^2}{g_2}p_1(t) + \frac{c^2}{m_2}p_2(t), \quad x(0) = 0 \\ \dot{p}_1(t) = g_1x(t) + (r-a)p_1(t), \quad p_1(T) = 0 \\ \dot{p}_2(t) = m_1x(t) + (r-a)p_2(t), \quad p_2(T) = 0 \end{array} \right.$$
$$\underbrace{\begin{pmatrix} \dot{x} \\ \dot{p}_1 \\ \dot{p}_2 \end{pmatrix}}_Y = \underbrace{\begin{pmatrix} a & b^2/g_2 & c^2/m_2 \\ g_1 & r-a & 0 \\ m_1 & 0 & r-a \end{pmatrix}}_A \underbrace{\begin{pmatrix} x \\ p_1 \\ p_2 \end{pmatrix}}_Y$$

can be solved analitically

$$\det(A - \lambda I) = (\lambda - r + a)^2(\lambda - a) - (\lambda - r + a)M = 0$$

$$\text{where } M = c^2(m_1/m_2) + b^2(g_1/g_2) > 0$$

$$Y = \sum_{i=1}^3 v_i e^{\lambda_i t}$$

$$\lambda_1 = \frac{r}{2} - \sqrt{\frac{r^2}{4} - a(r-a) + M}$$

$$\lambda_2 = \frac{r}{2} + \sqrt{\frac{r^2}{4} - a(r-a) + M} > 0$$

$$\lambda_3 = r - a$$

$$x(t) = h(g_1, g_2, m_1, m_2, x_0)$$

OLNE

$$(\Phi_1, \Phi_2) = \left( \frac{b}{g_2} \frac{w_{21}}{w_{11}} e^{\lambda_1 t} x_0, \frac{c}{m_2} \frac{w_{21}}{w_{31}} e^{\lambda_1 t} x_0 \right)$$

it is NOT markovian , NOT subgame perfect

See paper Li Yu et al "A new feedback form of open-loop stackelberg strategy in a general linear-quadratic differential game." (2022)

# MNE for LQ games

Hamilton Jacoby Bellman equation turns out to be quadratic in  $x$

**Quadratic value function:**

Homogeneous case:

$$V_i(x, t) = \frac{1}{2} v_i(t) x^2 \text{ if } T < +\infty$$

$$V_i(x, t) = \frac{1}{2} v_i x^2 \text{ if } T = +\infty$$

Non Homogeneous case:  $V(x, t) = x^2 + \beta(t)x + \gamma(t)$

Linear feedback strategies

$$(\Phi_1(x, t), \Phi_2(x, t)) = \left( \frac{b}{g_2} v_1(t) x, \frac{c}{m_2} v_2(t) x \right)$$



## Definition (Linear - State games)

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$$J^i = \int_0^T e^{-rt} L_i(x(t), u_1(t), u_2(t), t) dt + e^{-rT} S_i(x(T))$$

$$\dot{x}(t) = f(x(t), u_1(t), u_2(t), t)$$

Define  $\tilde{H}_i(x, u_1, u_2, p_i, t) = L_i(x(t), u_1, u_2, t) + p_i f(x(t), u_1, u_2, t)$

i)

$$\frac{\partial^2 \tilde{H}_i}{\partial x^2}(x, u_1, u_2, p_i, t) = 0, \quad \frac{\partial S_i(x)}{\partial x^2} = 0$$

ii)

$$\frac{\partial \tilde{H}_i}{\partial u_i}(x, u_1, u_2, p_i, t) = 0, \Rightarrow \frac{\partial^2 \tilde{H}_i}{\partial u_i \partial x}(x, u_1, u_2, p_i, t) = 0$$

## Proposition (Sufficient conditions)

*If there is no multiplicative interaction between the state  $x(t)$  and the controls  $u_i(t)$ , then the game is Linear-State*

$$\frac{\partial^2 \tilde{H}_i}{\partial u_1 \partial x}(x, u_1, u_2, p_i, t) = \frac{\partial^2 \tilde{H}_i}{\partial u_2 \partial x}(x, u_1, u_2, p_i, t) = 0 \Rightarrow \text{Linear State}$$

### Example:

$$L_i(x(t), u_1, u_2, t) = c_i(t)x(t) + k(u_1(t), u_2(t), t)$$

$$\dot{x}(t) = A(t)x(t) + g_1(u_1(t), u_2(t), t) = f(x(t), u_1, u_2, t)$$

$$S_i(x) = W_i x \text{ Linear in } x$$

# Linear state game: Sufficient conditions example

$x(t)$  stock of knowledge

$u_i(t)$  investment of player  $i$  in public knowledge

$$\dot{x}(t) = u_1(t) + u_2(t) - ax(t)$$

$$\max J_i = \int_0^T e^{-rt} [x(t) - k_i(u_i(t))] dt + e^{-rT} W_i x(T)$$

$$\tilde{H}_i(x, u_1, u_2, p_i, t) = x - k_i(u_i) + p_i(u_i + u_j - ax)$$

$$\frac{\partial \tilde{H}_i}{\partial u_i} = -k'_i(u_i) + p_i \quad \Rightarrow \quad k'_i(u_i) = p_i(t)$$

marginal cost of investment = marginal utility

$$\dot{p}_i(t) = -\frac{\partial \tilde{H}_i}{\partial x} + rp_i(t) = -1 + (a+r)p_i(t) \Rightarrow p_i(t) = Me^{(a+r)t} + \frac{1}{a+r}$$

**OLNE subgame perfect**

# Linear state game: Not Necessary conditions example

2 Firms producing durable goods.

$s_i(t)$  sales of firm  $i$        $X_i(t)$  accumulated sales of firm  $i$  up to time  $t$

$$\dot{X}_i(t) = s_i(t) = \alpha_i(t)(M - X_1(t) - X_2(t))$$

Assuming  $\alpha_i$  depend on price strategies  $u_i(t)$  and defining the state of the game  $x(t) = M - X_1(t) - X_2(t)$

$$\dot{x}(t) = -[\alpha_1(u_1(t), u_2(t)) + \alpha_2(u_1(t), u_2(t))]x(t)$$

Payoffs

$$J_i = \int_0^T e^{-rt} [u_i(t) - c_i] \cdot x(t) - \alpha_i(u_1(t), u_2(t))(M - x_1(t) - x_2(t)) dt$$

$$\frac{\partial \tilde{H}_i^2}{\partial x^2} = 0 \text{ It is linear state}$$

**BUT**

$$\frac{\partial \tilde{H}_i^2}{\partial u_i \partial x} \neq 0 \text{ there is a multiplicative term between } u_i \text{ and } x$$

# Linear State games

There may be a multiplicative interaction between the state variable of player  $i$ ,  $x_i$  and the control variables of player  $j$ ,  $u_j$ .

And still get a Markov perfect open-loop Nash Equilibrium.

See Example 7.3 Dockner page 191

In Linear State games OLNE  $\equiv$  Markov Perfect

Enjoy with differential games

Enjoy with your research

**Find the equilibria of your life!**