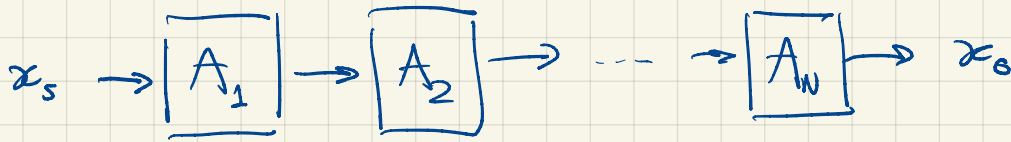


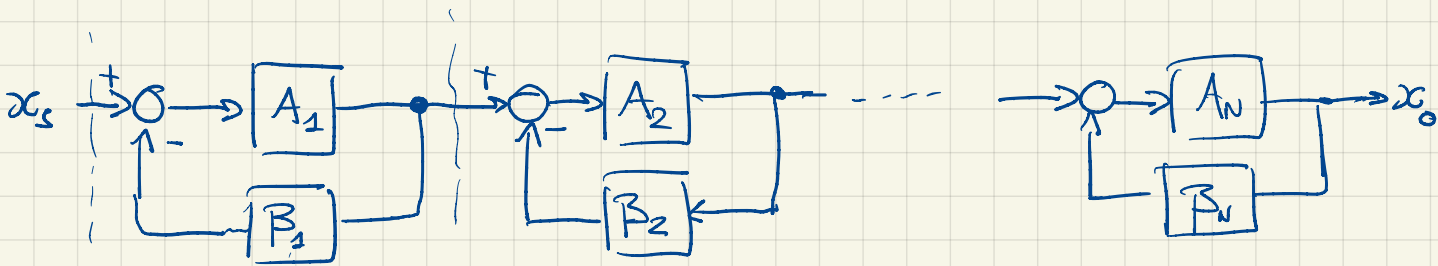
# ◇ FEEDBACK THEORY APPLICATION NOTES

## 1. MULTI-STAGE AMPLIFIER TOPOLOGIES



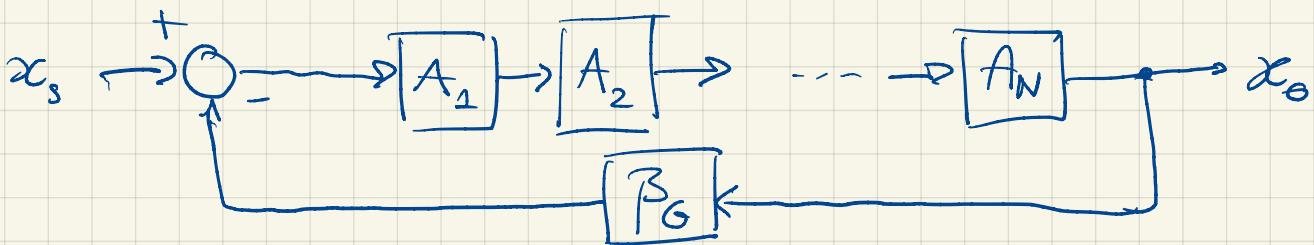
• FEEDBACK ARRANGEMENTS ARE BASICALLY :

- LOCAL FEEDBACK
- GLOBAL FEEDBACK



### LOCAL FEEDBACK

TO SIMPLIFY WE ASSUME  $A_1 = A_2 = \dots = A_N = A_{cl}$  AND  $\beta_1 = \beta_2 = \dots = \beta_N = \beta_L$



### GLOBAL FEEDBACK

UNDER THE ABOVE ASSUMPTIONS GLOBAL FEEDBACK IS MORE DIFFICULT TO STABILIZE EVEN WHEN

$$A_{OL} = \frac{A_{cl} M B}{1 + \frac{s}{\omega_p}}$$

IS A SINGLE POLE DYNAMIC SYSTEM

LOCAL FEEDBACK, IN THE SAME CONDITIONS, HAS NO STABILITY ISSUES.

SENSITIVITY OF THE CLOSED LOOP GAIN:

$$A_{FL} = \frac{A_a^N}{(1 + \beta_L A_a)^N} \quad \text{FOR LOCAL FEEDBACK}$$

$$A_{FG} = \frac{A_a^N}{1 + \beta_G A_a^N} \quad \text{FOR GLOBAL FEEDBACK}$$

FOR A FAIR COMPARISON, WE NEED TO ASSUME THAT  $A_{FG} \equiv A_{FL} \Rightarrow$

$$(1 + \beta_L A_a)^N \equiv 1 + \beta_G A_a^N$$

SENSITIVITY IS DEFINED AS

$$S_{A_F}^{A_a} = \frac{\partial A_F}{\partial A_a} \cdot \frac{A_a}{A_F}$$

WE COULD ALSO CONSIDER

$$S_{A_F}^{\beta} = \frac{\partial A_F}{\partial \beta} \cdot \frac{\beta}{A_F} = - \frac{A_a^2}{(1 + \beta A_a)^2} \cdot \frac{\beta}{A_a} \cdot (1 + \beta A_a) = - \frac{A_a \beta}{1 + A_a \beta}$$

$$A_F = \frac{A_a}{1 + \beta A_a}$$

$$S_{A_F}^{\beta} \approx -1 \quad \text{ANY TIME } A_a \cdot \beta \gg 1 \quad (\text{THE TYPICAL CASE})$$

ANY ERROR OR TOLERANCE OR DRIFT THAT MODIFIES  $\beta$ , MODIFIES  $A_F$  BY THE SAME AMOUNT (ONLY THE SIGN IS OPPOSITE).

**THEOREM:**  $\beta$ -NETWORKS MUST BE IMPLEMENTED WITH VERY STABLE COMPONENTS, WITH LOW TOLERANCE

LET'S GO BACK TO  $S_{A_{FL}}^{A_a}$

$$\begin{aligned} S_{A_{FL}}^{A_a} &= N \cdot \frac{A_a^{N-1}}{(1 + \beta_L A_a)^{N-1}} \cdot \frac{1 + \beta_L A_a - \beta_L A_a}{(1 + \beta_L A_a)^2} \cdot \frac{A_a}{A_{FL}} = N \cdot \frac{A_a^N}{(1 + \beta_L A_a)^{N+1}} \cdot \frac{(1 + \beta_L A_a)^N}{A_a^N} \\ &= N \cdot \frac{1}{1 + \beta_L A_a} \end{aligned}$$

$$S_{A_{FG}}^{A_a} = \frac{N \cdot A_a^{N-1} (1 + \beta_G A_a^N) - N \cdot \beta_G A_a^{N-1} A_a^N}{(1 + \beta_G A_a^N)^2} \cdot \frac{A_a (1 + \beta_G A_a^N)}{A_a^N} =$$

$$= \frac{N A_a^{N-1} + N \beta_G A_a^{2N-1} - N \beta_G A_a^{2N-1}}{(1 + \beta_G A_a^N)^2 A_a^{N-1}} = \frac{N}{1 + \beta_G A_a^N} \stackrel{\downarrow}{=} \frac{N}{(1 + \beta_L A_a)^N}$$

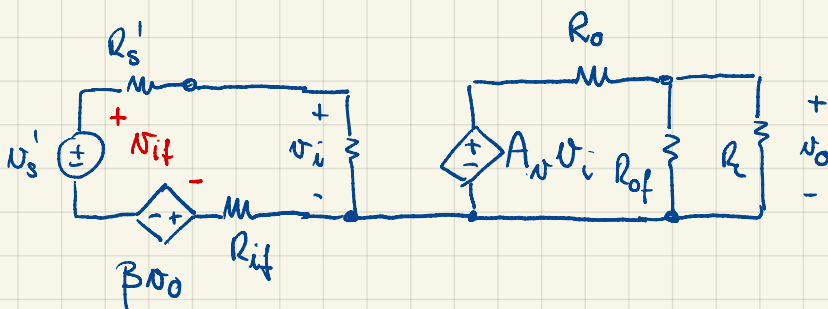
$$S_{A_{FG}}^{A_a} = \left( S_{A_{FL}}^{A_a} \right)^N \cdot \frac{1}{N^{N-1}} \ll S_{A_{FL}}^{A_a}$$

$\uparrow < 1$                        $\uparrow \ll 1$

GLOBAL FEEDBACK IS VERY ADVANTAGEOUS (WITH RESPECT LOCAL FEEDBACK) IN TERMS OF SENSITIVITY. IT IS LESS ADVANTAGEOUS IN TERMS OF STABILITY.

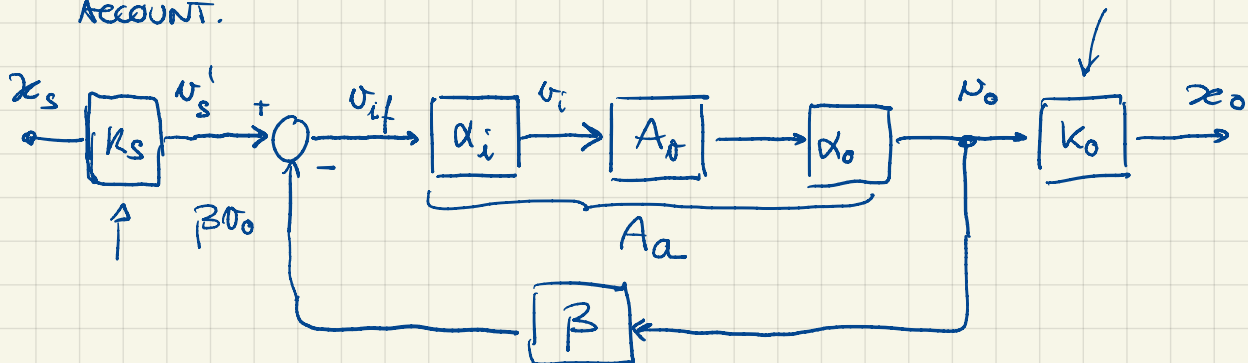
BECAUSE THERE'S NO CLEAR WINNER, BOTH SOLUTIONS ARE USED, OFTEN AT THE SAME TIME.

◇ BLOCK DIAGRAMS OF FEEDBACK AMPLIFIERS. (RELATION BETWEEN FEEDBACK THEORY AND CONTROL SYSTEM THEORY)



EQUIVALENT CIRCUIT OF A VOLTAGE AMPLIFIER WITH FEEDBACK

FROM THIS CIRCUIT, WE CAN IMMEDIATELY DERIVE A BLOCK DIAGRAM WHERE LOADING EFFECTS AND SCALE FACTORS ARE TAKEN INTO ACCOUNT.



$$\alpha_i = \frac{R_i}{R_i + R_s' + R_{if}}$$

$$\alpha_o = \frac{R_o \parallel R_{of}}{R_o + R_L \parallel R_{of}}$$

$$A_a = \alpha_i A_v \alpha_o$$

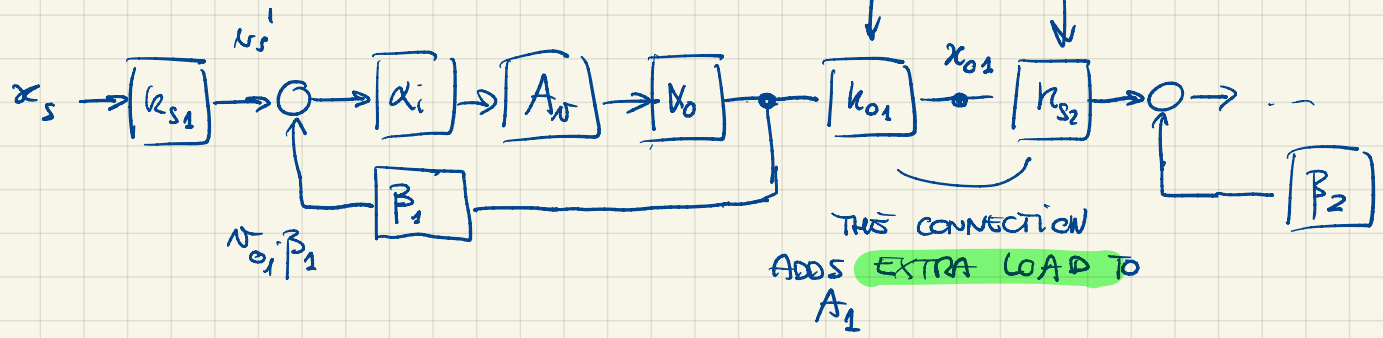
IT IS THEN POSSIBLE TO INTERCONNECT BLOCK DIAGRAMS TO TREAT COMPLEX AMPLIFIER ORGANIZATIONS SUCH AS:

- CASCADE ORGANIZATION
- NESTED LOOP ORGANIZATION
- INTERTWINED LOOP ORGANIZATION

BUT CARE MUST BE TAKEN TO ACCOUNT FOR LOADING EFFECTS

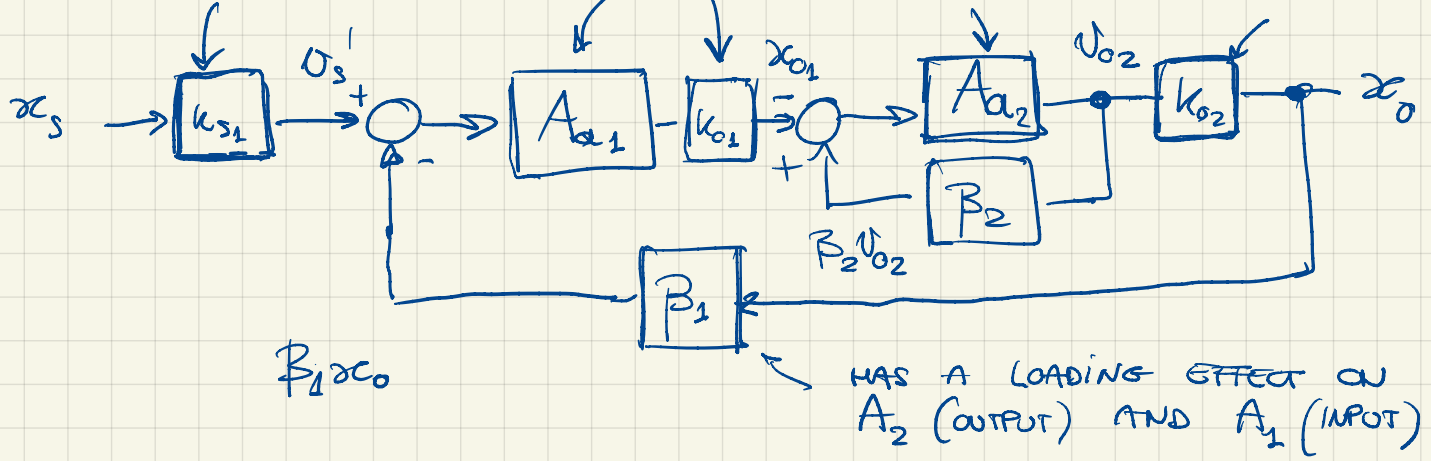
### 1. CASCADE

THESE MUST BE CALCULATED CONSIDERING THE LOADING EFFECTS



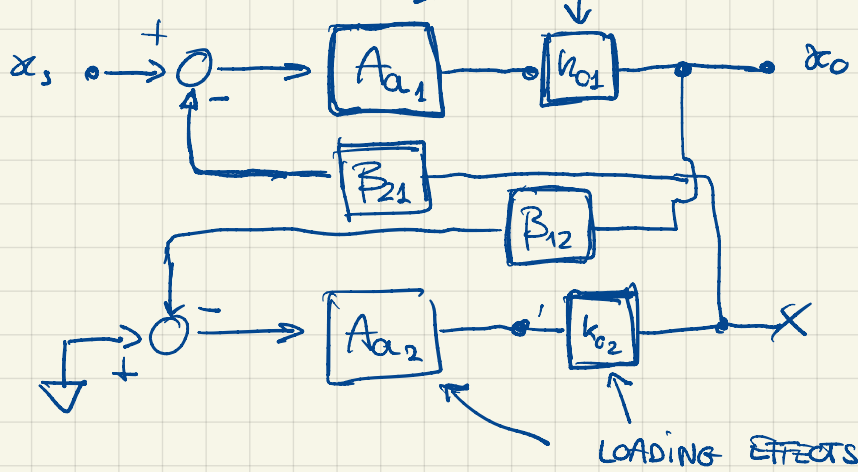
### 2. NESTED LOOP

WE NEED TO TAKE INTO ACCOUNT LOADING EFFECTS HERE



### 3. INTERTWINED

WE NEED TO TAKE LOADING EFFECTS INTO ACCOUNT



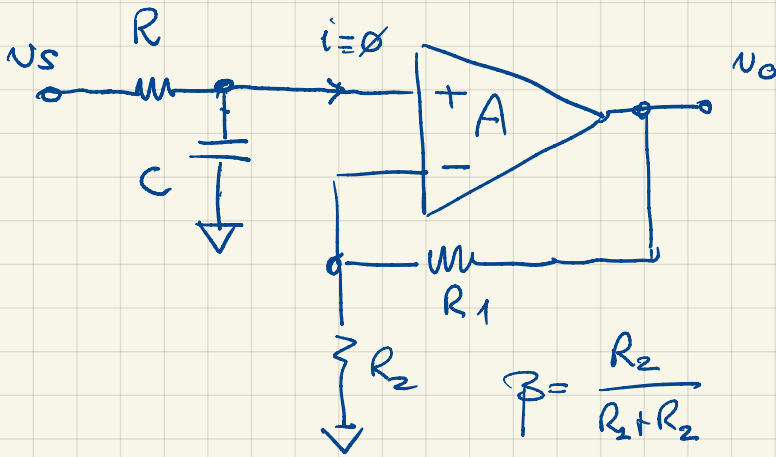
$\beta_{21}$  LOADS THE INPUT SIDE OF  $A_1$  AND THE OUTPUT SIDE OF  $A_2$

$\beta_{12}$  LOADS THE INPUT SIDE OF  $A_2$  AND THE OUTPUT SIDE OF  $A_1$

## ◇ FEEDBACK AND FREQUENCY RESPONSE

IN GENERAL TERMS, THE BANDWIDTH WIDENING PROPERTY HOLDS, BUT CARE MUST BE TAKEN BEFORE APPLYING SUCH PROPERTY TO ANY AMPLIFIER

CONSIDER THIS EXAMPLE:



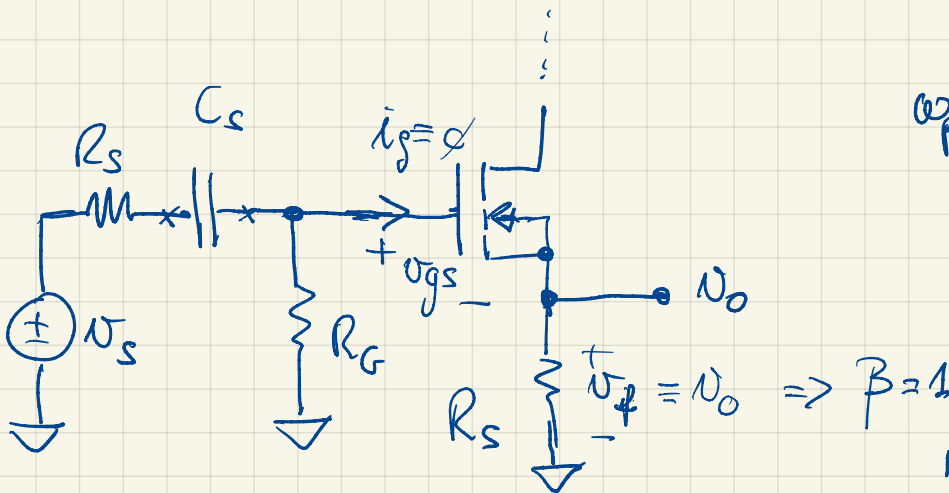
SINGLE POLE PLACED AT

$$\omega_p = \frac{1}{RC}$$

WHICH OBVIOUSLY DOES NOT DEPEND ON T OR  $1+T = 1+A\beta$

THE REASON THE POLE DOES NOT DEPEND ON T IS THAT IT IS PLACED **OUTSIDE THE FEEDBACK LOOP**. ACTUALLY, THE POLE IS LOCATED INSIDE  $K_S$

LET'S CONSIDER ANOTHER EXAMPLE



$$\omega_p = \frac{1}{C_s(R_s + R_g)}$$

AGAIN, THE POLE DOES NOT DEPEND ON T

INDEED  $C_s$  "SEES" THE SAME RESISTANCE  $R_s + R_g$  NO MATTER THE VALUE OF T

## ◇ FEEDBACK THEORY AND STABILITY

USING FEEDBACK THEORY WE CAN CALCULATE  $A_d$  AND  $\beta$  EXACTLY. THEREFORE WE CAN ALSO FIND  $T = \beta A_d$ .

ONCE WE HAVE T, WE CAN USE **NYQUIST THEOREM** AND

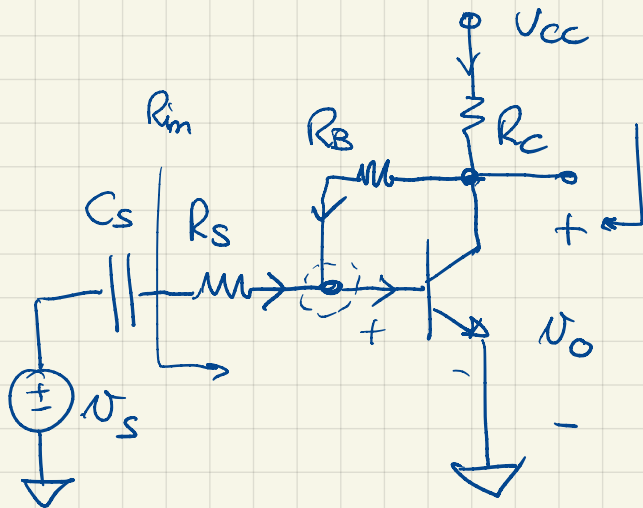
DISCUSS THE AMPLIFIER STABILITY.

BUT WE CAN ALSO SHAPE THE  $\beta$ -NETWORK TO ENHANCE THE AMPLIFIER'S STABILITY MARGINS (PHASE MARGIN AND/OR GAIN MARGIN)

THIS IS CALLED COMPENSATION OF AN AMPLIFIER. THIS WILL BE THE OBJECT OF NEXT LESSONS.

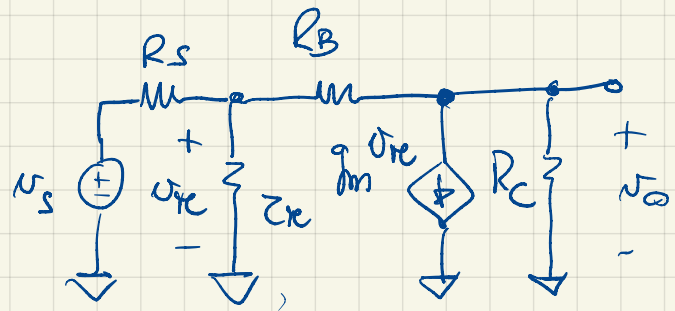
### EXAMPLE

CE AMPLIFIER WITH SELF-BIAS



$R_{out}$

SMALL SIGNAL EQUIVALENT CIRCUIT @ MID-BAND



1. FIND  $A_v \triangleq \frac{v_o}{v_s}$ ,  $R_{in}$  AND  $R_{out}$
2. DISCUSS THE POLE LOCATION
3. DRAW THE AMPLIFIER BLOCK DIAGRAM.