

Network Science

#21 Graph visualization

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The layout problem

Algorithms for graph visualization

Before

- ❑ always based on some properties: tree, series-parallel graph, planar graph
- ❑ and on some additional information: ordering of the vertices, decompositions into SP-components

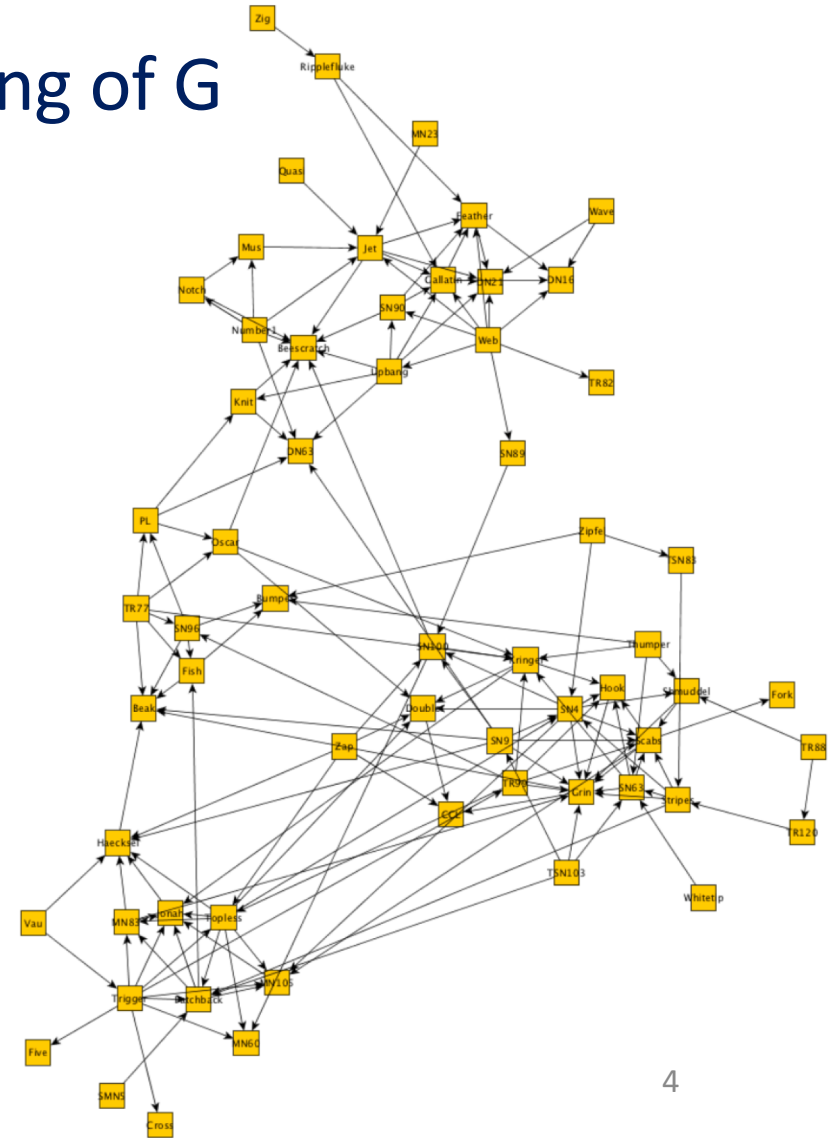
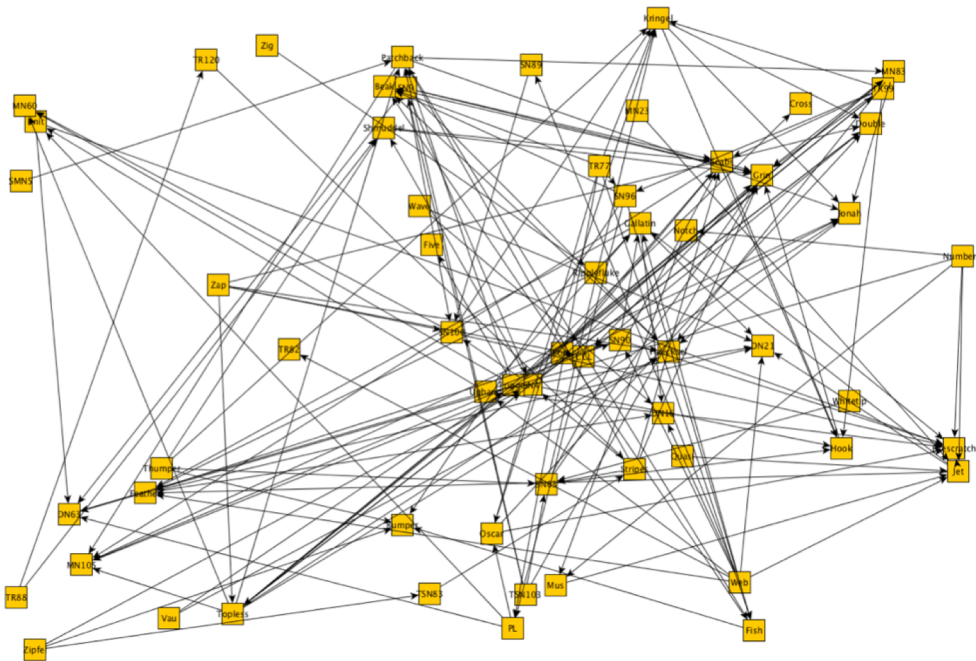
Today

- ❑ more direct and intuitive method based on physical analogies
- ❑ The methods are very popular: intuitiveness, easy to program, generality, fairly satisfactory results,...

General layout problem

Given a graph $G=(V,E)$

Find a clear and readable drawing of G



Which aesthetic criteria would you optimize?

Aesthetic criteria

- adjacent nodes are close
- non-adjacent far apart
- edges short, straight-line, similar length
- densely connected parts (clusters) form communities
- as few crossings as possible
- nodes distributed evenly



... but optimization criteria partially contradict each other

Examples

Given graph $G = (V, E)$, required edge length $l(e)$

Find drawing of G which realizes all the edge lengths

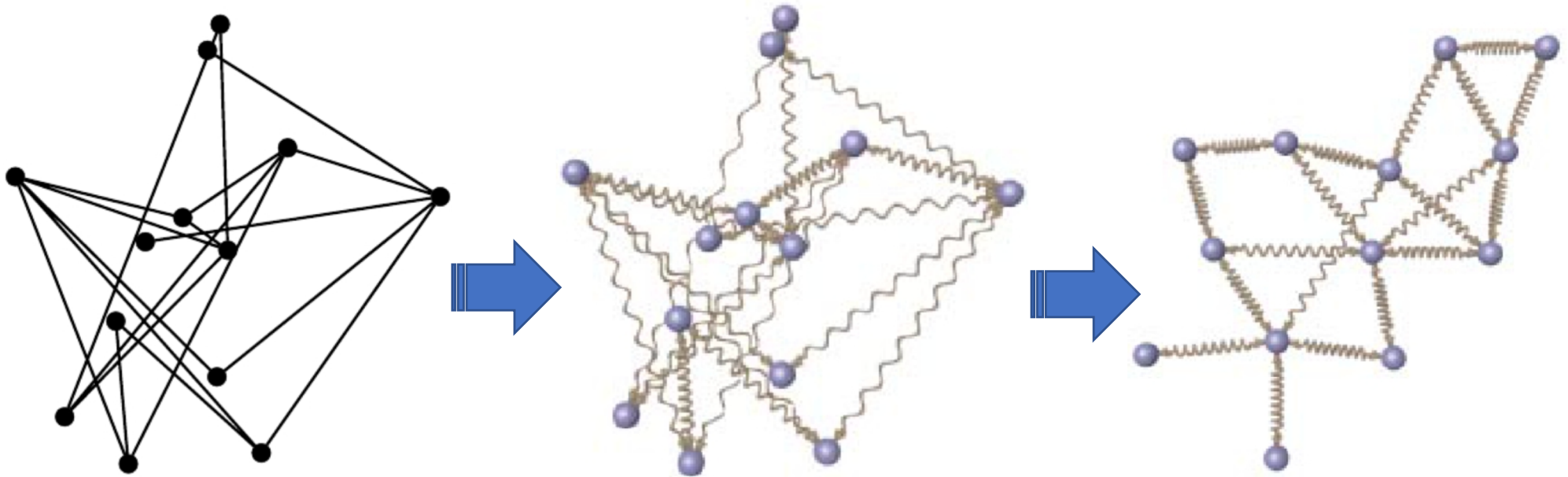
NP-hard for

- edge lengths $\{1, 2\}$ [Saxe, '80]
- planar drawing with unit edge lengths
[Eades, Wormald, '90]

Spring-embedder algorithms

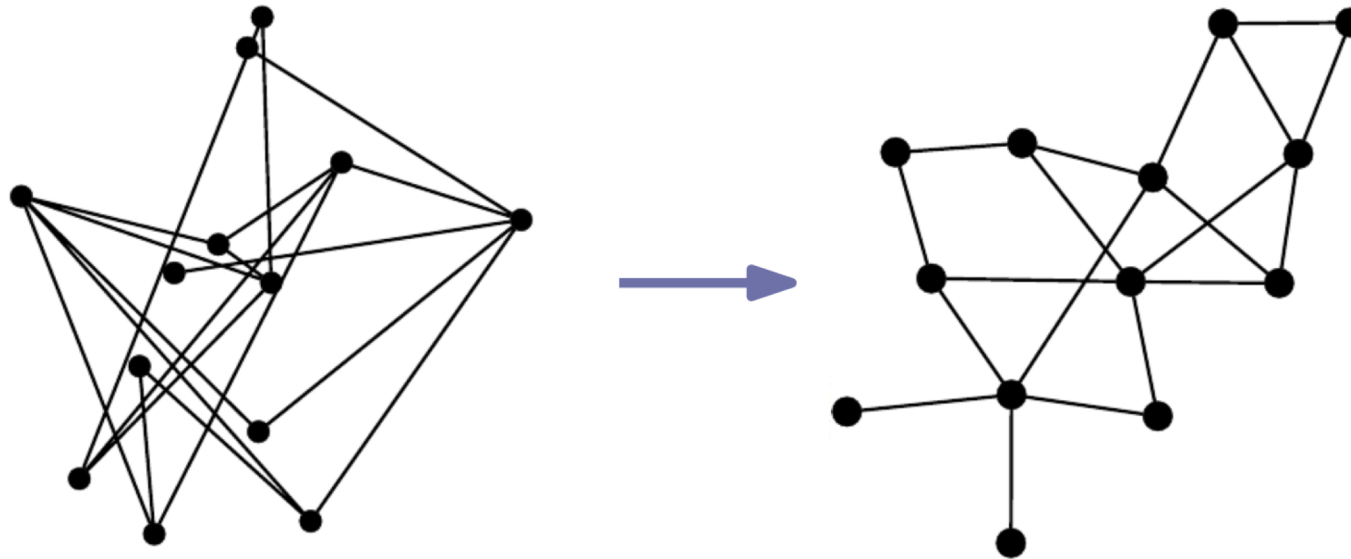
Eades, "A heuristic for graph drawing" (1984)

The physical model



“To embed a graph we replace the vertices by steel rings and replace each edge with a spring to form a mechanical system . . . The vertices are placed in some initial layout and let go so that the spring forces on the rings move the system to a minimal energy state.”

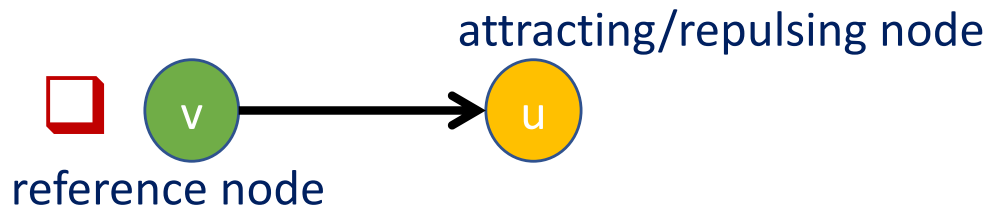
Spring-embedder algorithms



So-called spring-embedder algorithms that work according to this or similar principles are among the most frequently used graph-drawing methods in practice

Notation

- $l = l(e)$ ideal spring length for edge e
- $p_v = (x_v, y_v)$ position of node v
- $|p_v - p_u|$ Euclidean distance between u and v
- $\vec{p_v p_u}$ unit vector pointing from v to u



Spring-embedder model (Eades, 1984)

- **repulsive** force between non-adjacent nodes u and v

$$f_{\text{rep}}(p_u, p_v) = \frac{c_{\text{rep}}}{\|p_v - p_u\|^2} \cdot \overrightarrow{p_u p_v}$$

- **attractive** force between adjacent vertices u and v

$$f_{\text{spring}}(p_u, p_v) = c_{\text{spring}} \cdot \log \frac{\|p_u - p_v\|}{\ell} \cdot \overrightarrow{p_v p_u}$$

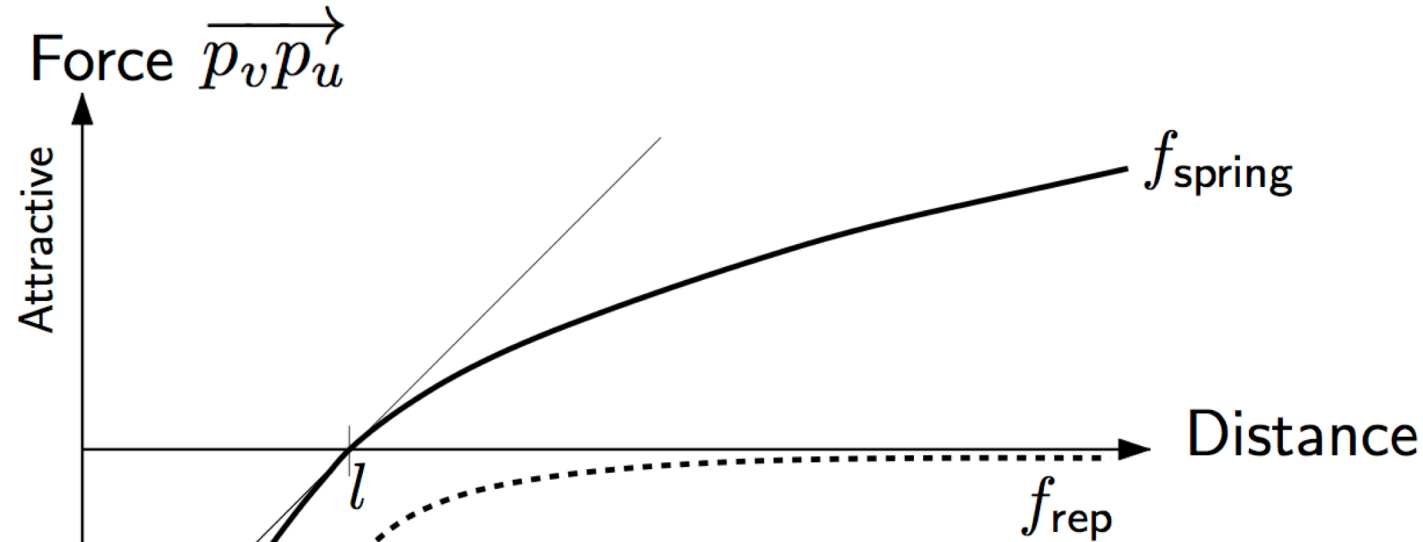
- resulting displacement vector for node v

$$F_v = \sum_{u: \{u,v\} \notin E} f_{\text{rep}}(p_u, p_v) + \sum_{u: \{u,v\} \in E} f_{\text{spring}}(p_u, p_v)$$

Diagram of repulsive/attractive forces

reference node

attracting/repulsing node



$$f_{\text{rep}}(p_u, p_v) = \frac{c_{\text{rep}}}{\|p_v - p_u\|^2} \cdot \overrightarrow{p_u p_v}$$

$$f_{\text{spring}}(p_u, p_v) = c_{\text{spring}} \cdot \log \frac{\|p_u - p_v\|}{\ell} \cdot \overrightarrow{p_v p_u}$$

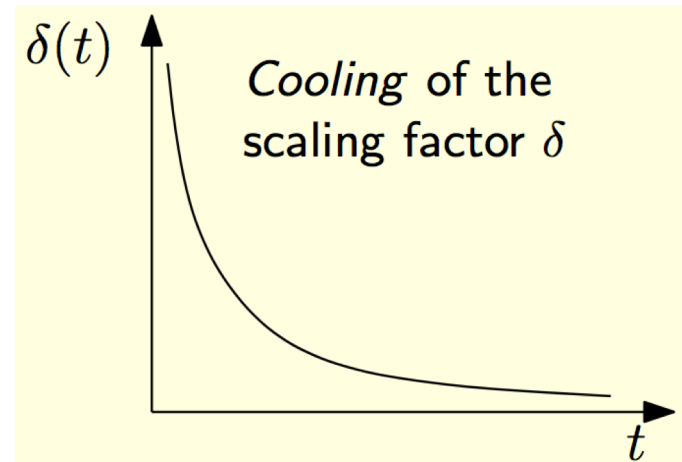
Algorithm

- While forces are sufficiently strong

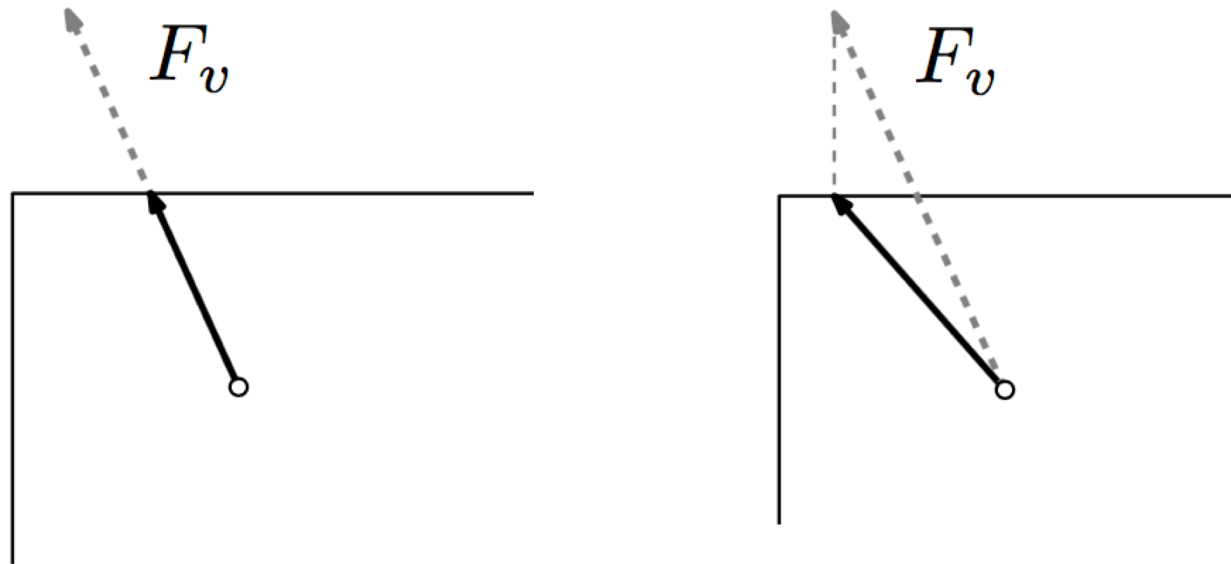
$$\max_{v \in V} \|F_v(t)\| > \varepsilon$$

- Update node position

$$p_v \leftarrow p_v + \delta \cdot F_v(t)$$



Bounded drawing area



If force F_v drives out of R , we adapt the vector appropriately within R

Discussion

Advantages

- ❑ very simple Algorithm
- ❑ good results for small and medium-sized graphs
- ❑ good representation of symmetry/structure

Disadvantages

- ❑ system is not stable at the end
- ❑ converging to local minima
- ❑ timewise f_{spring} in $O(|E|)$ and f_{rep} in $O(|V|^2)$

Influence

- ❑ Basis for many further ideas

Variants

Fruchterman and Reingold (1991)

Fruchterman & Reingold (1991). Graph drawing by force-directed placement
http://www.mathe2.uni-bayreuth.de/axel/papers/reingold:graph_drawing_by_force_directed_placement.pdf

- **repulsive** force between all node pairs

$$f_{\text{rep}}(p_u, p_v) = \frac{\ell^2}{\|p_v - p_u\|} \cdot \overrightarrow{p_u p_v} \quad \leftarrow \text{more repulsive}$$

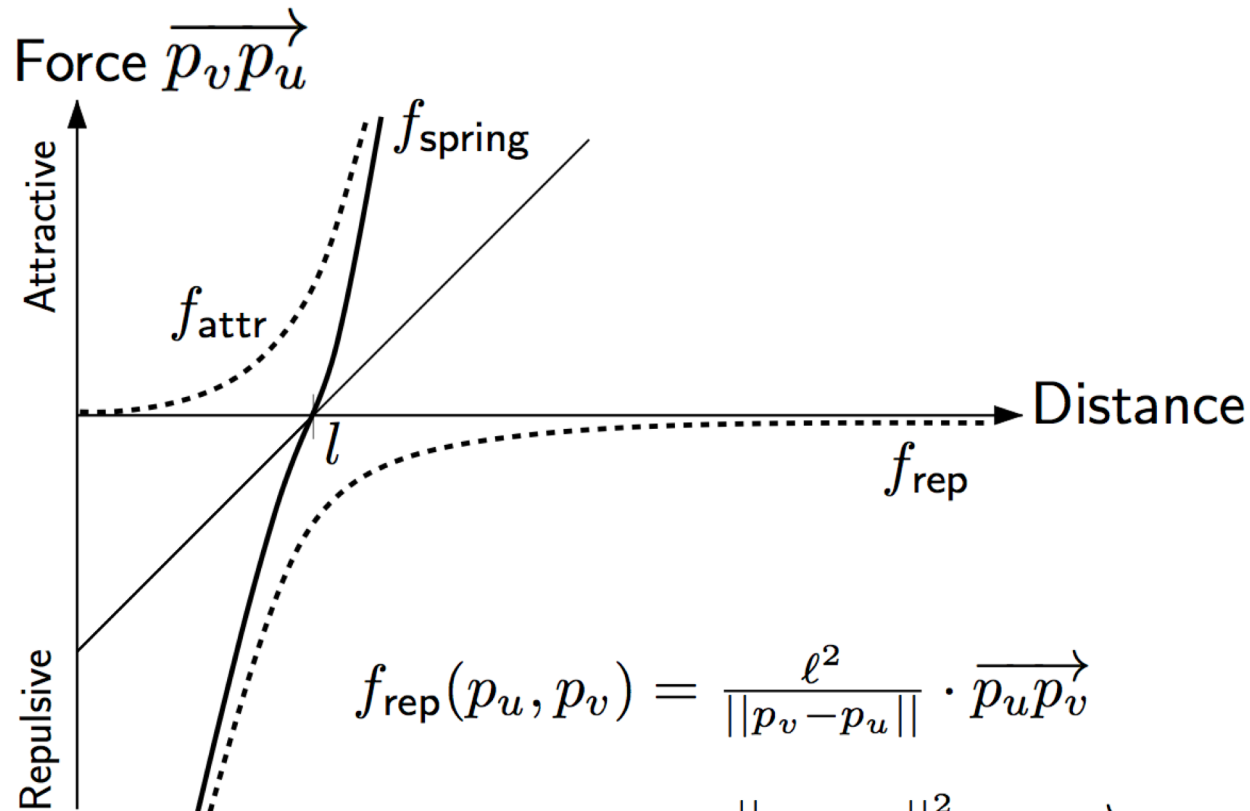
- **attractive** force between adjacent vertices u and v

$$f_{\text{attr}}(p_u, p_v) = \frac{\|p_u - p_v\|^2}{\ell} \cdot \overrightarrow{p_v p_u} \quad \leftarrow \text{more attractive}$$

Diagram of repulsive/attractive forces

reference node

attracting/repulsing node

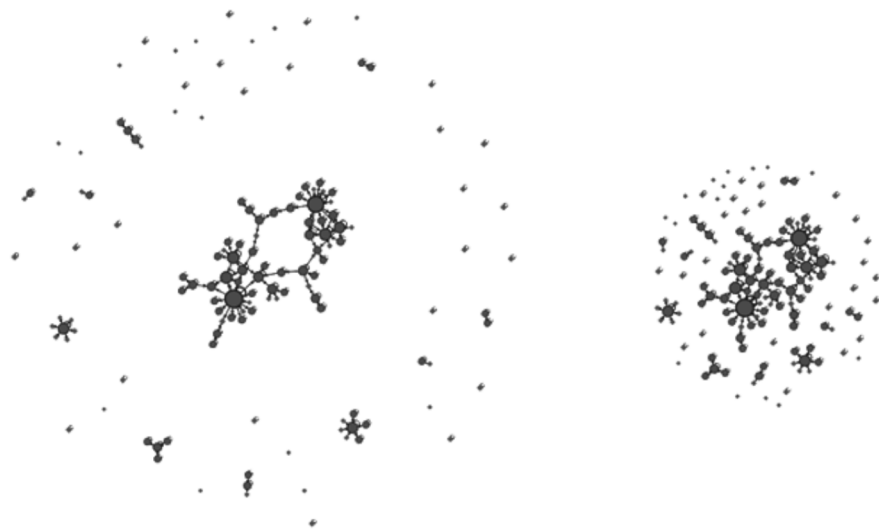


$$f_{\text{rep}}(p_u, p_v) = \frac{\ell^2}{\|p_v - p_u\|} \cdot \overrightarrow{p_u p_v}$$

$$f_{\text{attr}}(p_u, p_v) = \frac{\|p_u - p_v\|^2}{\ell} \cdot \overrightarrow{p_v p_u}$$

$$f_{\text{spring}}(p_u, p_v) = f_{\text{rep}}(p_u, p_v) + f_{\text{attr}}(p_u, p_v)$$

Gravity



$$\Phi(v) = 1 + \deg(v)/2$$

node mass

baricenter

$$p_{\text{bary}} = 1/|V| \cdot \sum_{v \in V} p_v$$

$$f_{\text{grav}}(p_v) = c_{\text{grav}} \cdot \Phi(v) \cdot \overrightarrow{p_v p_{\text{bary}}}$$

prevents disconnected components (islands) from drifting away; attracts nodes to the centre of the spatialisation. Its main purpose is to compensate repulsion for nodes that are far away from the centre.

Force atlas 2 (2014)

Jacomy, Venturini, Heymann, Bastian (2014).

ForceAtlas2, a continuous graph layout algorithm for handy network visualization designed for the Gephi software
<https://journals.plos.org/plosone/article?id=10.1371/journal.pone.0098679>

- **repulsive** force between all node pairs

$$f_{\text{rep}}(p_u, p_v) = k_r \frac{(\text{deg}(u) + 1)(\text{deg}(v) + 1)}{\|p_u - p_v\|}$$

correction

as F&R

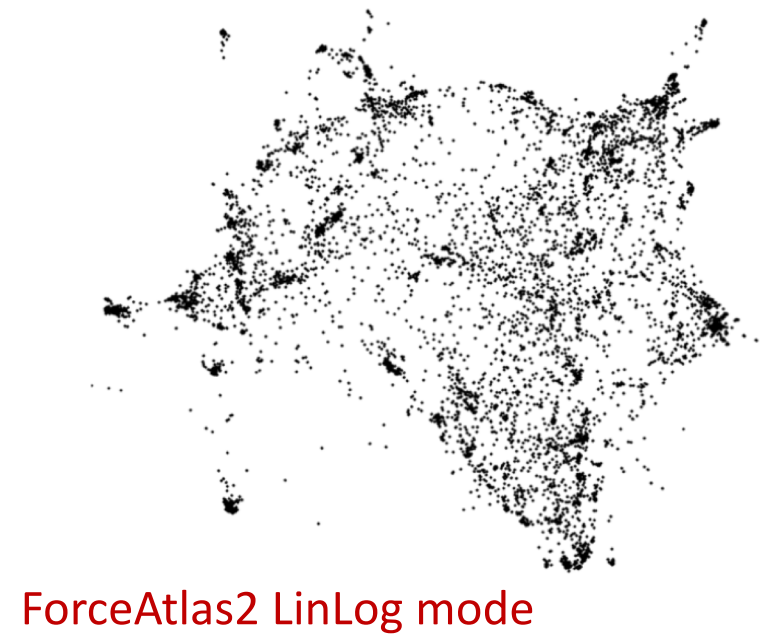
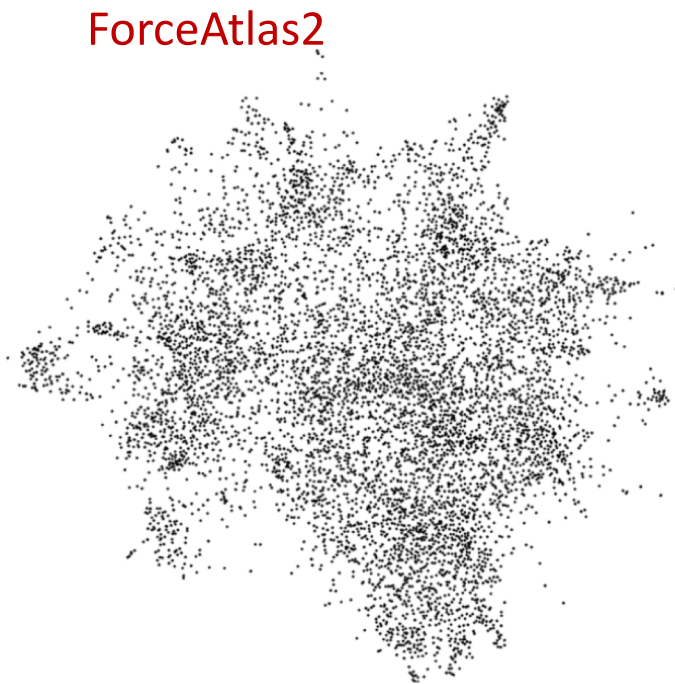
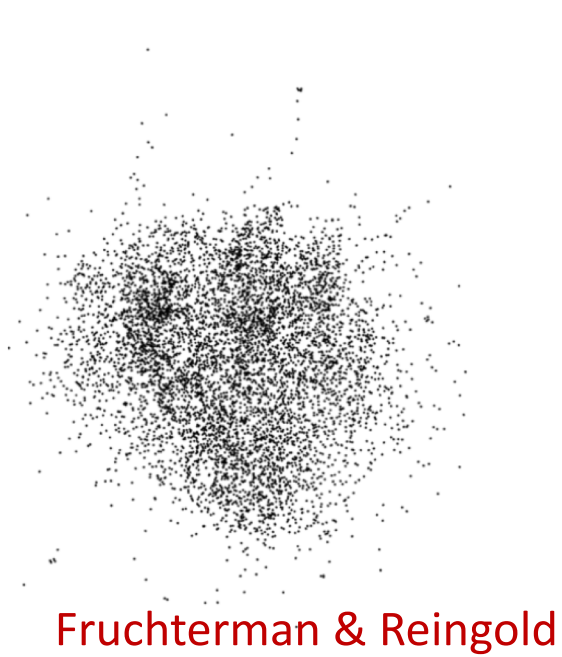
- **attractive** force between adjacent vertices u and v

$$f_{\text{attr}}(p_u, p_v) = \log(1 + \|p_u - p_v\|) \cdot \overrightarrow{p_v p_u}$$

less attractive

in lin-log mode

Force atlas 2 (2014)

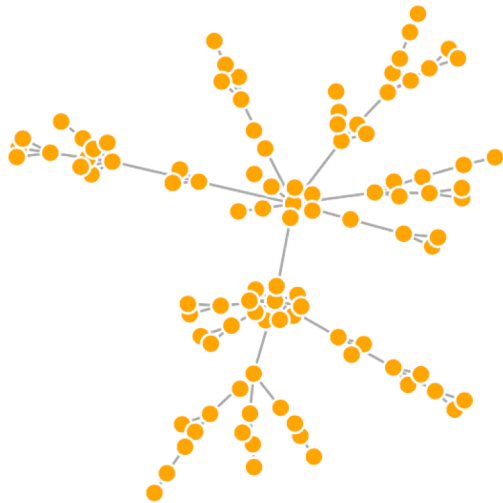


Comparison

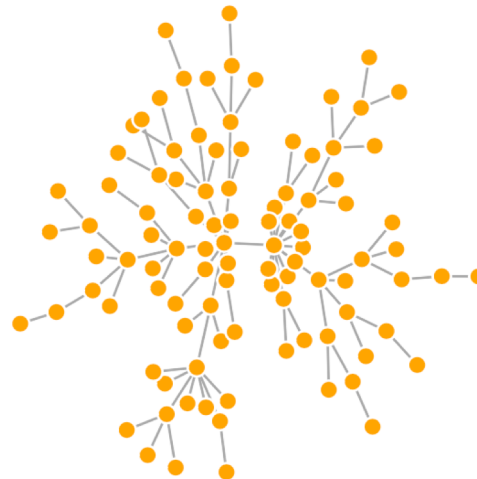
| | ATTRACTIVE | REPULSIVE |
|-------------------------|-----------------------------------|--|
| Spring model | $\log \frac{\ p_u - p_v\ }{\ell}$ | $\frac{c_{rep}}{\ p_v - p_u\ ^2}$ |
| Fruch & Rein | $\frac{\ p_u - p_v\ ^2}{\ell}$ | $\frac{\ell^2}{\ p_v - p_u\ }$ |
| Force Atlas 2 | $\ p_u - p_v\ $ | $\frac{(deg(u)+1)(deg(v)+1)}{\ p_u - p_v\ }$ |
| LinLog mode | $\log(1 + \ p_u - p_v\)$ | |

Comparison (R igraph library)

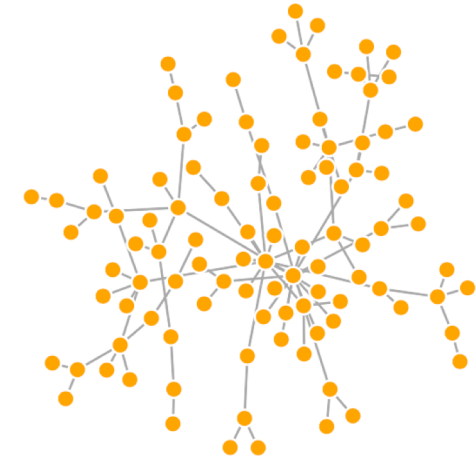
Fruchterman & Reingold



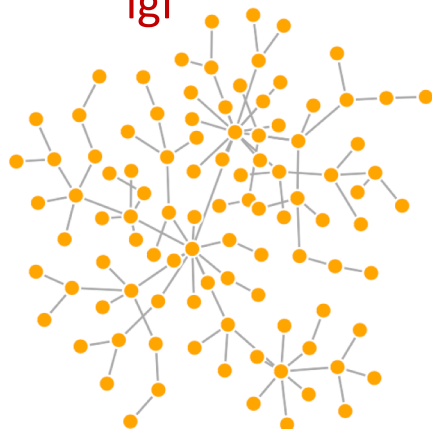
Kamada Kawai



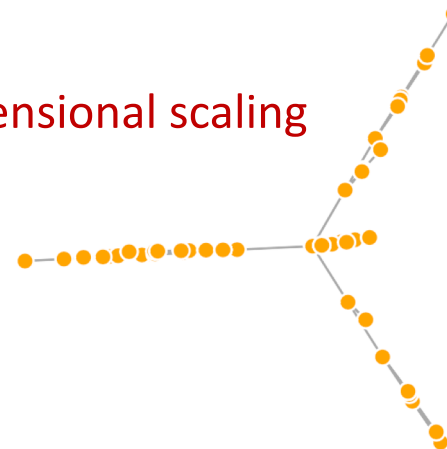
Graph opt



lgl



Multidimensional scaling



Discussion

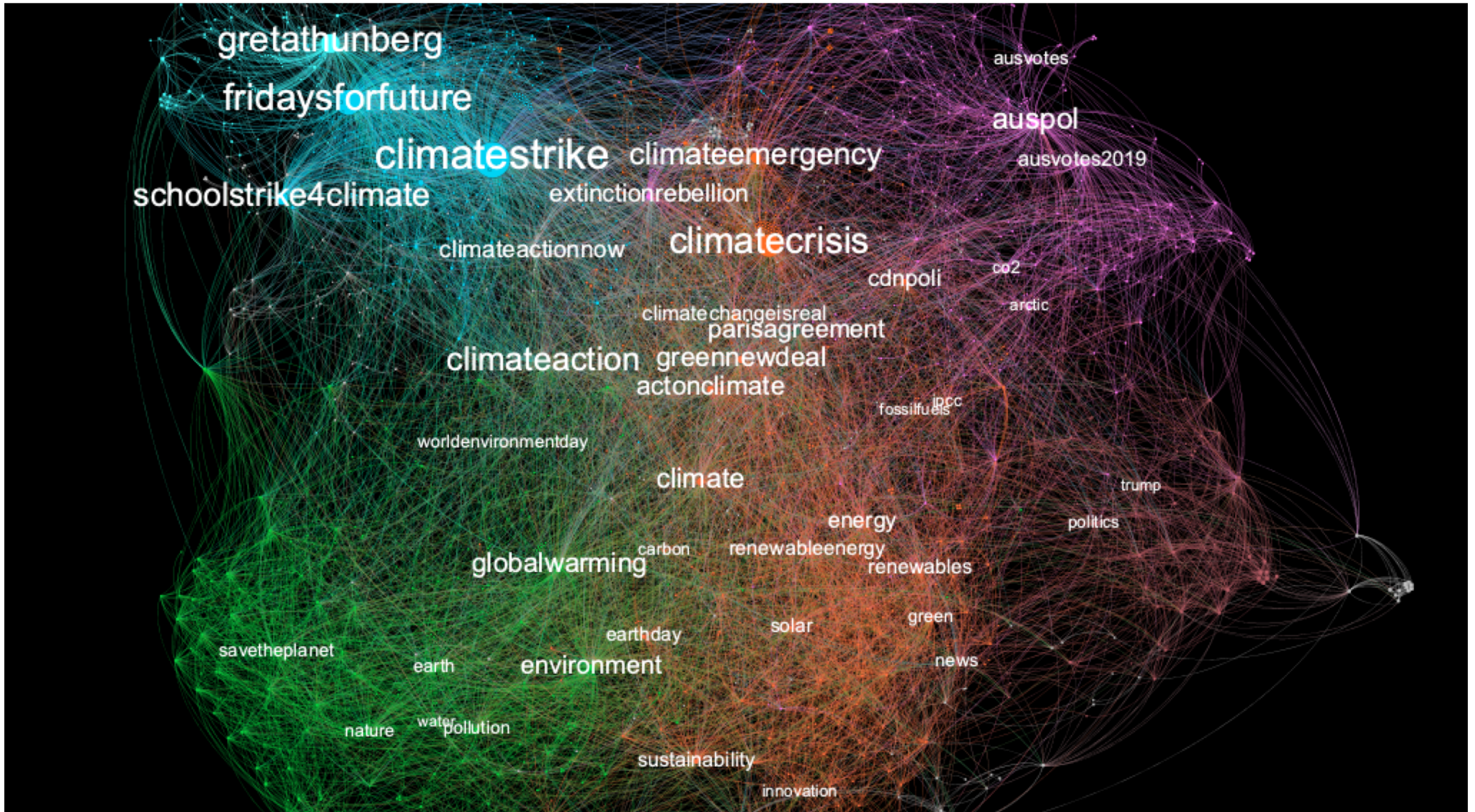
Force-based Approaches are

- ❑ easily understandable and implementable
- ❑ depending on the graphs (small and sparse)
- ❑ amazingly good layouts (Symmetries, Clustering)
- ❑ easily adaptable and configurable
- ❑ robust
- ❑ scalable

But...

- ❑ no quality and running time guarantees
- ❑ bad choice of starting layout → slow convergence
- ❑ possibly slow for large graphs
- ❑ fine-tuning can be done by experts

Example



Grip

Gajer, Kobourov (2004). Grip: Graph drawing with intelligent placement
<http://emis.um.ac.ir/journals/JGAA/accepted/2002/GajerKobourov2002.6.3.pdf>

GRIP – Graph dRawing with Intelligent Placement

Motivation

- ❑ Spring-Embedder for large graphs are too slow
- ❑ sensitivity to initialisation of node positions

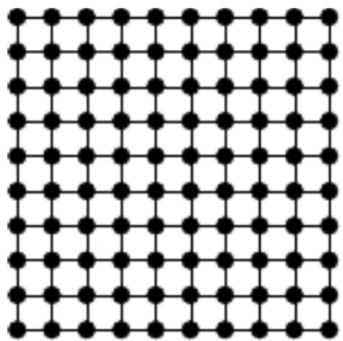
Approach

- ❑ top-down graph coarsening/filtration
- ❑ bottom-up calculation of the layout
- ❑ clever placement of new nodes
- ❑ force-based refinement of their positions

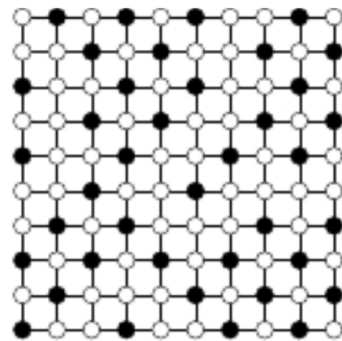


Maximal independent set (MIS) filtering

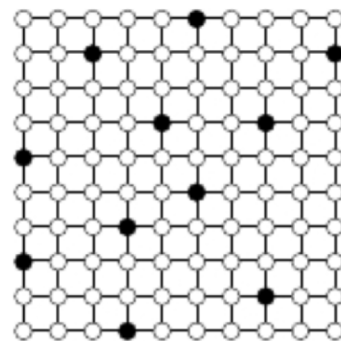
- ❑ Sequence of node sets $V = V_0 \supset V_1 \supset \dots \supset V_k \supset \emptyset$
- ❑ distance in G between nodes in V_i is $\geq 2^{i-1} + 1$
- ❑ can be done by **BFS** by deleting nodes closer than bound
- ❑ good balance between size of a level and depth of decomposition



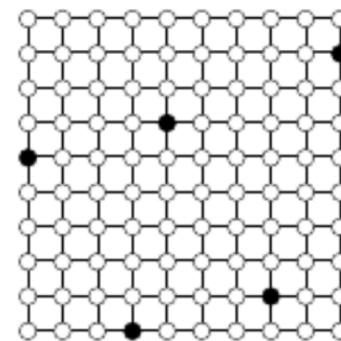
V_0



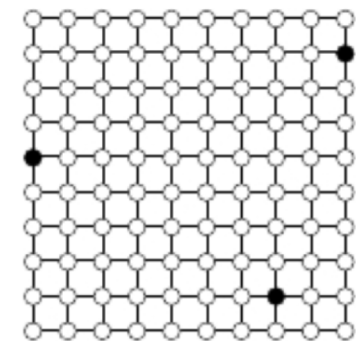
V_1



V_2



V_3



V_4

Level-based node placement

Step 1

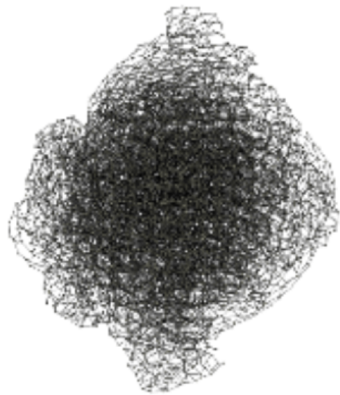
- for each node $v \in V_i \setminus V_{i+1}$ find optimal position with respect to three adjacent nodes V_{i+1}

Step 2

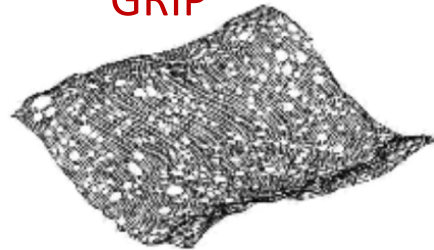
- perform force-based refinement, where forces are computed locally only to a constant number of nearest neighbours in V_i

Experiments

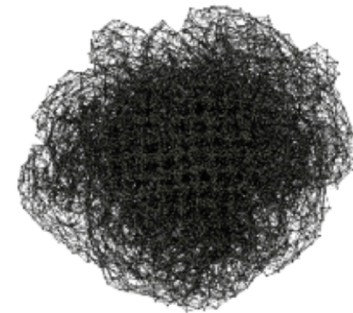
Fruchterman & Reingold



GRIP



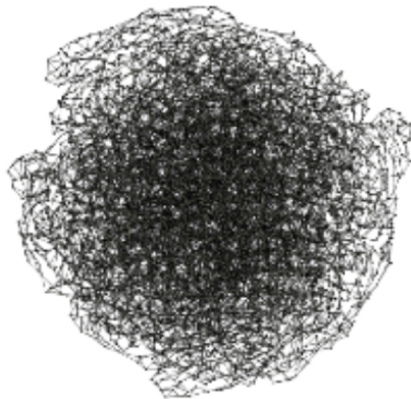
Fruchterman & Reingold



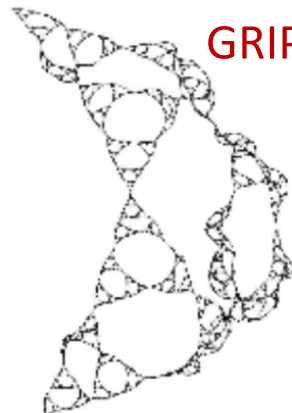
GRIP



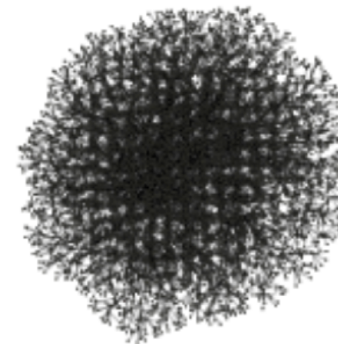
Fruchterman & Reingold



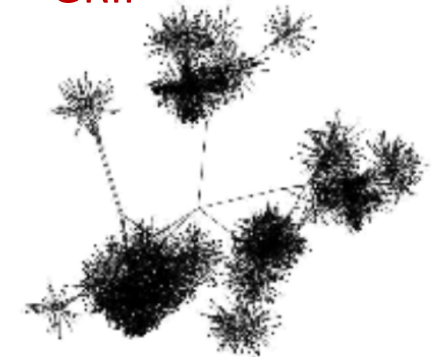
GRIP



Fruchterman & Reingold



GRIP



BERTopic

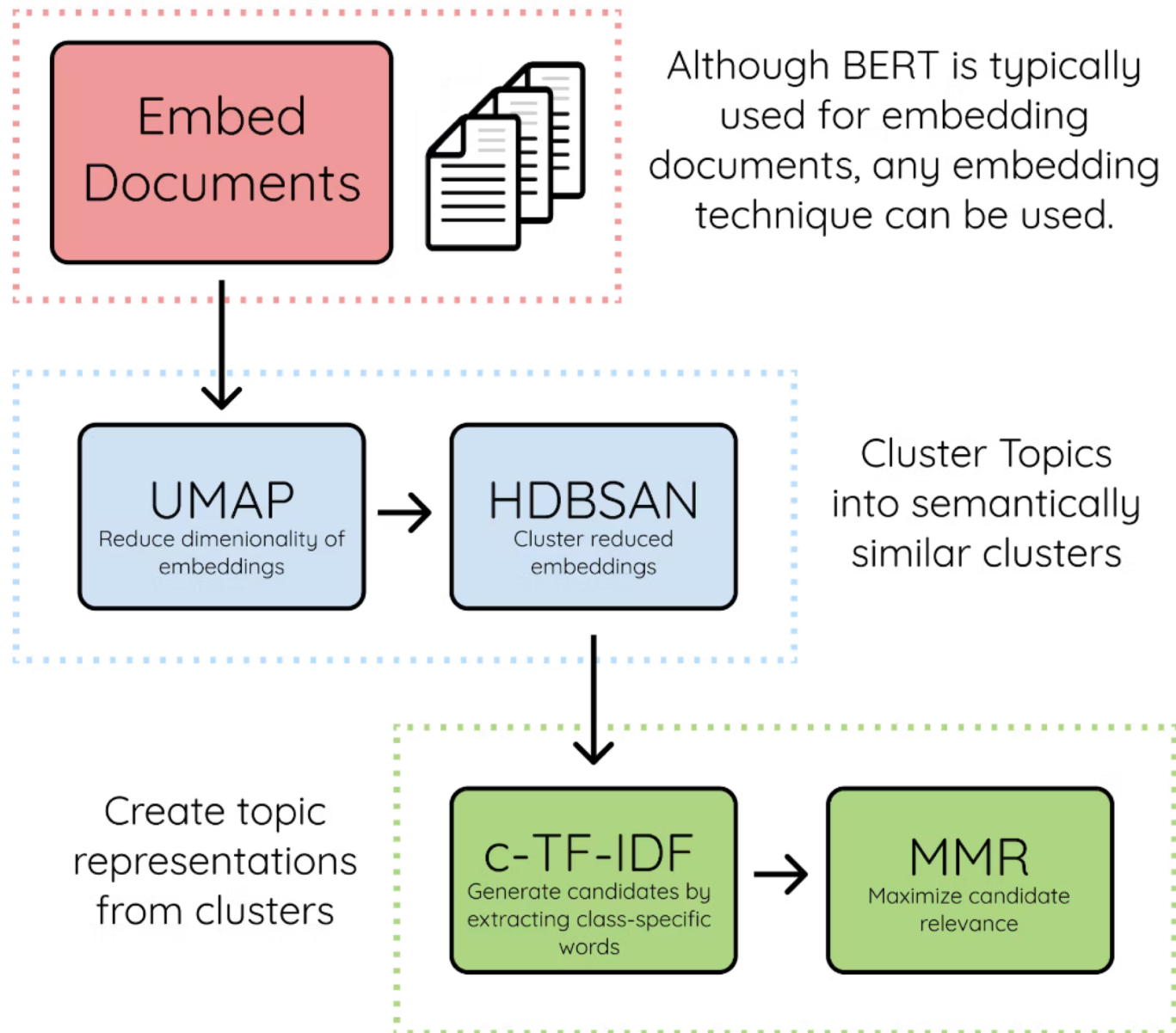
M. Grootendorst (2022)

BERTopic: Neural topic modeling with a class-based TF-IDF procedure

<https://arxiv.org/abs/2203.05794>

What is BERTopic?

from bertopic import BERTopic



What is UMAP

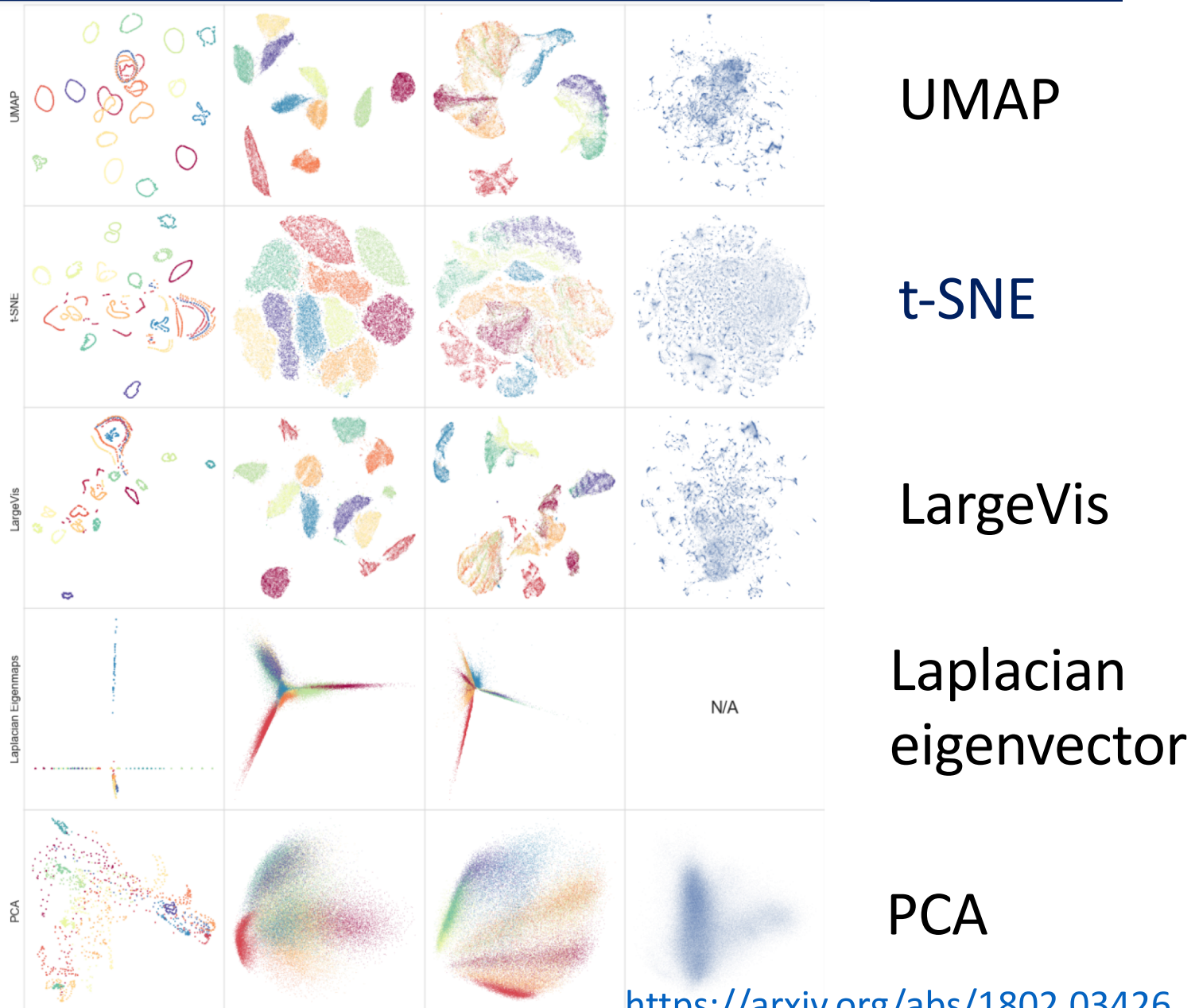
<https://arxiv.org/abs/1802.03426>

Idea

- ❑ Identify distances with k-nearest neighbours
- ❑ Apply a force-directed algorithm
- ❑ This keeps local info

| | ATT | REP |
|---------------|---|--|
| spring | $\log(d_{u,v}/\ell)$ | $\frac{c_{\text{rep}}}{d_{u,v}^2}$ |
| Fruch & Rein | $\frac{d_{u,v}^2}{\ell}$ | $\frac{\ell^2}{d_{u,v}}$ |
| Force Atlas 2 | $d_{u,v}$ | $\frac{(1 + \deg(u))(1 + \deg(v))}{d_{u,v}}$ |
| UMAP | $\frac{d_{u,v}^{2(b-1)}}{1 + d_{u,v}^2} \ell$ | $\frac{1 - \ell}{(\epsilon + d_{u,v}^2)(1 + ad_{u,v}^{2b})}$ |

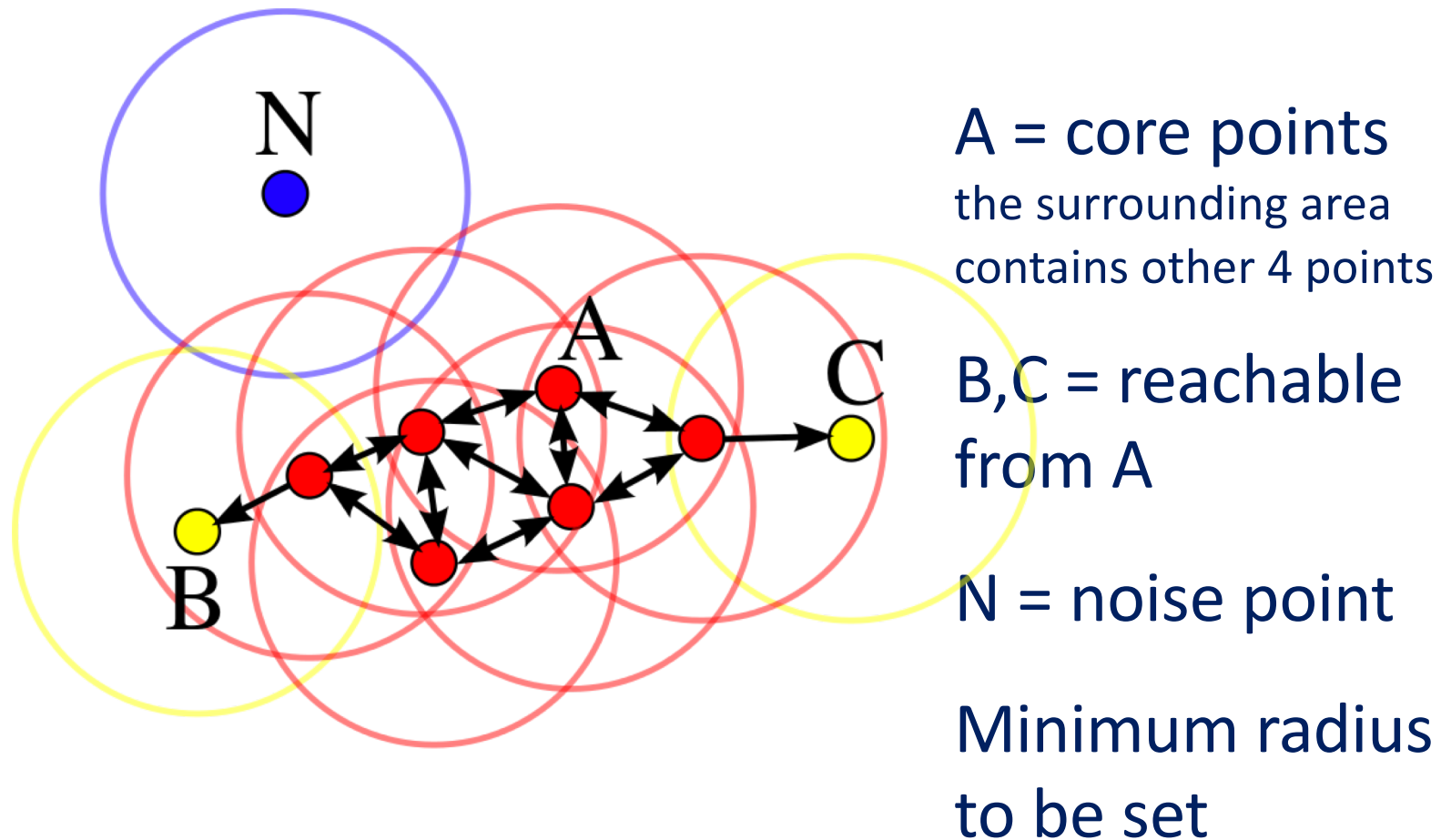
Comparison



What is HDBSCAN

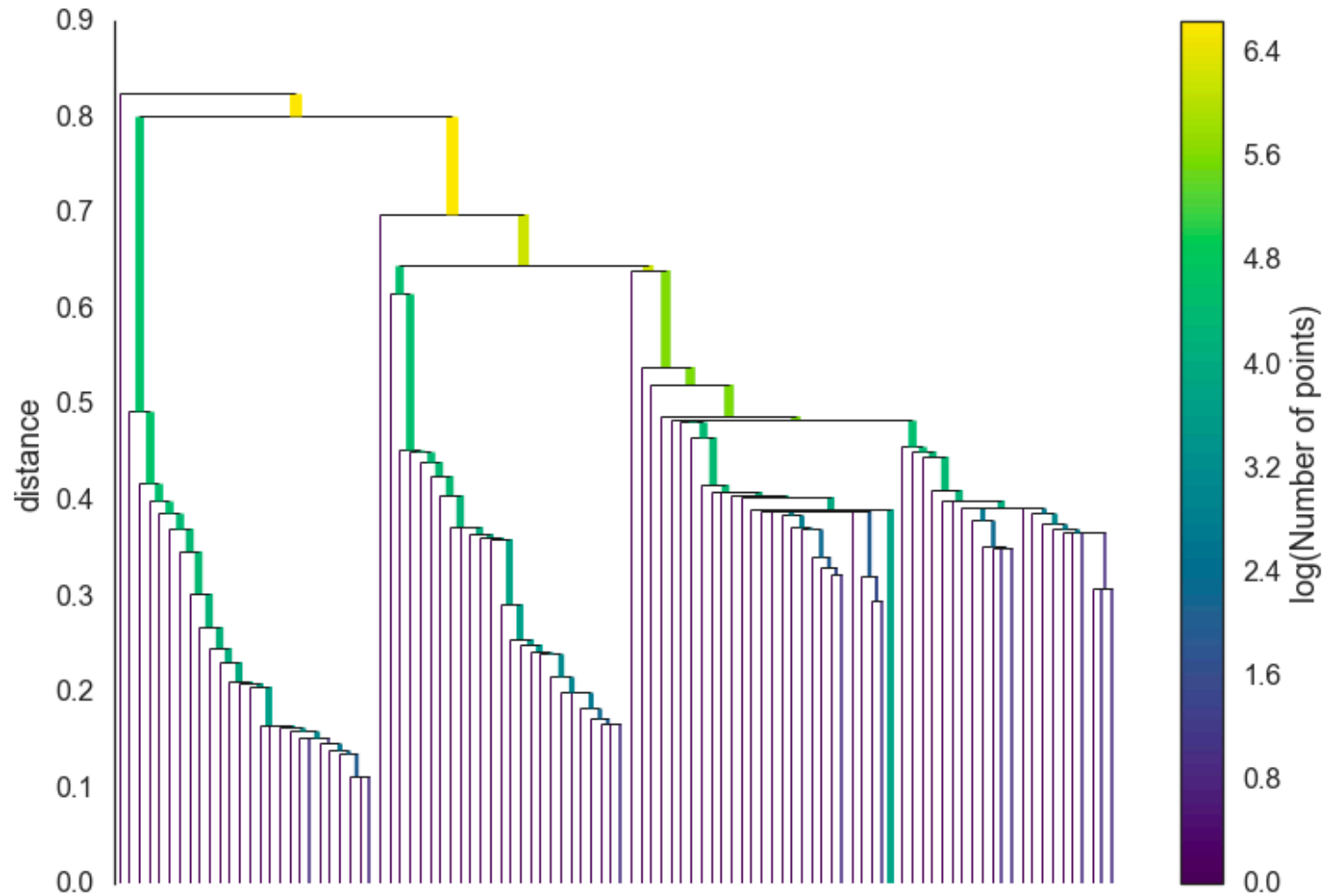
<https://en.wikipedia.org/wiki/DBSCAN>

Builds clusters by measuring distances



Hierarchical output

https://hdbscan.readthedocs.io/en/latest/how_hdbscan_works.html



What is c-TF-IDF

probability of word w in cluster c

probability of appearance of word w in documents

ranking

word

cluster (of documents)

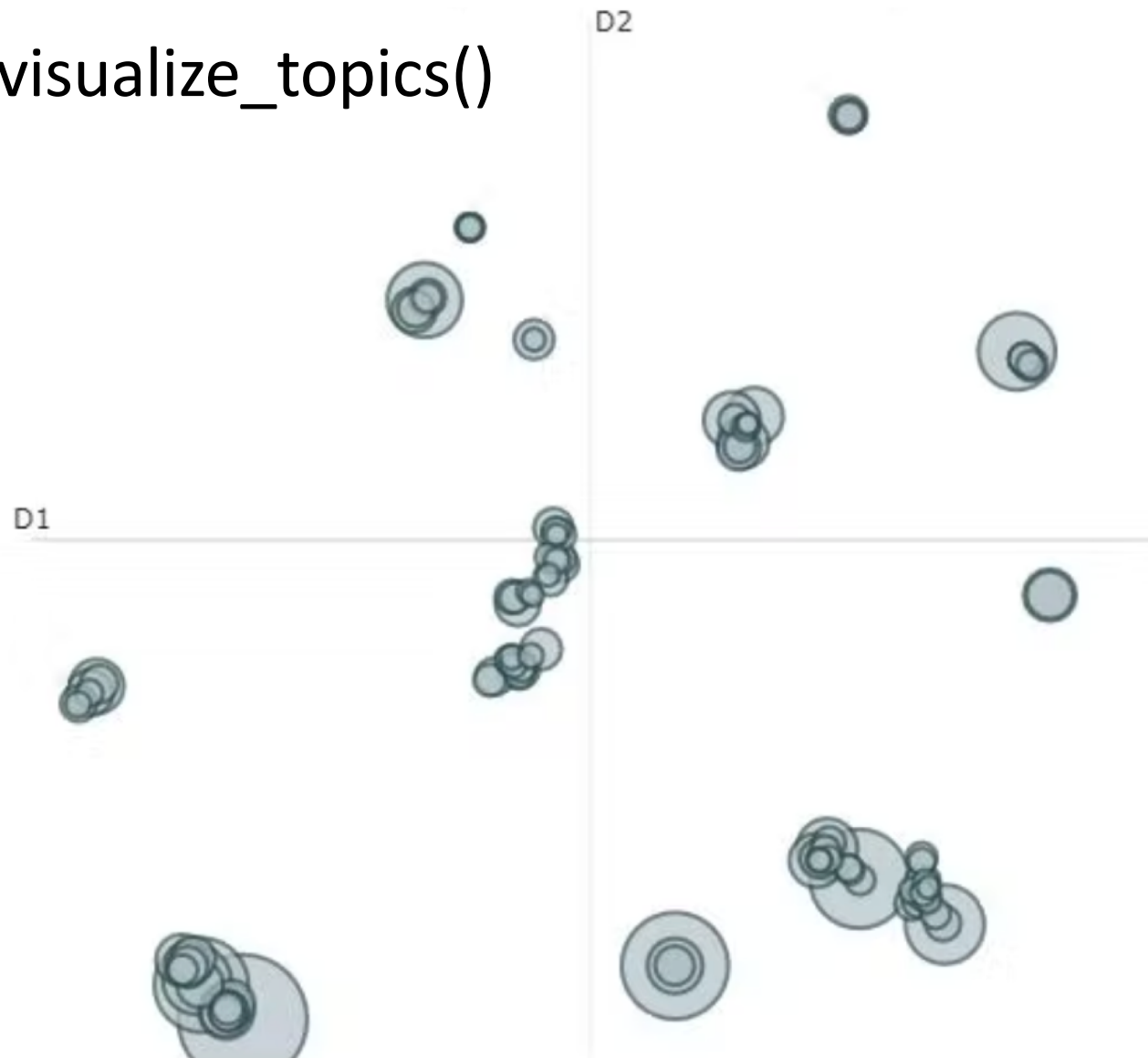
document

words which occur in many documents are rated less important

$$R_{w,c} = \frac{N_{w,c}}{\sum_w N_{w,c}} \cdot -\log \left(\frac{\sum_d N_{w,d}}{\sum_d 1} \right), \quad N_{w,c} = \sum_{d \in \mathcal{D}_c} N_{w,d}$$

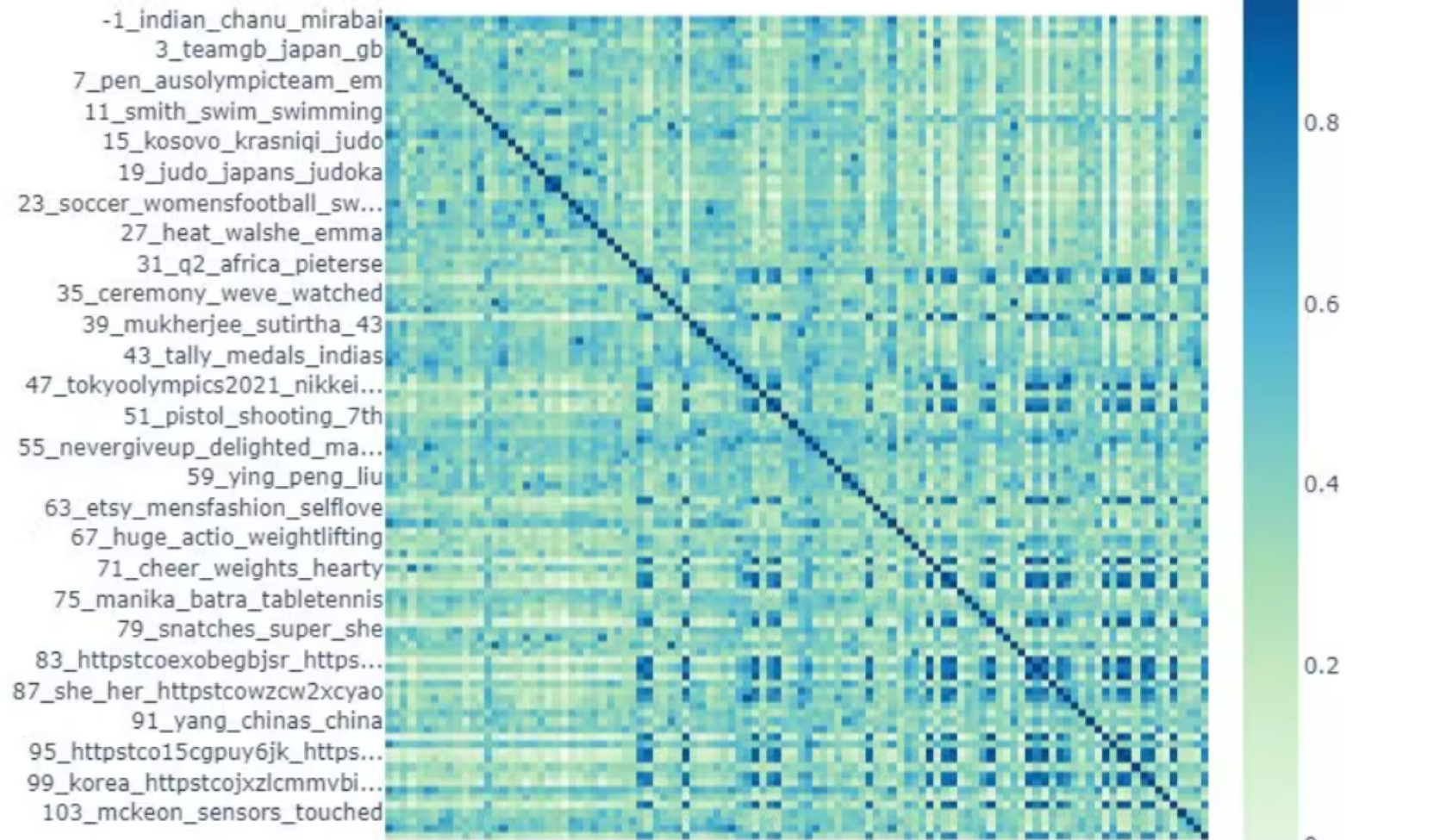
Intertopic distance map

```
model.visualize_topics()
```



Topic similarity

`model.visualize_heatmap()`



Visualize documents

`topic_model.visualize_documents()`

