D $\square$

# Introduction to differential games 

PhD Program in Mathematical Sciences

Buratto Alessandra
buratto@math.unipd.it

## Course contents <br> (12 hours)

- Recall of basic concepts of game theory, best response strategies, dominating strategies, Nash equilibrium
- Dynamic games: formalization of a differential game
- Simultaneous Noncooperative differential games (Nash equilibrium)
- Hierarchic differential games (Stackelberg equilibrium)


## References

- Basar T., and Olsder G.J., Dynamic Noncooperative Game Theory Classics in Applied Mathematics.. SIAM 2 Ed., 1999.
- Dockner, E.J. et al., Differential Games in Economics and Management Science, Cambridge University Press, 2000.
- Van Long, N., A Survey of Dynamic Games in Economics Surveys on Theories in Economics and Business Administration, Vol. 1, 2010.
- Bressan, A. "Noncooperative differential games." Milan Journal of Mathematics 79.2 (2011) 357-427.
- Jehle, G. A. and Reny P.J., Advanced Microeconomic Theory (Third). Essex: Pearson Education Limited, 2011.
- Haurie, A., et al, Games and dynamic games. Vol. 1 World Scientific Publishing Company, 2012.


## Exam

1. The lecturer will suggest a set of recent scientific publications on differential games
2. Each student will choose a paper among the suggested ones to read, comprehend and present in class

# Introduction to game theory 

Buratto Alessandra

# Game theory 

Quantitative methods
for strategic interactions
among entities

## Motivations

```
MILITARY
ECONOMICS - MARKETING
ECONOMICS - FINANCE POLITICS
SPORT
SOCIOLOGY
MEDICINE-BIOLOGY
PSICOLOGY
ENVIRONMENT
```

Gulf war,...
Advertising, Promotion, Price, ...
Portfolio Management
Voting systems,...
Attack / Defense Strategies
Migration, ...
Neurons, Bacterial evolution
Prisoners' dilemma, ...
Pollution, Kyoto cartel, ...

## A little bit of history

| 1928 | von Neumann | Minimax Theorem |
| :--- | :--- | :--- |
| 1940 | von Neumann, Turing, Zu | Computer $\rightarrow$ MILITARY |
| 1944 | von Neumann, Morgenstern | The Theory of Games and Economic <br> Behavior $\rightarrow$ ECONOMICS |
| 1950 | Nash | Equilibrium \& Bargaining |
| 1951 | Isaacs | Differential games |
| 1953 | Nash, Gillies, Shapley | Threat Core Value |
| 1957 | Bellmann | Dynamic programming (DP) |
| 1962 | Pontryagin | Pontryagin ‘s Maximum Principle (OC) |

## Nobel prizes in Economics

| 1994 | John F. Nash Jr. John Harsanyi Reinhard Seltens | $\left\{\begin{array}{l} \text { PERFECT } \\ \text { EQUILIBRIUM } \end{array}\right.$ |
| :---: | :---: | :---: |
| 2005 | Y. Robert J. Aumann Thomas C. Schelling | $\left\{\begin{array}{l} \text { COOPERATION \& } \\ \text { CONFLICT } \end{array}\right.$ |
| 2007 | Roger Myerson Leonid Hurwicz Eric Maskin | $\left\{\begin{array}{l} \text { MECHANISM } \\ \text { DESIGN } \end{array}\right.$ |
| 2012 | Lloyd Shapley Alvin Roth | $\left\{\begin{array}{l} \text { MARKET DESIGN \& } \\ \text { STABLE ALLOCATIONS } \end{array}\right.$ |
| 2014 | Jean Tirole | \} MARKET REGULATIONS |

## Our logical thread



## From Mathematical programming to Game Theory

\[

\]

| Two decision makers P1, P2 |  |
| :---: | :---: |
| $\max _{u 1} J(u 1, u 2)$, | $u 1 \in U 1$ |
| $\max _{u 2} J(u 1, u 2)$, | $u 2 \in U 2$ |

## Game

## Basic elements:

- Players with clear preferences, represented by a Payoff function.
- Each Action leads to an associated Consequence


## Axioms:

- Players are rational:

They are aware of their alternatives, forms expectations about any unknowns, have clear preferences, and choose their action deliberately after some process of optimization.

- And think strategically.

When designing his strategy for playing the game, each player takes into account any knowledge or expectation he may have regarding his opponents' behaviour.

## Rational Behavior

A Set of Actions from which the decision-maker makes a choice.
C Set of possible Consequences of these actions.
J: A --> C

Consequence function that associates a Consequence with each Action.

Preference relation (a complete transitive reflexive binary relation) on C .

## Static games (One-shot games)

- Each player makes one choice and this completely determines the payoffs.
- Zero-Sum (Noncooperative) matrix games $\leftrightarrow \rightarrow$ NonZero-sum bimatrix
- Normal (strategic) form: all possible sequences of decisions of each player are set out against each other (no dynamic)
- Matrix structure


Existence questions
Pure and mixed strategies

## Choice of strategies

## WHAT IS OPTIMAL?

## Best response strategies

| $\mathbf{P 1}^{\mathbf{P 2}}$ | $\boldsymbol{\alpha}$ | $\boldsymbol{\beta}$ |
| :---: | :---: | :---: |
| a | $(1,-1)$ | $(0,0)$ |
| b | $(2,-2)$ | $(0,-3)$ |
| $c$ | $(1,-1)$ | $(1,-1)$ |

$u_{i}^{b}$ best reply (response) by player 1 to a profile of strategies for all other players $u_{-i}$ if

$$
J^{i}\left(u_{i}^{b}, u_{-i}\right) \geq J^{j}\left(u_{i}, u_{-i}\right) \text { for all } u_{i} \in U^{i}
$$

## Strictly Dominating strategies

| $\mathbf{P 1}^{\mathbf{P 2}}$ | $\boldsymbol{\alpha}$ | $\boldsymbol{\beta}$ |
| :---: | :---: | :---: |
| a | $(1,0)$ | $(0,0)$ |
| $b$ | $(2,-2)$ | $(1,0)$ |
| $c$ | $(1,-1)$ | $(0,-1)$ |

$u_{i}^{d}$ of player I
$J^{j}\left(u_{i}^{d}, u_{i-}\right)>J^{i}\left(u_{i}, u_{-i}\right)$ for all $u_{i} \in U^{i}$, for all $u_{-i} \in U^{1} \times U^{2} \times \ldots \times U^{i-1} \times U^{i+1} \times \ldots \times U^{N}$

## Dominating strategies

- Eliminating some rows and/or columns which are known from the beginning to have no influence on the equilibrium solution
- Looking for Saddle points
- best reply to any feasible profile of the $N-1$ rivals:


## Example: Zero Sum Marketing game



Example: Zero Sum Marketing game -2(TV) VE

| $\mathbf{A}$ | 2,0 | 1,1 | 0,2 |
| :---: | :---: | :---: | :---: |
| 4,0 | $(1,-1)$ | $(0,0)$ | $(0,0)$ |
| 3,1 | $(2,-2)$ | $(1,-1)$ | $(0,0)$ |
| 2,2 | $(1,-1)$ | $(2,-2)$ | $(1,-1)$ |
| 1,3 | $(0,0)$ | $(1,-1)$ | $(2,-2)$ |
| 0,4 | $(0,0)$ | $(0,0)$ | $(1,-1)$ |

Dominating strategies Player A

| $\mathbf{A}$ | 2,0 | 1,1 | 0,2 |
| :---: | :---: | :---: | :---: |
| 4,0 | 1 | 0 | 0 |
| 3,1 | 2 | 1 | 0 |
| 2,2 | 1 | 2 | 1 |
| 1,3 | 0 | 1 | 2 |
| 0,4 | 0 | 0 | 1 |

## MaxiMin rule <br> (von Neumann)

- non-probabilistic decision-making rule
- decisions are ranked on the basis of their worst-case outcomes
- the optimal decision is one with the least worst outcome.
"In the worst of cases..."


## MaxiMin rule

| $\mathbf{A} \mathbf{B}$ | $s_{1}^{B}$ | $s_{2}^{B}$ | $s_{3}^{B}$ |
| :---: | :---: | :---: | :---: |
| $s_{1}^{A}$ | $(7,-7)$ | $(5,-5)$ | $(4,-4)$ |
| $s_{2}^{A}$ | $(2,-2)$ | $(6,-6)$ | $(3,-3)$ |
| $s_{3}^{A}$ | $(8,-8)$ | $(0,0)$ | $(1,-1)$ |

## MaxiMin rule

## Saddle point

| A B | $s_{1}^{B}$ | $s_{2}^{B}$ | $s_{3}^{B}$ | MIN of A |
| :---: | :---: | :---: | :---: | :---: |
| $s_{1}^{A}$ | $(7,-7)$ | $(5,-5)$ | $(4,-4)$ | 4 |
| $s_{2}^{A}$ | $(2,-2)$ | $(6,-6)$ | $(3,-3)$ | 2 |
| $s_{3}^{A}$ | $(8,-8)$ | $(0,0)$ | $(1,-1)$ | 0 |
| MIN of B MAX MIN of A |  |  |  |  |

## Saddle points may not exist ( $\nexists \boldsymbol{\not})$



## Static games in normal form Choice of strategies

- Dominating strategies
- MiniMax Theorem (von Newmann)
- Saddle points existence not guaranteed


## Nash Equilibrium

A set of strategies constitutes a Nash equilibrium if no single player in interested in changing his strategy unless one of the other players changes his own.

That is:

Keeping the choices of other players fixed, Nobody is interested in changing his own.

## Example with No saddle point but there exists 1 Nash equilibria

Set of strategies (a, $\boldsymbol{\beta}$ ) s.t.:
Knowing that G1 playes a then for G2 has not choise (convenience) but to play $\boldsymbol{\beta}$ Knowing that G2 playes $\boldsymbol{\beta}$ then for G1 has not choise (convenience) but to play a


## Example with No saddle point but there exist 2 Nash equilibria

Set of strategies (a, $\boldsymbol{\beta}$ ) s.t.:
Knowing that G1 playes a then for G2 has not choise (convenience) but to play $\boldsymbol{\beta}$ Knowing that G2 playes $\boldsymbol{\beta}$ then for G1 has not choise (convenience) but to play a

G2
$\alpha$
$\beta$

G1 | a | b |
| :--- | :--- |\(\left[\begin{array}{cc}\boldsymbol{\alpha} \& \boldsymbol{\beta} <br>

(-3,-2) \& (2,0) <br>
(0,2) \& (1,1)\end{array}\right]\)

## Nash equilibria for static games

Existence of Nash equilibrium Kakutani fixed point theorem for multivalued maps. Consequence of the classical Brouwer fixed point theorem.

In a zero-sum game, if a Nash equilibrium exists, then all Nash equilibria yield the same payoff $\vee$ (value of the game) (von Neumann)

## Nash Equilibrium Existence Theorem <br> (1950)

In a finite game there exists at least one Nash equilibrium (eventually mixed strategies)

P2

$\left(u_{i}^{N}, u_{-i}{ }^{N}\right)$ Nash equilibrium

$$
J^{i}\left(u_{i}^{N}, u_{-i}^{N}\right)>J^{j}\left(u_{i}, u_{-i}^{N}\right) \text { for all } u_{i} \in U^{i}
$$

## Nash Equilibrium

- There might be other combination of strategies that increase the payoff of some players without reducing the payoffs of the others. Or, more, that increase the payoff of all players: Prisoners' dilemma.


## Prisoners' Dilemma

- If only one confesses, and puts the blame on the other one, then he is set free and the other will be sentenced to 6 years of jail;
- If both confess, they will be sentenced to 5 years.
- If neither one confesses, they will be sentenced to 1 year.

$$
\begin{gathered}
\\
C \\
N C
\end{gathered}\left[\begin{array}{cc}
C & N C \\
(-5,-5) & (0,-6) \\
(-6,0) & (-1,-1)
\end{array}\right] \begin{array}{cc} 
& \begin{array}{c} 
\\
-5
\end{array} \\
-6
\end{array}
$$

## Prisoners' Dilemma A



## Prisoners' Dilemma B



## Prisoners' Dilemma



## Prisoners' Dilemma Nash equilibrium



## Nash Equilibrium

- Existence and uniqueness is not guaranteed
$\rightarrow$ There might exist more that one NE
- It gives solution when there might be uncertainty
- Each player does what is better for him (noncooperative)
- It might not be the better solution for everybody.
- Someone might increase his payoff moving far from the equilibrium. Nash Equilibrium might not be Pareto Optimum.


## Nash equilibrium

Noncooperative simultaneous game

- Symmetric Information structure

$$
\begin{aligned}
& u_{2} \in U^{2}
\end{aligned}
$$

## Stackelberg game

Noncooperative sequential game

- Asymmetric information structure

1. LEADER: declares his action $u_{L}$
2. FOLLOWER: computes his best response $u_{F}\left(u_{L}\right)$ (to any Leader's strategy $u_{L}$ )
3. LEADER: computes his optimal Stackelberg strategy $u_{L}{ }^{s}$
4. FOLLOWER: adjust his strategy to obtain the Stackelberg strategy $u_{F}{ }^{s}$

$$
\begin{aligned}
& \operatorname{Max} \mathrm{J}_{\mathrm{F}}\left(\mathrm{u}_{\mathrm{L}}, \mathrm{u}_{\mathrm{F}}\right) \\
& u_{\mathrm{F}} \in U^{\mathrm{F}} \\
& \mathrm{u}_{\mathrm{F}}{ }^{\mathrm{BR}}=\mathrm{u}_{\mathrm{F}}\left(\mathrm{u}_{\mathrm{L}}\right) \\
& \operatorname{Max} \mathrm{J}_{\mathrm{L}}\left(\mathrm{u}_{\mathrm{L}}, \mathrm{u}_{\mathrm{F}}\left(\mathrm{u}_{\mathrm{L}}\right)\right) \\
& u_{\mathrm{L}} \in U^{\mathrm{L}} \\
& \left(u_{L}{ }^{S}, u_{F}{ }^{S}\right)
\end{aligned}
$$

## Coordination game

## Cooperative simultaneous game

- Symmetric information structure

$$
\begin{aligned}
& \operatorname{Max}_{1}\left(\mathrm{u}_{1}, \mathrm{u}_{2}\right)+\mathrm{J}_{2}\left(\mathrm{u}_{1}, \mathrm{u}_{2}\right) \\
& \mathrm{u}_{1}, \mathrm{u}_{2} \in U^{1} \mathrm{X} U^{2}
\end{aligned}
$$

## Example Cournot duopoly static game with infinite strategy sets

$$
J_{1}=\left(\alpha-\beta\left(Q_{1}+Q_{2}\right)\right) Q_{1}-K_{1} Q_{1}{ }^{2} \quad J_{2}=\left(\alpha-\beta\left(Q_{1}+Q_{2}\right)\right) Q_{2}-K_{2} Q_{2}{ }^{2}
$$

NASH: $\left(\mathbf{Q}_{1}{ }^{\mathrm{N}}, \mathbf{Q}_{2}{ }^{\mathrm{N}}\right)=\left(\frac{\alpha}{2 K_{1}+3 \beta}, \frac{\alpha}{2 K_{2}+3 \beta}\right)$
Symm. case $\alpha=\beta=1, K_{i}=0 \Rightarrow\left(\mathrm{Q}_{1}{ }^{\mathrm{N}}, \mathrm{Q}_{2}{ }^{\mathrm{N}}\right)=(1 / 3,1 / 3) . \mathrm{J}_{1}{ }^{\mathrm{N}}=\mathrm{J}_{2}{ }^{\mathrm{N}}=1 / 9$
STACKELBERG: $(\mathrm{QLS}, \mathrm{QFS})=\left(\frac{\alpha\left(1-\frac{\beta}{2\left(K_{F}+\beta\right)}\right)}{2\left(K_{L}+\beta\right)-\beta^{2} /\left(K_{F}+\beta\right)}, \frac{\alpha-\beta Q_{L}{ }^{s}}{2\left(K_{F}+\beta\right)}\right)$
Symm. case $\alpha=\beta=1, K_{i}=0 \Rightarrow\left(\mathrm{Q}_{1}{ }^{\mathrm{s}}, \mathrm{Q}_{2}{ }^{\mathrm{s}}\right)=(1 / 2,1 / 4) \mathrm{J}_{\mathrm{L}}^{\mathrm{s}}=1 / 8, \mathrm{~J}_{\mathrm{F}}^{\mathrm{s}}=1 / 16$
COOPERATIVE: Symm. case $\alpha=\beta=1, K_{i}=0 \Rightarrow J^{\mathrm{C}}=2 / 9=\mathrm{J}_{1}{ }^{\mathrm{N}}+\mathrm{J}_{2}{ }^{\mathrm{N}}$

